# Why is quantifier elimination doubly exponential? 

James Davenport

University of Bath and DEWCAD group [ $\left.\mathrm{BDE}^{+} 21\right]$
https://matthewengland.coventry.domains/dewcad/index.html
(supported by EPSRC under EP/T015713)

## Notation

d The maximum degree (in each variable separately) of the input polynomials. $\mathfrak{d} \leq d n$ total degree.
/ The maximum bit-length of the integer coefficients
$m$ The number of (distinct) polynomials.
$n$ The number of variables.
$a$ The number of alternations of quantifiers. $a \leq n-1$.
c The number of equational constraints.
$(M, D)$ At most $M$ sets, each of combined degree $\leq D[\mathrm{McC84}]$.
(2) This is the standard theory setting. Real problems tend to involve rational functions, and rational, or even algebraic, numbers. See [UDE22].
The complexity of QE (and hence CAD) is doubly exponential in $n$, more precisely $d^{2^{e} d} m^{2^{e m}}$ where $e_{d}$ and $e_{m}$ depend non-trivially on $n$ (or on $a$ ). What are $e_{d}, e_{m}$ ?

## Quantifier Elimination

Given a quantified statement in $n=k+l$ variables

$$
Q_{1} x_{1} \cdots Q_{k} \Phi\left(x_{1}, \ldots, x_{k}, y_{1}, \ldots, y_{l}\right), \quad Q_{i} \in\{\exists, \forall\}
$$

find an equivalent quantifier-free formula $\Psi\left(y_{1}, \ldots, y_{l}\right)$. Our applications will be either $\mathbf{C}$ (with,,$+- \times,=, \neq$ ) or $\mathbf{R}$ (with $+,-, \times,=, \neq,>, \geq,<, \leq)$.
Note the absence of division: philosophical and practical issues here [UDE22].
$\mathbf{R}$ implies $\mathbf{C}$ (take real and imaginary parts, and you get $|z|$ and $\bar{z}$ for free). $\mathbf{C}$ with $\bar{z}$ implies $\mathbf{R}$.
Solved by [Tar51, Sei54], but indescribable complexity. First plausible solution [Col75], via cylindrical algebraic decomposition (CAD), constructed via projection/lifting.

## CAD Sign invariant for $P$

Decomposition: $\mathbf{R}^{n}=\bigcup_{i} C_{i}$ and $i \neq j \Rightarrow C_{i} \cap C_{j}=\emptyset$
Cylindrical: If $P_{m}$ is the projection onto the first $m$ variables, then either $P_{m}\left(C_{i}\right)=P_{m}\left(C_{j}\right)$ or $P_{m}\left(C_{i}\right) \cap P_{m}\left(C_{j}\right)=\emptyset$.
Also A sample point in each cell, arranged cylindrically.
In fact This is slightly stronger than we need: can relax to "block-cylindrical", where $m$ has to be where $Q_{m} \neq Q_{m+1}$, i.e. the quantifiers alternate.
(Semi-)Algebraic The boundaries of each cell are semi-algebraic functions, i.e. defined by polynomials and $=, \neq,>, \geq,<, \leq$.
N.B. This is the standard definition, but permits many pathological examples that "no sane algorithm would construct". See [DLS20].
Sign invariant In each $C_{i}$ every $P_{j} \in \mathcal{P}$ is positive, or negative, or identically zero, so sample points suffice, and $\forall x_{i}$ translates to " $\forall x_{i}$ i-th coordinates of sample points".

