

# Parallel Algorithms

## Fork and Join

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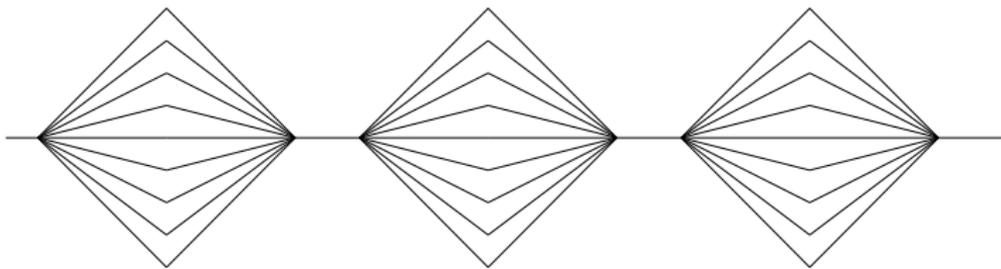
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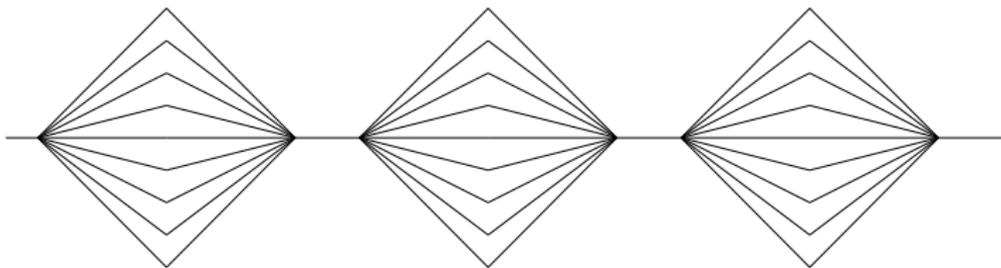
Superstep

# Parallel Algorithms

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Superstep

Of course, we would like to make the sequential parts between the forks as small as possible

# Parallel Algorithms

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We could use barriers between the two phases

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We might want to do the sub-tasks provider/consumer, or manager/worker or thread pool or whatever

It is very unlikely we would want to use `pthread_create` and `pthread_join` every time

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## Pipelines/Systolic

Another structuring method we have seen before is the *pipeline*, also called *systolic array*



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Input data is transformed by several separate stages by several separate processors

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Pipeline

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A well-balanced pipeline (eventually) gives perfect speedup and efficiency

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## MapReduce

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This is a combination of a *map* and a *reduce*, and is a kind of divide and conquer

A map takes a function and a structure (a list or vector or tree or whatever) of data, and applies that function to each element in the structure

As long as there is no interference between the items of data, this is trivially parallelisable: stick different items of data on different processors and execute the function on each

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Other reductions might be less or more parallelisable

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Reduce: merging and sorting the partial results

MapReduce is much used by Google for their various services, not just searching

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MapReduce also copes well with less than 100% reliability of the hardware

# Parallel Algorithms

## Aside: Reliability

A quick word on reliability: modern machines are pretty reliable and we are not used to them breaking down too often

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So another issue large systems and the algorithms that run on them have to contend with is machines failing

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For example, you might want to run the same sub-task on more than one processor for reliability: if one breaks you'll still get the result

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At one point Hector, a UK academic cluster, was having a failure rate of one node per day

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Some processes may want to simply read data, a *reader*

Others might want to read and then update data, a *writer*

To ensure consistency in the data, a writer must have exclusive access to the database

(A simplification of reality, if you know anything about databases)

# Parallel Algorithms

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One solution is to use simple primitives

# Parallel Algorithms

## Readers/Writers

```
int readers = 0;
rlock = make_lock();    // protect readers
wsem = make_semaphore(1); // sync writers

void reader()
{
    lock(rlock);
    readers++;
    if (readers == 1) wait(wsem);
    unlock(rlock);
    ... read ...
    lock(rlock);
    readers--;
    if (readers == 0) signal(wsem);
    unlock(rlock);
}

void writer()
{
    wait(wsem);
    ... write ...
    signal(wsem);
}
```

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write semaphore
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if (readers == 0) signal(wsem); the last reader out  
releases the semaphore
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This works, but has a problem

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The problem is that this code is unfair in the way it treats readers and writers

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- and so on

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With low probability, but it happens

This is *starvation* of the writer

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We might try to fix the writer starvation by having a writer pending count, and have readers wait if there is a writer (or some suitable number of writers) waiting

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**Exercise** Do this

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But now we have a writers' preference and readers can be starved

# Parallel Algorithms

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Making this fair for both readers and writers is harder than you think

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**Exercise** Go and read up on the many suggested solutions to readers/writers

