

# Proving an Execution of an Algorithm Correct?

James Davenport  
masjhd@bath.ac.uk

University of Bath

16 February 2023

The quintessential NP-complete problem: Given a Boolean statement  $\Phi(x_1, \dots, x_n)$  produce

either  $f : \{x_i\} \mapsto \{T, F\}$  such that  
 $\Phi(f(x_1), \dots, f(x_n)) = T$  (a satisfying assignment)  
 $\perp$  indicating that no satisfying assignment exists.

The first can be verified easily enough: what about the second? Since at least 2016, contestants in the annual SAT contests have been required to produce proofs (occasionally  $> 100\text{GiB!}$ ) in DRAT format, which can be checked (Marijn says there are subtleties to “easy” checking).

# Integration

P is algebra professor, S is awkward student

P  $e^{-x^2}$  has no integral.

S But in analysis the professor proved that every continuous function has an integral.

P I meant that there was no formula for the integral.

S But in statistics the professor used  $\text{erf}(x)$  and everything seemed OK.

P I meant that there was no *elementary* formula, in terms of  $\exp$ ,  $\log$  and the solution of polynomial equations.

S How do you prove that?

P Differential Algebra!

S What's that?

P A field  $K$  equipped with  $' : K \rightarrow K$  such that  $(a + b)' = a' + b'$  and  $(ab)' = a'b + ab'$ .

Given  $f \in K = \mathbf{Q}(x, \theta_1, \dots, \theta_n)$  where  $x' = 1$  and each  $\theta_i$  is elementary over  $\mathbf{Q}(x, \theta_1, \dots, \theta_{i-1})$  (need *decidable* [Ric68]) produce

either  $F$  in some elementary extension  $L$  of  $K$  such that  $F' = f$  (an elementary integral)

or  $\perp$  indicating that no such elementary integral exists.

The first can be verified: what about the second?



The verification isn't necessarily trivial: there are issues of simplification of elementary functions.



Because of branch cuts,  $F$  might not denote a continuous function  $\mathbf{R} \rightarrow \mathbf{R}$ , despite the student's memory of analysis [CDJW00].

The Heaviside function differentiates to 0, so it's a "constant" in terms of differentiable algebra.

# Liouville's Principle [Lio35, Rit50]

Looking for any elementary might seem like “needle in a haystack”.

## Theorem (Liouville's Principle)

*Let  $f$  be an expression from some expression field  $K$ . If  $f$  has an elementary integral over  $K$ , it has an integral of the following form:*

$$\int f = v_0 + \sum_{i=1}^n c_i \log v_i, \quad (1)$$

*where  $v_0$  belongs to  $K$ , the  $v_i$  belong to  $\hat{K}$ , an extension of  $K$  by a finite number of constants algebraic over  $\text{const } K$ , and the  $c_i$  belong to  $\hat{K}$  and are constant.*

Alternatively

$$f = v_0' + \sum_{i=1}^n c_i \frac{v_i'}{v_i}. \quad (2)$$

Only a single bale of hay! Proof by equating coefficients in  $f = F'$ .

$f, g \in \overline{\mathbf{Q}}(x, \theta_1, \dots, \theta_n)$  where each  $\theta_i$  is either

**logarithmic**  $\theta'_i = \frac{u'_i}{u_i}$ ,  $u_i \in \overline{\mathbf{Q}}(x, \theta_1, \dots, \theta_{i-1})$ .

**exponential**  $\theta'_i = u'_i \theta_i$ ,  $u_i \in \overline{\mathbf{Q}}(x, \theta_1, \dots, \theta_{i-1})$ .

Induct on  $n$ , that we can

$$\int \text{Solve (or } \perp) f = v'_0 + \sum_{i=1}^n c_i \frac{v'_i}{v_i}$$

**Risch o.d.e.** Solve (or  $\perp$ )  $y' + fy = g$  for  $y \in \overline{\mathbf{Q}}(x, \theta_1, \dots, \theta_n)$ .

In both cases, the algorithm is a fairly messy “comparison of terms” argument, and the Risch o.d.e. for exponential  $\theta_n$  was a “similarly”, which wasn't quite [Dav86].