## Projection/Lifting for a property $Z$

Given $\mathcal{P}_{v}$ polynomials in $v$ variables, construct a set $\operatorname{Proj}\left(P_{v}\right)$ in $v-1$ variables such that a CAD of $\mathbf{R}^{v-1} Z$-invariant for $\operatorname{Proj}\left(P_{v}\right)$ can be lifted to a CAD of $\mathbf{R}^{\vee} Z$-invariant for $P_{v}$.
[Col75] $Z$ is "sign". Because a polynomial might vanish identically on a cell, also take subresultants, so $e_{m} \approx n \log _{2} 3$.
[McC85] $Z$ is "order". Might fail if a polynomial vanishes identically on a cell. But $e_{m} \approx n$.
[Bro01] $Z$ is "order", but projection is cheaper.
[Laz94, MPP19] $Z$ is "lex-least", and (Lazard lifting) if a polynomial vanishes identically, divide out the obstruction. Again $e_{m} \approx n$.
[BM20] $Z$ is "lex-least", but projection is cheaper.
Proj always involves $\operatorname{disc}_{x_{v}}\left(p_{i}\right)$ and $\operatorname{res}_{x_{v}}\left(p_{i}, p_{j}\right)$, hence both degree and number of polynomials squares with each projection.

## The problem with iterated resultants

Consider $f_{1}, f_{2}, f_{3} \in \mathbf{Q}[x, y, z]$ of degree $d$ in each variable. Then $\operatorname{res}_{z}\left(f_{1}, f_{2}\right)$ etc. have degree $2 d^{2}$, and $R:=\operatorname{res}_{y}\left(\operatorname{res}_{z}\left(f_{1}, f_{2}\right), \operatorname{res}_{z}\left(f_{1}, f_{3}\right)\right)$ has degree $8 d^{4}$.
[And so $e_{d} \approx n$ ]
But (Bézout) $f_{1}=f_{2}=f_{3}=0$ has $\leq 27 d^{3}$ points ( $x, y, z$ ).
The problem is that $R$ has as roots

$$
\begin{gathered}
\text { (true) } x: \exists y \exists z f_{1}(x, y, z)=f_{2}(x, y, z)=f_{3}(x, y, z)=0 \\
\text { (spurious) } x: \exists y\left[\exists z_{1} f_{1}\left(x, y, z_{1}\right)=f_{2}\left(x, y, z_{1}\right)=0\right] \wedge \\
{\left[\exists z_{2} f_{1}\left(x, y, z_{2}\right)=f_{3}\left(x, y, z_{2}\right)=0\right] .}
\end{gathered}
$$

In this case, a Gröbner base [EBD20], or even $\operatorname{gcd}\left(R, \operatorname{res}_{y}\left(\operatorname{res}_{z}\left(f_{1}, f_{2}\right), \operatorname{res}_{z}\left(f_{2}, f_{3}\right)\right)\right)$, will solve the problem. Goes some way to explain [McC99a]'s observation that iterated resultants tend to factor.
But in the general case, those "spurious" roots are where the projected topology of $V\left(f_{i}\right)$ changes.

## Equational Constraints

[Col98] What if our formula $\Phi$ is $f=0 \wedge \hat{\Phi}$, where $\hat{\Phi}$ involves $m-1$ polynomials $g_{i}$ ?
[McC99b] Answers this: we only need $O(m) \operatorname{res}_{x}\left(f, g_{i}\right)$, not $O\left(m^{2}\right)$ $\operatorname{res}_{x}\left(g_{i}, g_{j}\right)$, since

$$
\begin{equation*}
\left.\operatorname{res}_{x}\left(g_{i}, g_{j}\right)\right|_{f=0} \propto \operatorname{res}_{y}\left(\operatorname{res}_{x}\left(f, g_{i}\right), \operatorname{res}_{x}\left(f, g_{j}\right)\right) \tag{1}
\end{equation*}
$$

Means that, after the $x$ projection, we only have $O(m)$ polynomials not $O\left(m^{2}\right)$.
[McC01] Generalises to $f_{1}=0 \wedge \cdots \wedge f_{c}=0 \wedge \hat{\phi}$.

+ Reduces $e_{m}$ from $n$ to $n-c$, nothing for $e_{d}$.
$\left[\mathrm{BDE}^{+} 16\right]$ Generalises to where only part of the formula has equational constraints: "truth-table invariant CAD"
[EBD20] Can use Gröbner bases, rather than just iterated resultants, to reduce degree growth, ideally $e_{d}$ becomes $n-c$.
But All this is for the McCallum projection, i.e. well-oriented.


