

Approximation properties of two-layer neural networks with values in a Banach space

Yury Korolev

Department of Applied Mathematics and Theoretical Physics, University of Cambridge, UK

Layout

Introduction:

Scalar-valued neural networks and Barron spaces

Contribution:

Vector-valued neural networks and Barron spaces

Two-layer neural networks

Two-layer neural network (NN) $f: \mathbb{R}^d \rightarrow \mathbb{R}$:

$$f(x) = \sum_{i=1}^n a_i \sigma(\langle x, b_i \rangle + c_i), \quad x \in \mathbb{R}^d,$$

where

$\{b_i\}_{i=1}^n \subset \mathbb{R}^d$ and $\{a_i\}_{i=1}^n \subset \mathbb{R}$ are the **weights**;

$\{c_i\}_{i=1}^n \subset \mathbb{R}$ are the **biases**;

$\sigma: \mathbb{R} \rightarrow \mathbb{R}$ is the **activation function**;

$\{\sigma(\langle x, b_i \rangle + c_i)\}_{i=1}^n$ are the **neurons**, collectively called the **hidden layer** of the network;

$\langle \cdot, \cdot \rangle$ denote the scalar product in \mathbb{R}^d .

Approximation by two-layer neural networks

Universal approximation theorems (Cybenko, 1989; Hornik et al., 1989; Leshno et al., 1993)

If σ is not a polynomial then any continuous function on a compact set can be approximated uniformly by two-layer NNs.

Approximation rates

in general exponential in dimension d even for Lipschitz functions, error $O(n^{-1/d})$;

Monte-Carlo rates $O(n^{-1/2})$ for special classes of functions (next slide).

Spectral Barron space

Theorem (Barron, 1993)

For any function f on a compact set $B \subset \mathbb{R}^d$ let F be the magnitude of its Fourier transform. For any constant $C > 0$ denote

$$\Gamma_C := \left\{ f: \mathbb{R}^d \rightarrow \mathbb{R} \quad \text{s.t.} \quad \int |\omega| F(\omega) d\omega < C \right\}.$$

Then for any $n \in \mathbb{N}$ and for any $f \in \Gamma_C$ there exists a two-layer NN f_n with n neurons such that

$$\|f - f_n\|_{L^2(B)} \leq \frac{2C}{\sqrt{n}}.$$

The weights of the second layer $\{a_i\}_{i=1}^n$ can be chosen to satisfy

$$\sum_{i=1}^n |a_i| \leq 2C.$$

NB: ℓ^1 bound on $\{a_i\}_{i=1}^n$ uniform in n and depends only on C .

Infinitely wide two-layer neural networks

Infinitely wide two-layer neural network $f: \mathbb{R}^d \rightarrow \mathbb{R}$:

$$f(x) = \int_{\mathcal{A}} \sigma(\langle x, b \rangle + c) da(b, c), \quad x \in \mathbb{R}^d,$$

where \mathcal{A} is a compact topological **parameter space** and $a \in \mathcal{M}(\mathcal{A})$ is a signed Radon measure. Typically $\mathcal{A} = \mathbb{B}_{\mathbb{R}^d}$.

Definition (Bach, 2017; E, Ma, and Wu, 2019)

The space of functions that can be represented as above, equipped with the following norm

$$\|f\|_{\mathcal{B}} := \inf_a \{ \|a\|_{\mathcal{M}} : f(x) = \int_{\mathcal{A}} \sigma(\langle x, b \rangle + c) da(b, c), \quad x \in \mathbb{R}^d \},$$

is called the **Barron space**.

Barron spaces: also known as

Variation norm spaces

- Bach (2017). Breaking the curse of dimensionality with convex neural networks;

Barron spaces (not to be confused with the spectral Barron space)

- E, Ma, Wu (2019). Barron spaces and compositional function spaces for neural network models;
- E, Wojtowysch (2020). Representation formulas and pointwise properties for Barron functions;

Radon-BV² spaces

- Ongie, Willett, Soudry, Srebro (2020). A function space view of bounded norm infinite width ReLU nets: The multivariate case;
- Parhi, Nowak (2021). Banach space representer theorems for neural networks and ridge splines;

Reproducing kernel Banach spaces

- Bartolucci, De Vito, Rosasco, Vigogna (2021). Understanding neural networks with reproducing kernel Banach spaces;

Mean field approach

- Rotskoff, Vanden-Eijnden (2018). Parameters as interacting particles: long time convergence and asymptotic error scaling of neural networks;
- Mei, Montanari, Nguyen (2018). A mean field view of the landscape of two-layer neural networks;
- Chizat, Bach (2018). On the global convergence of gradient descent for over-parameterized models using optimal transport;
- Sirignano, Spiliopoulos (2020). Mean field analysis of neural networks: A law of large numbers

