

# The unreasonable effectiveness of algebra (but don't take it for granted)

James Davenport

University of Bath  
(visiting Waterloo)

11 June 2009

What is the derivative of  $\sin x$ ?

What is the derivative of  $\sin x$ ?

$$f'(x) = \lim_{\delta \rightarrow 0} \left( \frac{\sin(x + \delta) - \sin(x)}{\delta} \right)$$

## What is the derivative of $\sin x$ ?

$$f'(x) = \lim_{\delta \rightarrow 0} \left( \frac{\sin(x + \delta) - \sin(x)}{\delta} \right)$$

$$\forall \epsilon > 0 \exists D_\epsilon : \delta < D_\epsilon \Rightarrow \left| f'(x) - \frac{\sin(x + \delta) - \sin(x)}{\delta} \right| < \epsilon$$

## What is the derivative of $\sin x$ ?

$$f(x) = \lim_{\delta \rightarrow 0} \left( \frac{\sin(x + \delta) - \sin(x)}{\delta} \right)$$

$$\forall \epsilon > 0 \exists D_\epsilon : \delta < D_\epsilon \Rightarrow \left| f(x) - \frac{\sin(x + \delta) - \sin(x)}{\delta} \right| < \epsilon$$

$\sin(x + \delta) - \sin(x) = \cos(x) \sin(\delta) - \sin(x)(1 - \cos(\delta))$  so we can make the choice  $f(x) = \cos(x)$ .

## What is the derivative of $\sin x$ ?

$$f'(x) = \lim_{\delta \rightarrow 0} \left( \frac{\sin(x + \delta) - \sin(x)}{\delta} \right)$$

$$\forall \epsilon > 0 \exists D_\epsilon : \delta < D_\epsilon \Rightarrow \left| f'(x) - \frac{\sin(x + \delta) - \sin(x)}{\delta} \right| < \epsilon$$

$\sin(x + \delta) - \sin(x) = \cos(x) \sin(\delta) - \sin(x)(1 - \cos(\delta))$  so we can make the choice  $f'(x) = \cos(x)$ . We can then take

$D_\epsilon = \frac{1}{2} \min(\sqrt{\epsilon}, 1)$ , and some simple algebra shows the result.

## What is the derivative of $\sin x$ ?

$$f(x) = \lim_{\delta \rightarrow 0} \left( \frac{\sin(x + \delta) - \sin(x)}{\delta} \right)$$

$$\forall \epsilon > 0 \exists D_\epsilon : \delta < D_\epsilon \Rightarrow \left| f(x) - \frac{\sin(x + \delta) - \sin(x)}{\delta} \right| < \epsilon$$

$\sin(x + \delta) - \sin(x) = \cos(x) \sin(\delta) - \sin(x)(1 - \cos(\delta))$  so we can make the choice  $f(x) = \cos(x)$ . We can then take

$D_\epsilon = \frac{1}{2} \min(\sqrt{\epsilon}, 1)$ , and some simple algebra shows the result.

Did any of you do that?

## What is the derivative of $\sin x$ ?

$$f(x) = \lim_{\delta \rightarrow 0} \left( \frac{\sin(x + \delta) - \sin(x)}{\delta} \right)$$

$$\forall \epsilon > 0 \exists D_\epsilon : \delta < D_\epsilon \Rightarrow \left| f(x) - \frac{\sin(x + \delta) - \sin(x)}{\delta} \right| < \epsilon$$

$\sin(x + \delta) - \sin(x) = \cos(x) \sin(\delta) - \sin(x)(1 - \cos(\delta))$  so we can make the choice  $f(x) = \cos(x)$ . We can then take

$D_\epsilon = \frac{1}{2} \min(\sqrt{\epsilon}, 1)$ , and some simple algebra shows the result.

Did any of you do that?

Did any of you take  $D_\epsilon = \frac{\min(\sqrt{\epsilon}, 1)}{2 \max(|\cos(x)|, |\sin(x)|, 1)}$  to allow for  $x \in \mathbf{C}$ ?



## What is the derivative of $\sin x$ ?

$$f'(x) = \lim_{\delta \rightarrow 0} \left( \frac{\sin(x + \delta) - \sin(x)}{\delta} \right)$$

$$\forall \epsilon > 0 \exists D_\epsilon : \delta < D_\epsilon \Rightarrow \left| f'(x) - \frac{\sin(x + \delta) - \sin(x)}{\delta} \right| < \epsilon$$

$\sin(x + \delta) - \sin(x) = \cos(x) \sin(\delta) - \sin(x)(1 - \cos(\delta))$  so we can make the choice  $f'(x) = \cos(x)$ . We can then take

$D_\epsilon = \frac{1}{2} \min(\sqrt{\epsilon}, 1)$ , and some simple algebra shows the result.

Did any of you do that?

Did any of you take  $D_\epsilon = \frac{\min(\sqrt{\epsilon}, 1)}{2 \max(|\cos(x)|, |\sin(x)|, 1)}$  to allow for  $x \in \mathbf{C}$ ?

Or did you “just know it”?

What is the integral:  $\int_0^{\pi/2} \cos x$ ?