## Doesn't Lazard projection/lifting eliminate "well-oriented"?

+ Yes, for straight cylindrical algebraic decomposition
But if $f(x, y, z, \ldots)$ vanishes identically on some surface $S(y, z, \ldots)$, the constant of proportionality in (1) is 0 , and we learn nothing about $\operatorname{res}_{x}\left(g_{i}, g_{j}\right)$ from $\operatorname{res}_{x}\left(f, x_{i}\right)$.
(2) "Nullification" has come back to bite us, but only nullification of $f$, not the $g_{i}$.
Call $S$ the foot of the "curtain": the "vertical" part of $f=0$ [NDS20].
$\operatorname{dim}(S)$ The case $\operatorname{dim}(S)=0$ is tractable [Nai21] - see that thesis for more details of $\operatorname{dim}(S)>0$.


## Graph Theory to the rescue?

Instead of considering degrees of the polynomials in $F$, consider the graph $\mathcal{G}(F)$ on $\left\{x_{1}, \ldots, x_{n}\right\}$ with an edge betwen $\left(x_{i}, x_{j}\right)$ iff there is a polynomial in $F$ contaning both $x_{i}$ and $x_{j}$.
Connectedness?
Gröbner If $\mathcal{G}(F)$ is not connected, the problems are independent, and [Buc79, Criterion 1] will treat them as such.
CAD Essentially independent, but this is hard to describe: we have "the outer product" of the two (or more) CADs. We definitely need to project one component at a time.

## Problem

Recognise, and treat effectively, this case, also "nearly disconnected" (see next)

## Graph Theory to the rescue continued

A graph $\mathcal{G}$ is chordal if every $>3$-cycle has a chord. Equivalently, every induced cycle has length 3 . Every graph $\mathcal{G}$ has a chordal completion $\overline{\mathcal{G}}$.
Minimum chordal completion is NP-complete [Yan81], but that doesn't really worry me: minimal will probably do. If this is the complete graph, then graph theory doesn't seem to help us: the exciting case is when $\overline{\mathcal{G}}$ is smaller.
An ordering $\succ$ on the vertices $x_{1}, \ldots, x_{n}$ is a perfect elimination ordering (PEO) if $\forall i x_{i}$ and its neighbours $x_{j}: x_{j} \prec x_{i}$ form a clique. This, and chordality, can be found efficiently [RTL76]. Let $n^{\prime}$ be the maximal length of a path from $x_{1}$ to $x_{n}$ (as reordered) in $\mathcal{G}$ following $\succ$.

## Graph Theory to the rescue continued

Non-trivial chordality has been exploited.
Regular Chains [Che20] shows how it can be exploited efficiently.
Gröbner Bases [CP16] consider "chordal elimination". The challenge here is that an $S$-polynomial can introduce new edges in $\mathcal{G}$.
Triangular Chordality preserving is proved in [MBL21].
CAD [LXZZ21] consider chordality, ordering $x_{i}$ in a perfect elimination ordering, then essentially use the same algorithm.
$e_{d}$ is now $n^{\prime}$ rather than $n$ (polynomials "drop through" layers!).

2
The quantifier structure may be incompatible with the perfect elimination ordering.
What we currently lack is any view of how common in practice these non-trivial chordal structures are, but they are related to "nearly disconnected" $\mathcal{G}$.

## But [DM22] in CASC 2022 (being digested)

- [MBL21] proves that (sparse) triangular decomposition following a PEO preserves chordal structure.
- But when run in practice, they observe new edges.

Original Chordal Graph Graphs of triangular decompositions

?swap 2,3

(a)

(b)

Extra lines in red
There are four issues:

- Simplifying a Polynomial Set with Its Binomials;
- Simplifying a Polynomial System with Binomials;
- Reducing Inequation Polynomials with a Polynomial in the TS;
- Reducing a TS with a Polynomial in the TS.
? But is it safe to do these as a post-process?