The “mess” comes in showing that every case is covered, and that the “bug fix” in [Dav86] is complete: each individual case is fairly straightforward.

# Producing a proof of $\perp$

① Have a formal proof of Liouville's Principle.



I haven't done this formally, but it doesn't look outrageous: it's all algebra in [Rit48].

② At each comparison of terms, spit this out in a form that a theorem-prover can digest.



Again, I haven't done this, but I did have an implementation in Axiom which produced a (very stylised) informal proof.

Note that I am *not* considering the case of  $\theta_i$  algebraic.  $\theta_1$  algebraic is in [Dav81], but there is **much** more mathematics involved in finding the  $c_i, v_i$  or proving they don't exist. More general is in [Bro90, Bro91], again more mathematics.

"Mathematics" *may* reduce to "is a divisor on an elliptic curve a torsion divisor", and  $\perp$  here is hard.

**Thanks** to this conference, I knew I should talk to Anne Baanen.

**And** now done, but we should keep talking.

Let each  $Q_i$  be one of the quantifiers  $\forall, \exists$ . Real Quantifier Elimination problem is the following: given a statement

$$\Phi_0 := Q_1 x_{1,1}, \dots, x_{1,k_1} \cdots Q_{a+1} x_{a+1,1}, \dots, x_{a+1,k_{a+1}} \Phi(y_i, x_{i,j}), \quad (3)$$

where  $\Phi$  is a Boolean combination of equalities and inequalities between real polynomials  $P_\alpha(y_i, x_{i,j})$ , produce a Boolean combination  $\Psi$  of equalities and inequalities between polynomials  $Q_\beta(y_i)$  which is equisatisfiable, i.e.  $\Psi$  is true if and only  $\Phi_0$  is true. If all the polynomials  $Q_\beta(y_i)$  in  $\Psi(y_i)$  have integer coefficients, we call  $\Psi(y_i)$  a Tarski formula.

- Proved decidable in 1950s
- First feasible solution by [Col75] through Cylindrical Algebraic Decomposition



Fix coordinates in  $\mathbf{R}^n$  consistent with quantifier order.

Given a set of polynomials  $\{p_\alpha\}$  in  $\overline{\mathbf{Q}}[x_1, \dots, x_n]$ , produce a finite set of cells  $C_i \subset \mathbf{R}^n$  which is:

**Cylindrical**  $\forall i, j, k \text{ Proj}_{\mathbf{R}^k}(C_i), \text{Proj}_{\mathbf{R}^k}(C_j)$  are equal or disjoint;

**Algebraic** Defined by polynomials in  $\overline{\mathbf{Q}}[x_1, \dots, x_n]$ ;

**Decomposition** disjoint and cover  $\mathbf{R}^n$ ;

**Sampled** each cell has a sample point  $s_i$  (cylindrical);

such that on each cell every  $p_\alpha$  is sign-invariant  $(+, -, 0)$ .

Then the truth of  $\Phi$  is invariant on a cell, and we can write down  $\Psi$  as the union of those cells where  $\Phi_0$  is true at the sample point. Unfortunately QE is doubly exponential in  $n$  [DH88], so CAD's worst case must be, and in practice CAD nearly always is.

# Challenges with Cylindrical Algebraic Decomposition

- CAD doesn't care about the quantifiers (other than variable order), in particular  $\exists x_1, \dots, x_n \Phi$  (the SAT problem) isn't treated as a special case.
- As formulated, it doesn't care about the Boolean structure of  $\Phi$ .

✓ When it's  $(p_1 = 0) \wedge \Phi'$  we can do better [McC99].

✓ Even if this is only part of  $\Phi$ , we can use an equality [EBD15].

- If  $f, g, h$  have degree  $d$ ,  $\text{res}_y(\text{res}_z(f, g), \text{res}_z(f, h))$  has degree  $O(d^4)$ , even though there are only  $O(d^3)$  common solutions  $f(x, y, z) = g(x, y, z) = h(x, y, z)$ .

!  $f(x, y, z_1) = g(x, y, z_1); f(x, y, z_2) = h(x, y, z_2)$ . Note that these points *are* relevant for cylindricity in the worst case, and are used in [DH88].

