Introduction to Dynamics on Networks

- Dynamical Processes on Complex Networks, A. Barrat, M. Barthélemy and A. Vespignani, Cambridge University Press (2008)
- 2. Statistical physics of social dynamics, Castellano *et al.*, Rev. Mod. Phys. 81 (2009).

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- Interested in transition between *disordered* and *ordered* phases, where nodes share similar states;
 - can use tools of *statistical mechanics* and *population dynamics*.
- Results can often be translated to different contexts.

General Framework – Basics

- Associate variables x_i with states on node i, can be:
 - continuous variable, or set of variables $\mathbf{x}_{\mathbf{i}} = (x_{1i}, x_{2i}, ...);$
 - enumerated states $x_i \in \{1, 2, 3, ..., s\}$ (same meaning);
 - system configuration: $\mathbf{x} = (x_1, x_2, ..., x_N)$,
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- Dynamical systems theory gives tools to do this, given:
 - intial values x₀,
 - dynamical equations: $x'_i = f_i(\mathbf{x})$, for future state x'.
 - e.g.: $\dot{\mathbf{x}} = f(\mathbf{x}) + \sigma L \mathbf{x}$; reaction diffusion system.

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- 2. Network structure not known precisely, or different for each realisation:
 - cities, friendship networks, computer networks, biological or ecological networks...
- 3. Initial conditions not known precisely,
 - outcomes can be very sensitive to IC,
 - often know only certain features, e.g. distributions of numbers *S* in each state.

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 - gain some statistical insight,
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- to gain more understanding need to simplify in meaningful way,
 - make analytically feasible.

Analytical Methods

- Know that dynamics tends to reduce variability and increase order:
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- Use concepts and tools from statistical mechanics,
 - need to extend to deal with complex topologies.
- Ask questions such as:
 - what are likely equilibrium states, if they exist?
 - what are mechanisms driving ordered/polarised state?
 - what are thresholds for transitions?

Analytical Methods - Master Equation

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 - instead focus on probability $P(\mathbf{x}, t)$, for particular config.
- Master equation (ME):

$$\partial_t P(\mathbf{x},t) = \sum_{\mathbf{x}'} \left[P(\mathbf{x}',t) W(\mathbf{x}' \to \mathbf{x}) - P(\mathbf{x},t) W(\mathbf{x} \to \mathbf{x}') \right],$$

 $W(\mathbf{x}^a \rightarrow \mathbf{x}^b)$ are transition rates.

Master Equation for number of nodes N_k with degree k:

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$$\partial_t N_k = r_{k-1 \to k} N_{k-1} - r_{k \to k+1} N_k + \delta_{k,m}$$

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$$n_k = n_{k-1} \frac{(k-1)}{(k+1)}$$
; and hence:
• $n_k = \frac{4}{k(k+1)(k+2)}$. I.e. $P(k) \propto k^{-3}$

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- State x_i of node i depends only on its neighbours j so:

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• Network topology now plays a role in dynamics.

 In principle possible to compute expectation value of function A(x):

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- In practice impossible to solve ME in most cases!
- Additionally most real-world applications are non-equilibrium
 - not possible to use equilibrium thermodynamics and ergodic hypothesis.

Approx. Solutions of Master Equation

- 1. Consider appropriate projection:
 - e.g.: average number in state $x_i = a$ at time t:

$$\langle N_a(t) \rangle = \sum_{\mathbf{x}} \sum_i \delta_{\mathbf{x}_i, \mathbf{a}} P(\mathbf{x}, t),$$

 δ is Kronecker delta.

• average quantity \Rightarrow deterministic.

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- average quantity \Rightarrow deterministic.
- 2. Neglect network structure, assume homogeneous system with no correlations; $prob(x_i = a) = p_a$, for each *i*:

$$P(\mathbf{x}) = \prod_i p_{x_i}.$$

• Mean Field (MF) approximation.

(In-) Validity of Mean Field Approx.