## CGB=Comprehensive Gröbner Bases (I) [Wei98, FIS15]

The key idea is this. We consider an "innermost block" in this form:

$$
\exists \bar{x}\left(\begin{array}{c}
f_{1}(\bar{y}, \bar{x})=0 \wedge \cdots f_{r}(\bar{y}, \bar{x})=0 \wedge \\
p_{1}(\bar{y}, \bar{x})>0 \wedge \cdots p_{s}(\bar{y}, \bar{x})>0 \wedge \\
q_{1}(\bar{y}, \bar{x}) \neq 0 \wedge \cdots q_{t}(\bar{y}, \bar{x}) \neq 0
\end{array}\right)
$$

where $\bar{y}$ represents the remaining variables, and $f_{i}, p_{j}, q_{k} \in \mathbf{Q}[\bar{y}, \bar{x}] \backslash \mathbf{Q}[\bar{y}]$. We introduce new variables $\bar{z}$ and $\bar{w}$, with $\bar{z}, \bar{w} \succ \bar{x}$, and consider the polynomials

$$
\{f_{1}, \ldots, f_{r}, \underbrace{z_{1}^{2} p_{1}-1, \ldots, z_{s}^{2} p_{s}-1}_{\text {forcing positive }}, \underbrace{w_{1} q_{1}-1, \ldots, w_{t} q_{t}-1}_{\text {forcing nonzero }}\} .
$$

Let $\mathcal{G}=\left(S_{i}, G_{i}\right)$ be a Comprehensive Gröbner System (with parameters $\bar{y}$ ) for this so that $\bar{y}$ space is partitioned by the $S_{i}$. We claim each $G_{i}$ will be $\left\{f_{1}^{\prime}, \ldots, f_{r^{\prime}}^{\prime}, u_{1} z_{1}^{2}-p_{1}^{\prime}, \ldots, u_{s} z_{s}^{2}-p_{s}^{\prime}, v_{1} w_{1}-q_{1}^{\prime}, \ldots, v_{t} w_{t}-q_{t}^{\prime}\right\}$. Our answer will be $\bigvee_{i} \Psi_{i}\left(S_{i}, G_{i}\right)$ : next two slides explain $\Psi_{i}$.

## $G_{i}$ zero-dimensional ( $\bar{z}, \bar{w}$ irrelevant for dimension)

If $G_{i}=(1)$ then we return false. Otherwise recall
$G_{i}=\left\{f_{1}^{\prime}, \ldots, f_{r^{\prime}}^{\prime}, u_{1} z_{1}^{2}-p_{1}^{\prime}, \ldots, u_{s} z_{s}^{2}-p_{s}^{\prime}, v_{1} w_{1}-q_{1}^{\prime}, \ldots, v_{t} w_{t}-q_{t}^{\prime}\right\}$.
Let $I=\left\langle f_{1}^{\prime}, \ldots, f_{r^{\prime}}^{\prime}\right\rangle$,

$$
\chi(x)=\prod_{\left(e_{1}, \ldots, e_{s}\right) \in\{0,1\}^{s}} \chi_{\left(p_{1}^{\prime} / u_{1}\right)^{e_{1}, \ldots,\left(p_{s}^{\prime} / u_{s}\right)^{e_{s}}}}^{\prime}(x)=x^{2^{s} d}+\sum_{0}^{2^{s} d-1} a_{i} x^{i} .
$$

The answer is $\Psi_{i}:=\mathcal{F}\left(S_{i}\right) \wedge I_{2^{s} d}\left(a_{i}\right)$.
JHD: at least that's my reconstruction. I can't see where the $w_{i}$ (the $\neq 0$ ) terms come in. Also, the subscript of $\chi_{\ldots}^{\prime}$, the characteristic polynomial of $M_{\ldots}^{l}$, is not a polynomial.