- Major improvements to CAD import more mathematics, up to “Puisseux with parameters” [MPP19].
- Despite attempts [CM10], there is no formal proof of correctness of even basic Collins.

# Cylindrical Algebraic Coverings I [ADEK21]

For purely existential problems  $\exists x_k, \dots, x_n \Phi$ .

$\sigma_{i,j} \in \{=, <, \leq, >, \geq\}$ , but for exposition, assume all

$\sigma_{i,j} \in \{<, >\}$ .

①  $\Phi = (p_{1,1}\sigma_{1,1}0 \wedge \dots) \vee (p_{2,1}\sigma_{2,1}0 \wedge \dots) \vee \dots$

② Commute  $\exists$  and  $\vee$  and treat each disjunct  $\Phi_i$  separately

So we don't care where  $p_{1,1}$  and  $p_{2,1}$  meet. Doesn't change asymptotics, but may well be useful in practice.

③ Choose a sample point  $(s_1, \dots, s_n^{(1)})$ .

④ If this satisfies  $\Phi_i$  return SAT (and witness)

⑤ Otherwise  $\exists j : p_{i,j}(s_1, \dots, s_n^{(1)}) \not\sigma_{i,j}0$ . Remember  $j$  with  $(s_1, \dots, s_n^{(1)})$ .

⑥ Compute largest interval  $I_{n,1} = (l, u)$  such that  $\forall x_n \in (l, u) p_{i,j}(s_1, \dots, x_n) \not\sigma_{i,j}0$ .

⑦ If  $I_{n,1} \neq \mathbf{R}$  choose  $s_n^{(2)} \notin I_{n,1}$ . If  $(s_1, \dots, s_n^{(2)})$  satisfies  $\Phi_i$  return SAT (and witness).

⑧ Repeat steps 5–7 until  $(s_1, \dots, s_{n-1}, \mathbf{R})$  is covered.

\* Some intervals might be redundant, so prune

- 9 Each of  $I_{n,i}$  defines an oval in  $(s_1, \dots, s_{n-2}, x, y)$  space which cover  $(s_1, \dots, s_{n-1}, \mathbf{R})$ .
- 10 Compute largest interval  $I_{n-1,1} = (l, u)$  such that  $\forall x_{n-1} \in (l, u)$  the  $I_{n,i}$  cover  $(s_1, \dots, s_{n-2}, x_{n-1}, \mathbf{R})$ .
- 11 If  $I_{n-1,1} \neq \mathbf{R}$  choose a different value of  $s_{n-1}, \notin I_{n-1,1}$ .
- 12 Repeat steps 4–11 until  $(s_1, \dots, s_{n-2}, \mathbf{R})$  is covered.
- 13 Repeat, decreasing the dimension, until we're covered the whole of the  $x_1$ -axis (or we get SAT).

Termination isn't entirely obvious, but each cell we compute contains at least one cell (the cell its sample point is in) from a CAD for the same polynomials, and the CAD itself is finite.

# How might these be verifiable?

This is still work in progress, and there is more than one option

## A. Verifying each (non-redundant) calculation in reverse




- 1 For each  $I^{(1)} = (l_1, r_1)$  as an interval of  $\mathbf{R}^1$  prove that it's covered because
- 2 For each  $I^{(2)} = (l_2, r_2)$  covering the cylinder above  $I^{(1)}$  prove that  $I^{(1)} \times I^{(2)}$  is covered because
- 3 ...
- 4 For each  $I^{(n)} = (l_n, r_n)$  covering the cylinder above  $I^{(1)} \times I^{(2)} \times \dots$  prove that  $I^{(1)} \times I^{(2)} \times \dots \times I^{(n)}$  is covered by the  $p_j$  we remembered for that sample point.


## B Reverse-engineering a rough "CAD".

- 1 For each sample point  $(s_1, \dots, s_n)$  check that the corresponding cuboid  $I^{(1)} \times I^{(2)} \times \dots \times I^{(n)}$  is contained within the  $p_j \neq 0$  region.
- 2 Verify that these cuboids are arranged cylindrically, and are complete.