Linear-nonlinear decomposition

Linear-nonlinear decomposition of a two-layer NN $f: \mathbb{R}^d \rightarrow \mathbb{R}$

$$f(x) = A\sigma(Bx + c), \quad x \in \mathbb{R}^d,$$

where

$$B: \mathbb{R}^d \rightarrow \mathbb{R}^n, \quad c \in \mathbb{R}^n \quad \text{and} \quad A: \mathbb{R}^n \rightarrow \mathbb{R}$$

for a NN with $n < \infty$ neurons,

$$B: \mathbb{R}^d \rightarrow \mathcal{C}(\mathbb{R}^d), \quad c \in \mathcal{C}(\mathbb{R}^d) \quad \text{and} \quad A: \mathcal{C}(\mathbb{R}^d) \rightarrow \mathbb{R}$$

for an infinitely wide NN.

(E and Wojtowysch, 2020)

Linear-nonlinear decomposition

Linear-nonlinear decomposition of a two-layer NN $f: \mathbb{R}^{d+1} \rightarrow \mathbb{R}$

$$f(x) = A\sigma(Bx), \quad x \in \mathbb{R}^{d+1},$$

where we slightly abused the notation and identified \mathbb{R}^d with $\mathbb{R}^d \times \mathbb{R}$ and B with an operator (B, c) acting on $\mathbb{R}^d \times \mathbb{R}$ as $(x, \alpha) \mapsto Bx + \alpha c$. For inputs of the form $(x, 1)$ the two formulas are the same.

Now we have

$$B: \mathbb{R}^{d+1} \rightarrow \mathbb{R}^n \quad \text{and} \quad A: \mathbb{R}^n \rightarrow \mathbb{R}$$

for a NN with $n < \infty$ neurons,

$$B: \mathbb{R}^d \rightarrow \mathcal{C}(\mathbb{R}^{d+1}) \quad \text{and} \quad A: \mathcal{C}(\mathbb{R}^{d+1}) \rightarrow \mathbb{R}$$

for an infinitely wide NN.

Linear-nonlinear decomposition

Linear-nonlinear decomposition of a two-layer NN $f: \mathbb{R}^{d+1} \rightarrow \mathbb{R}$

$$f(x) = A\sigma(Bx), \quad x \in \mathbb{R}^{d+1}.$$

If σ is positively one-homogeneous, parameters can be chosen on the unit ball $\mathbb{B}_{\mathbb{R}^{d+1}}$.

Finally, we get

$$B: \mathbb{R}^{d+1} \rightarrow \mathbb{R}^n \quad \text{and} \quad A: \mathbb{R}^n \rightarrow \mathbb{R}$$

for a NN with $n < \infty$ neurons,

$$B: \mathbb{R}^{d+1} \rightarrow \mathcal{C}(\mathbb{B}_{\mathbb{R}^{d+1}}) \quad \text{and} \quad A: \mathcal{C}(\mathbb{B}_{\mathbb{R}^{d+1}}) \rightarrow \mathbb{R}$$

for an infinitely wide NN.

Hence, A is a linear functional on $\mathcal{C}(\mathbb{B}_{\mathbb{R}^{d+1}})$, can be identified with $a \in \mathcal{M}(\mathbb{B}_{\mathbb{R}^{d+1}})$.

Then

$$\|f\|_B = \inf_a \{ \|a\|_{\mathcal{M}} : f(x) = \langle \sigma(Bx), a \rangle, x \in \mathbb{R}^{d+1} \},$$

where $\langle \cdot, \cdot \rangle$ is the dual pairing between $\mathcal{C}(\mathbb{B}_{\mathbb{R}^{d+1}})$ and $\mathcal{M}(\mathbb{B}_{\mathbb{R}^{d+1}})$.

Monte-Carlo rates in Barron spaces

Theorem (direct approximation; E, Ma and Wu, 2019)

Let $\mu \in \mathcal{P}_p(\mathbb{R}^d)$ be a probability measure with $p \geq 1$ finite moments and let $f \in \mathcal{B}(\mathbb{R}^d)$. Then for any $n \in \mathbb{N}$ there exists a two-layer NN f_n with n neurons such that

$$\|f - f_n\|_{L^2_\mu(\mathbb{R}^d)} \leq \frac{2 \|f\|_{\mathcal{B}}}{\sqrt{n}}$$

and

$$\sum_{i=1}^n |a_i| \leq 2 \|f\|_{\mathcal{B}}.$$

Cf. Barron's theorem: $\|f\|_{\mathcal{B}}$ substitutes the spectral Barron norm.

Inverse approximation also holds (E, Ma and Wu, 2019).