## $\exists \phi: G_{i}>0$-dimensional ( $\bar{z}, \bar{w}$ irrelevant for dimension)

$\bar{u}:=$ maximal independent variables $\left(\bar{x}, G_{i}, \succ\right)$. (B)
If $\bar{u}=\bar{x}$ return $\operatorname{SYNRAC}(\mathcal{F}(S) \wedge \exists \bar{x} \phi)$ [Wei98]
$\bar{x}^{\prime}:=\bar{x} \backslash \bar{u} ; \phi_{1}:=\operatorname{Free}\left(\phi, \bar{x}^{\prime}\right) ; \phi_{2}:=\operatorname{NonFree}\left(\phi, \bar{x}^{\prime}\right)$;
$\varphi:=\phi_{1} \wedge \operatorname{Recurse}\left(S_{i}, \exists \bar{x}^{\prime} \phi_{2}\right) \quad$ (1)(A)
JHD: I think this means $\varphi$ now only contains $\bar{u}$-variables Let $\varphi_{1} \vee \cdots \vee \varphi_{\text {l }}$ be a disjunctive normal form of $\varphi$. (C) for $1 \leq j \leq /$ do

$$
\begin{aligned}
& \varphi_{j}^{(1)}:=\operatorname{Free}(\varphi, \bar{u}) ; \varphi_{j}^{(2)}:=\operatorname{NonFree}\left(\varphi_{j}, \bar{u}\right) ; \\
& \psi_{j}:=\varphi_{j}^{(1)} \wedge \operatorname{Recurse}\left(S_{i}, \exists \bar{u} \phi_{j}^{(2)}\right)
\end{aligned}
$$

Return $\Psi:=\mathcal{F}\left(S_{i}\right) \wedge\left(\psi_{1} \vee \cdots \vee \psi_{l}\right)$
JHD: "Recurse" goes right back to the MainQE, note that call (1) has pushed the $\bar{u}$-variables into being parameters (I think) (D).
But somehow $S_{i}$ gets lost in these recursions: I hope I've added it in the right place. Their Theorem 16 states that this does terminate - far from obvious (F).

## CGB=Comprehensive Gröbner Bases (IV) [Wei98, FIS15]

(A) Recursing with $S$ is, I think, my interpolation to make sense of the recursions we'll see later. $S$ initially is $\mathbf{R}^{\# \bar{y}}$.
(B) There's a lot of freedom here: ML?
( - Note that our main recursion is on $\phi$ in conjunctive normmal form (CNF), whereas here we convert to disjunctive normal form (DNF) and implicitly back at the end of the block. Since CNF $\leftrightarrow$ DNF naïvely is exponential, this would provide an exponential blowup at each $\exists / \forall$ boundary, similar to [DH88].
(0) Therefore this recursion is on strictly fewer variables, since $\operatorname{dim}>0$.
(e) Therefore this recursion is on strictly fewer variables, since $\bar{u} \neq \bar{x} . \varphi_{j}^{(1)}$ is free of $\bar{u}$ by construction, and free of $\bar{x}^{\prime}$ since it comes from $\phi_{1}$, so actually belongs in an outer block. We might ask why such things exist, but they could be generated by the recursion.
(9) But the two previous notes are probably key.

## Complexity of CGB

I know no results on the complexity of Comprehensive Gröbner Bases/Systems.
Since we are doing Gröbner Bases, we might hope for singly exponential behaviour at each block, and hence $e_{d}=O(a)$ rather than $O(n)$, but worst-case Gröbner bases can be doubly exponential [MR13]. If we get $O(a)$ behaviour, though, this does not depend on having a lot of equational constraints.
We are doing CNF/DNF conversions at each quantifier alternation, as with VTS, so this could be expected to give us $e_{m}=O(a)$ rather than $O(n)$.