Need Resultants and inequalities, but no topology.

- UNSAT, or its equivalent, can be a bigger challenge than positive answers.
- Completeness proofs of algorithms can be challenging.
- But *in some cases*, we may not need the completeness proof.
- (At least not in all cases).
- This may require more book-keeping in the algorithm, to keep the “hints” that drove us this way.
- Possibly (e.g. algebraic integration) we may not be able to prove UNSAT in all circumstances.
- ? is this still valuable?

-  E. Abraham, J.H. Davenport, M. England, and G. Kremer.  
Deciding the Consistency of Non-Linear Real Arithmetic Constraints with a Conflict Driven Search Using Cylindrical Algebraic Coverings.  
*Journal of Logical and Algebraic Methods in Programming*  
Article 100633, 119, 2021.
-  M. Bronstein.  
Integration of elementary function.  
*J. Symbolic Comp.*, 9:117–173, 1990.
-  M. Bronstein.  
The Algebraic Risch Differential Equation.  
In *Proceedings ISSAC 91*, pages 241–246, 1991.

-  R.M. Corless, J.H. Davenport, D.J. Jeffrey, and S.M. Watt.  
According to Abramowitz and Stegun, or arccoth needn't be uncouth.  
*SIGSAM Bulletin 2*, 34:58–65, 2000.
-  C. Cohen and A. Mahboubi.  
A Formal Quantifier Elimination for Algebraically Closed Fields.  
In S. Autexier *et al.*, editor, *Proceedings CICM 2010*, pages 189–203, 2010.
-  G.E. Collins.  
Quantifier Elimination for Real Closed Fields by Cylindrical Algebraic Decomposition.  
In *Proceedings 2nd. GI Conference Automata Theory & Formal Languages*, pages 134–183, 1975.





J.H. Davenport.

*On the Integration of Algebraic Functions*, volume 102 of *Springer Lecture Notes in Computer Science*.  
Springer Berlin–Heidelberg–New York (Russian ed. MIR Moscow 1985), 1981.



J.H. Davenport.

On the Risch Differential Equation Problem.  
*SIAM J. Comp.*, 15:903–918, 1986.



J.H. Davenport and J. Heintz.

Real Quantifier Elimination is Doubly Exponential.  
*J. Symbolic Comp.*, 5:29–35, 1988.



M. England, R. Bradford, and J.H. Davenport.  
Improving the Use of Equational Constraints in Cylindrical Algebraic Decomposition.

In D. Robertz, editor, *Proceedings ISSAC 2015*, pages 165–172, 2015.



J. Liouville.

Mémoire sur l'intégration d'une classe de fonctions transcendentes.

*Crelle's J.*, 13:93–118, 1835.



S. McCallum.

On Projection in CAD-Based Quantifier Elimination with Equational Constraints.

In S. Dooley, editor, *Proceedings ISSAC '99*, pages 145–149, 1999.



S. McCallum, A. Parusiński, and L. Paunescu.

Validity proof of Lazard's method for CAD construction.

*J. Symbolic Comp.*, 92:52–69, 2019.



D. Richardson.

Some Unsolvable Problems Involving Elementary Functions of a Real Variable.

*Journal of Symbolic Logic*, 33:514–520, 1968.



R.H. Risch.

The Problem of Integration in Finite Terms.

*Trans. A.M.S.*, 139:167–189, 1969.



J.F. Ritt.

*Integration in Finite Terms: Liouville's Theory of Elementary Methods.*

Columbia University Press, 1948.



J.F. Ritt.

*Differential Algebra.*

Colloquium Proceedings vol. XXXIII. American Mathematical Society, 1950.



A. Seidenberg.

A new decision method for elementary algebra.

*Ann. Math.*, 60:365–374, 1954.



A. Tarski.

*A Decision Method for Elementary Algebra and Geometry.*

2nd ed., Univ. Cal. Press. Reprinted in *Quantifier Elimination and Cylindrical Algebraic Decomposition* (ed. B.F. Caviness & J.R. Johnson), Springer-Verlag, Wein-New York, 1998, pp. 24–84., 1951.