MF valid when:

- Variables (degrees of freedom) of system are iid:
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- Homogeneous mixing; i.e. all *i* have equal chance of interacting with all *j*,
 - again, network structure invalidates this,
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However:

- produces analytically tractable results,
- in many cases useful ones.

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• Using:
$$\langle N_A(t) \rangle = \sum_{\mathbf{x}} \sum_{i} \delta_{x_i,A} P(\mathbf{x}, t)$$

and $\langle N_B(t) \rangle = \sum_{\mathbf{x}} \sum_{i} \delta_{x_i,B} P(\mathbf{x}, t)$

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• ME: $\partial_t \langle N_B(t) \rangle = \sum \sum \delta_{x_i,B} \delta_t P(\mathbf{x}, t)$

$$\partial_t \langle N_B(t) \rangle = \sum_i \sum_{\mathbf{x}'} \sum_{\mathbf{x}} \left[\delta_{x_i,B} \prod_k w(x'_k \to x_k | x'_j) P(\mathbf{x}', t) - \delta_{x_i,B} \prod_k w(x_k \to x'_k | x_j) P(\mathbf{x}, t) \right]$$

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$$\begin{split} \sum_{\mathbf{x}'} \prod_{k} w(x_k \to x'_k | x_j) &= 1, \\ \sum_{\mathbf{x}} \delta_{x_i, B} \prod_{k} w(x'_k \to x_k | x'_j) &= w(x'_i \to x_i = B | x'_j) \\ \partial_t \langle N_B(t) \rangle &= \sum_{i} \sum_{\mathbf{x}'} \left[w(x'_i \to x_i = B | x'_j) P(\mathbf{x}', t) \right] - \langle N_B(t) \rangle \end{split}$$

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$$\partial_{t} \langle N_{B}(t) \rangle = \sum_{i} \sum_{\mathbf{x}'} \left[w(x'_{i} \to x_{i} = B | x'_{j}) P(\mathbf{x}', t) \right] - \langle N_{B}(t) \rangle$$

$$N_{B} = \sum_{i} \sum_{\mathbf{x}'} \left[w(x'_{i} \to x_{i} = B | x'_{j}) P(\mathbf{x}', t) \right] - \langle N_{B}(t) \rangle$$

Now using MF: $p_A = N_A/N$, $p_B = N_B/N$ and $P(\mathbf{x}') = \prod_i p_{\mathbf{x}'_i}$:

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$$\sum_{\mathbf{x}'} \left[w(x'_{i} = A \to x_{i} = B | x'_{i}) p_{A} \prod_{i} p_{x'_{i}} + w(x'_{i} = B \to x_{i} = B | x'_{i}) p_{B} \prod_{i} p_{x'_{i}} \right]$$

$$\sum_{x'_j} \left[w(x'_i = A \to x_i = B | x'_j) p_A \prod_{j \in \mathcal{V}(i)} p_{x'_j} + w(x'_i = B \to x_i = B | x'_j) p_B \prod_{j \in \mathcal{V}(i)} p_{x'_j} \right]$$

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LHS $w = \beta$ with prob $1 - (1 - p_B)^k$, and RHS w = 1 always, so:

$$\partial_t \langle N_B(t) \rangle = \sum_i \sum_{\mathbf{x}'} \sum_{\mathbf{x}} \left[\delta_{x_i,B} \prod_k w(x'_k \to x_k | x'_j) P(\mathbf{x}', t) - \delta_{x_i,B} \prod_k w(x_k \to x'_k | x_j) P(\mathbf{x}, t) \right]$$

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$$N_{ij} = \sum_{i} \sum_{\mathbf{x}'} \left[w(x'_i \to x_i = B | x'_j) P(\mathbf{x}', t) \right] - \langle N_B(t) \rangle$$

Now using WF:
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, $p_B = N_B/N$ and $P(\mathbf{x}) = \prod_i p_{x'_i}$.

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$$\partial_t \langle N_B(t) \rangle = \beta N_A (1 - (1 - N_B/N)^k).$$