Layout

Introduction:

Scalar-valued neural networks and Barron spaces

Contribution:

Vector-valued neural networks and Barron spaces

Learning in infinite-dimensional spaces

Reproducing kernel Hilbert/Banach spaces a.k.a. random feature models

- Micchelli, Pontil (2005). On learning vector-valued functions;
- Zhang, Zhang (2013). Vector-valued reproducing kernel Banach spaces with applications to multi-task learning;
- Álvarez, Rosasco, Lawrence (2012). Kernels for vector-valued functions: A review;
- Nelsen, Stuart (2020). The random feature model for input-output maps between Banach spaces.

Universal approximation theorems for operators

- Chen, Chen (1995). Universal approximation to nonlinear operators by neural networks with arbitrary activation functions and its application to dynamical systems;
- Lanthaler, Mishra, Karniadakis (2021). Error estimates for DeepOnets: A deep learning framework in infinite dimensions.

Vector-valued two-layer neural networks

Vector-valued two-layer NN $f: \mathcal{X} \rightarrow \mathcal{Y}$

$$f(x) = A\sigma(Bx), \quad x \in \mathcal{X},$$

where

\mathcal{X}, \mathcal{Y} have separable preduals and \mathcal{Y} is also a vector lattice,
 $\sigma: \mathcal{Y} \rightarrow \mathcal{Y}$ is the generalised ReLU function,

$$\sigma(y) := y_+ = y \vee 0 \quad \text{in the lattice sense,}$$

$B: \mathcal{X} \rightarrow \mathcal{C}(\mathbb{B}_{\mathcal{L}(\mathcal{X};\mathcal{Y})}; \mathcal{Y})$ maps

$$x \mapsto \mathcal{L}_x(\cdot) \quad \text{such that} \quad \mathcal{L}_x(K) = Kx,$$

$A: \mathcal{C}(\mathbb{B}_{\mathcal{L}(\mathcal{X};\mathcal{Y})}; \mathcal{Y}) \rightarrow \mathcal{Y}$ maps

$$\varphi(\cdot) \mapsto \int_{\mathbb{B}_{\mathcal{L}}} \varphi(K) da(K), \quad \text{where } a \in \mathcal{M}(\mathbb{B}_{\mathcal{L}(\mathcal{X};\mathcal{Y})}).$$

Vector lattices, a.k.a. Riesz spaces

Vector space \mathcal{X} with partial order " \leq " called an *ordered vector space* if

$$\begin{aligned}x \leq y &\implies x + z \leq y + z && \forall x, y, z \in \mathcal{X}, \\x \leq y &\implies \lambda x \leq \lambda y && \forall x, y \in \mathcal{X} \text{ and } \lambda \in \mathbb{R}_+.\end{aligned}$$

A *vector lattice* (or a *Riesz space*) is an ordered vector space \mathcal{X} with well defined suprema and infima

$$\begin{aligned}\forall x, y \in \mathcal{X} \quad \exists x \vee y \in \mathcal{X}, \quad x \wedge y \in \mathcal{X}; \\x \vee \mathbf{0} = x_+, \quad (-x)_+ = x_-, \quad x = x_+ - x_-, \quad |x| = x_+ + x_-\end{aligned}$$

Examples of vector lattices

- Sequence spaces ℓ^p , $1 \leq p \leq \infty$

$$x \geq y \iff x^i \geq y^i \quad i \in \mathbb{N};$$

- Space of signed Radon measures $\mathcal{M}(\Omega)$

$$\mu \geq \nu \iff \mu(A) \geq \nu(A) \quad \forall A \subset \Omega;$$

- Lebesgue spaces \mathcal{L}^p , $1 \leq p \leq \infty$

$$f \geq g \iff f(x) \geq g(x) \quad \text{a.e. in } \Omega;$$

- Space of continuous functions $\mathcal{C}(\Omega)$, space of Lipschitz functions $\text{Lip}(\Omega)$

$$f \geq g \iff f(x) \geq g(x) \quad \forall x \in \Omega;$$

- Space of linear operators between two partially ordered spaces $\mathcal{L}^r(\mathcal{X}; \mathcal{Y})$

$$A \geq B \iff \forall x \geq 0 \text{ it holds that } Ax \geq Bx.$$

Caveats – 1

The parameter space is $\mathbb{B}_{\mathcal{L}(\mathcal{X};\mathcal{Y})}$. To make sure it is compact, we need to

- make sure that $\mathcal{L}(\mathcal{X};\mathcal{Y})$ is a dual space and
- use the weak* topology.