## it's not R/C: it's quantifiers (and alternations)

[DH88, BD07] Are really about the combinatorial complexity of quantifier alternations
Let $S_{k}\left(x_{k}, y_{k}\right)$ be the statement $x_{k}=f\left(y_{k}\right)$ and then define recursively $S_{k-1}\left(x_{k-1}, y_{k-1}\right):=x_{k-1}=f\left(f\left(y_{k-1}\right)\right):=$

$$
\underbrace{\exists z_{k} \forall x_{k} \forall y_{k}}_{Q_{k}} \underbrace{(\underbrace{\left(y_{k-1}=y_{k} \wedge x_{k}=z_{k}\right.}_{L_{k}^{1}}) \vee(\underbrace{\left.y_{k}=z_{k} \wedge x_{k-1}=x_{k}\right)}_{L_{k}^{2}})}_{L_{k}} \Rightarrow S_{k}\left(x_{k}, y_{k}\right) .
$$

We can transpose this to the complexes, and get zero-dimensional QE examples in $\mathbf{C}^{n}$ with $2^{2^{O(n)}}$ isolated point solutions, roots of an irreducible polynomial of that degree [DH88]. Or can get that many even though the equations are all linear and the solution set is zero-dimensional [BD07].

$$
\exists z_{1} \forall x_{1} \forall y_{1}\left[\left(L_{1}^{1} \vee L_{1}^{2}\right) \Rightarrow \exists z_{2} \forall x_{2} \forall y_{2}\left[\left(L_{2}^{1} \vee L_{2}^{2}\right) \Rightarrow \Phi\right]\right]
$$

which becomes

$$
\exists z_{1} \forall x_{1} \forall y_{1} \exists z_{2} \forall x_{2} \forall y_{2}\left(L_{1}^{1} \vee L_{1}^{2}\right) \Rightarrow\left[\left(L_{2}^{1} \vee L_{2}^{2}\right) \Rightarrow \Phi\right] .
$$

The quantified part is then

$$
\left(\neg L_{1}^{1} \wedge \neg L_{1}^{2}\right) \vee\left(\neg L_{2}^{1} \wedge \neg L_{2}^{2}\right) \vee \Phi .
$$

We will get singly-exponential blow-up as we convert this to Conjunctive Normal Form

## Other questions than QE: multistaionarity

Consider ([BDE $\left.{ }^{+} 17\right]$ ) a single semi-algebraic set defined by

$$
\begin{gathered}
f_{1}\left(x_{1}, \ldots, x_{n-1}, k_{1}\right)=0 \wedge f_{2}\left(x_{1}, \ldots, x_{n-1}, k_{1}\right)=0 \wedge \cdots \\
f_{n-1}\left(x_{1}, \ldots, x_{n-1}, k_{1}\right)=0 \wedge x_{1}>0 \wedge \cdots \wedge x_{n-1}>0
\end{gathered}
$$

and ask the question "How does the number of solutions vary with $k_{1}$ ?" The $f_{i}$ are multilinear ( $d=1$ but $\mathfrak{d}=2,3,4$ ) and primitive, and are pretty "generic".
Of course, this doesn't guarantee that all the iterated resultants in [EBD15], or the Gröbner polynomials in [ED16], are primitive, but in practice they are.
In practice can handle $k_{1}, k_{2}$ and looking at $k_{1}, k_{2}, k_{3}$. But note we want $k_{1}, \ldots, k_{19}$ for the real biochemical application.

## Questions

(1) Can we actually say anything about the complexity of GB methods [EBD20]?
(2) What happens when we have equational constraints that don't involve the first projection variable?
(3) Can we actually say anything about the complexity of CGB-based methods for QE?
(1) Can CGB methods, which do QE, actually produce block-cylindrical algebraic decompositions? If so, this would be the first real construction here.
(5) Chordality: understand [DM22].
( Are there any "weak average case complexity" [AL17] results? The examples of [BD07, DH88] seem very special.
(1) Understand "which no sane algorithm would construct".

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