**Exercise** Read about the POSIX `pthread_rwlock`

**Exercise** Read about *read-copy-update* (RCU) and its choice of compromises

**Exercise** Think about how you might use GCD queues

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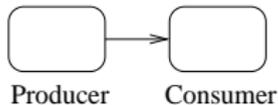
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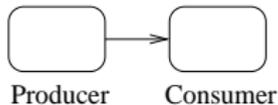
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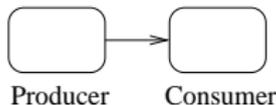
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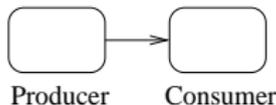
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**Exercise** Compare with MPI

# Parallel Algorithms

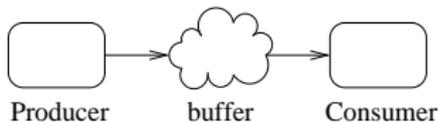
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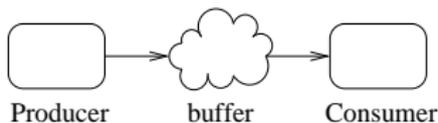


Buffered Producer/Consumer

# Parallel Algorithms

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Buffered Producer/Consumer

This is just some area of memory in a shared memory system;  
or a message queue for a distributed memory system

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- each can work at their own rate, until the buffer fills or empties
- there is less synchronisation, thus less waiting around
- the producer and consumer are now working *asynchronously*: not synchronising on every message

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When the producer produces data, it writes it into the next free place in the buffer

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We need to see how to manage this synchronisation

# Parallel Algorithms

## Producers/Consumers

For example, a buffer of size 1, using two semaphores, called empty and full

```
        empty = make_semaphore(1);
        full = make_semaphore(0);
producer() {
    produce data
    wait(empty);
    insert in buffer
    signal(full);
}
consumer() {
    wait(full);
    take from buffer
    signal(empty);
    consume data
}
```

# Parallel Algorithms

## Producers/Consumers

A simple extension to a buffer of size  $n$  is to use counting semaphores `data` and `free` with `free` initialised to  $n$

```
    free = make_counting_semaphore(n);
    data = make_counting_semaphore(0);
producer() {
    produce data
    wait(free);
    append to buffer
    signal(data);
}
consumer() {
    wait(data);
    remove from buffer
    signal(free);
    consume data
}
```

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In this code as written, the producer and consumer might be acting simultaneously on the buffer: we need to make sure the update does not have a data race

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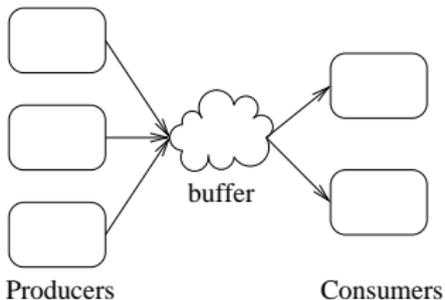
In this code as written, the producer and consumer might be acting simultaneously on the buffer: we need to make sure the update does not have a data race

So, for example, might want a lock on the buffer, or make sure the buffer can otherwise safely support a simultaneous read and write (e.g., for a hash table this might be difficult)

# Parallel Algorithms

## Producers/Consumers

And things get more interesting when there is more than one producer, or more than one consumer



Multiple Produces/Consumers

# Parallel Algorithms

## Producers/Consumers

Now concurrent access to the buffer is really a problem

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We might use a lock to do this

```
        free = make_semaphore(1);
        data = make_semaphore(0);
        buffy = make_lock();
producer() {
    produce data
    wait(free);
    get_lock(buffy);
    insert in buffer
    free_lock(buffy);
    signal(data);
}
        consumer() {
    wait(data);
    get_lock(buffy);
    take from buffer
    free_lock(buffy)
    signal(free);
    consume data
}
```

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## Producers/Consumers

**Exercise** Prove that this cannot deadlock

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Using one lock means that we cannot insert into the buffer at the same time as reading from it

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**Exercise** Prove that this cannot deadlock

Using one lock means that we cannot insert into the buffer at the same time as reading from it

This is often an unnecessary restriction, e.g., the buffer is an area of memory where we can read one element at the same time as writing a different one

# Parallel Algorithms

## Producers/Consumers

**Exercise** Prove that this cannot deadlock

Using one lock means that we cannot insert into the buffer at the same time as reading from it

This is often an unnecessary restriction, e.g., the buffer is an area of memory where we can read one element at the same time as writing a different one

Again, this might not be possible if the buffer was some more sophisticated kind of datastructure

# Parallel Algorithms

## Producers/Consumers

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And we have to be careful when they coincide, e.g., when the buffer is full or empty

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In any case, the buffers are usually actually *queues*, namely first in first out

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More advanced use of queues is possible

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The “gap” between testing for a space in the buffer and inserting is not a problem as no-one else is inserting data

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You still have to think carefully about the interaction of this with the removal of data

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**Exercise** Find out how to do this (it involves memory barriers!)