Theorem (Ryan, Introduction to tensor products of Banach spaces, 2002)

Suppose that \mathcal{X} and \mathcal{Y} have separable preduals \mathcal{X}^\diamond and \mathcal{Y}^\diamond and that either \mathcal{X} or \mathcal{Y}^\diamond has the approximation property. Then the dual of the space of nuclear operators $\mathcal{N}(\mathcal{Y}^\diamond; \mathcal{X}^\diamond)$ can be identified with the space of bounded operators $\mathcal{L}(\mathcal{X}; \mathcal{Y})$

$$(\mathcal{N}(\mathcal{Y}^\diamond; \mathcal{X}^\diamond))^* \simeq \mathcal{L}(\mathcal{X}; \mathcal{Y}).$$

Consequently, the unit ball $\mathbb{B}_{\mathcal{L}(\mathcal{X};\mathcal{Y})}$ is weakly compact and metrisable.*

Caveats – 2

Since $\mathbb{B}_{\mathcal{L}(\mathcal{X};\mathcal{Y})}$ is equipped with the weak* topology, we need to make sure that

- the function $\mathcal{L}_x: \mathbb{B}_{\mathcal{L}(\mathcal{X};\mathcal{Y})} \rightarrow \mathcal{Y}$ such that $\mathcal{L}_x(K) = Kx$ is weakly-* continuous \rightarrow true if \mathcal{Y} is equipped with the weak* topology;
- the nonlinearity σ is weakly-* continuous \rightarrow turns out to be quite restrictive for the ReLU!

Examples:

- ✓ Sequence spaces ℓ^p , $p > 1$; Lipschitz space $\text{Lip}(\Omega)$;
- ✗ Lebesgue spaces L^p_μ (unless μ is atomic); space of linear operators $\mathcal{L}^r(\mathcal{X};\mathcal{Y})$ (except in special cases); space of Radon measures $\mathcal{M}(\Omega)$ (unless Ω is discrete).

Caveats – 3

In order to obtain convergence rates in Bochner spaces L^p , we need to metrize the weak* topology on the unit ball in \mathcal{Y} . This can be done using the following metric

$$d_*(y, z) = \sum_{i=1}^{\infty} 2^{-i} |\langle \eta_i, y - z \rangle|.$$

where $\{\eta_i\}_{i \in \mathbb{N}}$ is a countable dense system in the predual such that $\|\eta_i\| = 1$ for all i .

Approximation rates will be obtained in Lebesgue-Bochner spaces $L^p(\mathcal{X}, (\mathcal{Y}, d_*))$.

Vector-valued Barron space

Definition (Vector-valued Barron functions)

Let \mathcal{X}, \mathcal{Y} have separable preduals and let \mathcal{Y} be such that lattice operations are 1-Lipschitz with respect to the d_* metric. We define the space of \mathcal{Y} -valued Barron functions as follows

$$\mathcal{B}(\mathcal{X}; \mathcal{Y}) := \{f \in \text{Lip}_0 : \|f\|_{\mathcal{B}} < \infty\},$$

where Lip_0 is the space of Lipschitz functions with respect to the d_* metric in \mathcal{Y} that vanish at zero and

$$\|f\|_{\mathcal{B}} := \inf_{a \in \mathcal{M}(\mathbb{B}_{\mathcal{L}})} \left\{ \|a\|_{\mathcal{M}} : f(x) = \int_{\mathbb{B}_{\mathcal{L}}} \sigma(\mathcal{L}_x(K)) da(K) \quad \forall x \in \mathcal{X} \right\}.$$

Monte-Carlo rates in vector-valued Barron spaces

Theorem (direct approximation; YK 2021)

Let above assumptions be satisfied and let $f \in \mathcal{B}(\mathcal{X}; \mathcal{Y})$. Then for any $n \in \mathbb{N}$ there exists a two-layer neural network with n neurons

$$f_n(x) := \sum_{i=1}^n \alpha_i (K_i x)_+, \quad x \in \mathcal{X},$$

where K_i have finite rank and $\|K_i\|_{\mathcal{L}(\mathcal{X}; \mathcal{Y})} \leq 1$, such that if $\mu \in \mathcal{P}_p(\mathcal{X})$ and $m_p(\mu) < \infty$ is its p -th moment, $p \geq 1$, then

$$\|f - f_n\|_{L_\mu^p} \leq \frac{2\sqrt{2} \|f\|_{\mathcal{B}} (m_p(\mu))^{\frac{1}{p}}}{\sqrt{n}}.$$

Inverse approximation also holds.

Conclusions

We have

- ✓ Generalised Barron spaces with ReLU activation to networks with values in a Banach space;
- ✓ Proved inverse and direct approximation theorems, obtained Monte-Carlo rates;
- ✓ Results also hold for any 1-homogeneous and weakly-^{*} continuous activation, e.g., *leaky ReLU*

$$\sigma(y) := y_+ - \lambda y_-, \quad \lambda \in (0, 1);$$

- ✗ Saw a limitation – weak^{*} continuity of σ often not fulfilled by ReLU → is the use of weak^{*} topologies a technicality?
- ✗ More complex architectures.

So long, and thanks for all the ~~fish~~ funding



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