What is the integral:  $\int_0^{\pi/2} \cos x$ ?

$$I = \lim_{|\Delta| \rightarrow 0} \bar{S}_\Delta [\cos(x)] = \lim_{|\Delta| \rightarrow 0} \underline{S}_\Delta [\cos(x)]$$

( $\Delta$  ranges over all dissections of  $[0, \pi/2]$ )

What is the integral:  $\int_0^{\pi/2} \cos x$ ?

$$I = \lim_{|\Delta| \rightarrow 0} \bar{S}_\Delta [\cos(x)] = \lim_{|\Delta| \rightarrow 0} \underline{S}_\Delta [\cos(x)]$$

( $\Delta$  ranges over all dissections of  $[0, \pi/2]$ )

Does anyone actually do this?

What is the integral:  $\int_0^{\pi/2} \cos x$ ?

$$I = \lim_{|\Delta| \rightarrow 0} \bar{S}_\Delta [\cos(x)] = \lim_{|\Delta| \rightarrow 0} \underline{S}_\Delta [\cos(x)]$$

( $\Delta$  ranges over all dissections of  $[0, \pi/2]$ )

Does anyone actually do this?

*Can* anyone actually do this?

What is the integral:  $\int_0^{\pi/2} \cos x$ ?

$$I = \lim_{|\Delta| \rightarrow 0} \bar{S}_\Delta [\cos(x)] = \lim_{|\Delta| \rightarrow 0} \underline{S}_\Delta [\cos(x)]$$

( $\Delta$  ranges over all dissections of  $[0, \pi/2]$ )

Does anyone actually do this?

*Can* anyone actually do this?

Or do we say “well, we have proved that  $\sin' = \cos$ , so  $\int \cos = \sin$ , and therefore the answer is  $\sin \frac{\pi}{2} - \sin 0 = 1$ ?

What is the integral:  $\int_0^{\pi/2} \cos x$ ?

$$I = \lim_{|\Delta| \rightarrow 0} \bar{S}_\Delta [\cos(x)] = \lim_{|\Delta| \rightarrow 0} \underline{S}_\Delta [\cos(x)]$$

( $\Delta$  ranges over all dissections of  $[0, \pi/2]$ )

Does anyone actually do this?

*Can* anyone actually do this?

Or do we say “well, we have proved that  $\sin' = \cos$ , so  $\int \cos = \sin$ , and therefore the answer is  $\sin \frac{\pi}{2} - \sin 0 = 1$ ?

We might say “therefore, by the Fundamental Theorem of Calculus, . . .”

What is the Fundamental Theorem of Calculus?



# What is the Fundamental Theorem of Calculus?

Indeed, what is calculus?

# What is the Fundamental Theorem of Calculus?

Indeed, what is calculus?

*... the deism of Leibniz over the dotage of Newton ...*  
*[Babbage, chapter 4]*

# What is the Fundamental Theorem of Calculus?

Indeed, what is calculus?

*... the deism of Leibniz over the dotage of Newton ...*  
*[Babbage, chapter 4]*

I claim that calculus is actually the interesting fusion of *two, different* subjects.

# What is the Fundamental Theorem of Calculus?

Indeed, what is calculus?

*... the deism of Leibniz over the dotage of Newton ...*  
*[Babbage, chapter 4]*

I claim that calculus is actually the interesting fusion of *two, different* subjects.

- What you learned in calculus, which I shall write as  $D_{\epsilon\delta}$ : the “differentiation of  $\epsilon$ - $\delta$  analysis”. Also  $\frac{d}{d_{\epsilon\delta}x}$ , and its inverse  ${}_{\epsilon\delta}\int$ .

# What is the Fundamental Theorem of Calculus?

Indeed, what is calculus?

*... the deism of Leibniz over the dotage of Newton ...*  
*[Babbage, chapter 4]*

I claim that calculus is actually the interesting fusion of *two, different* subjects.

- What you learned in calculus, which I shall write as  $D_{\epsilon\delta}$ : the “differentiation of  $\epsilon$ - $\delta$  analysis”. Also  $\frac{d}{d_{\epsilon\delta}x}$ , and its inverse  ${}_{\epsilon\delta}\int$ .
- What is taught in differential algebra, which I shall write as  $D_{DA}$ : the “differentiation of differential algebra”. Also  $\frac{d}{d_{DA}x}$ , and its inverse  ${}_{DA}\int$ .

$D_{\epsilon\delta}$  (for functions  $\mathbf{R} \rightarrow \mathbf{R}$ )

## $D_{\epsilon\delta}$ (for functions $\mathbf{R} \rightarrow \mathbf{R}$ )

Define  $\text{CL}(f, x_0)$  (the “Cauchy Limit”) as

$$\text{CL}(f, x_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

and  $D_{\epsilon\delta}(f) = \lambda x. \text{CL}(f, x)$ .

## $D_{\epsilon\delta}$ (for functions $\mathbf{R} \rightarrow \mathbf{R}$ )

Define  $\text{CL}(f, x_0)$  (the “Cauchy Limit”) as

$$\text{CL}(f, x_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

and  $D_{\epsilon\delta}(f) = \lambda x. \text{CL}(f, x)$ . Then the following are theorems.



## $D_{\epsilon\delta}$ (for functions $\mathbf{R} \rightarrow \mathbf{R}$ )

Define  $\text{CL}(f, x_0)$  (the “Cauchy Limit”) as

$$\text{CL}(f, x_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

and  $D_{\epsilon\delta}(f) = \lambda x. \text{CL}(f, x)$ . Then the following are theorems.

- $D_{\epsilon\delta}(c) = 0 \quad \forall c \text{ constants.}$

## $D_{\epsilon\delta}$ (for functions $\mathbf{R} \rightarrow \mathbf{R}$ )

Define  $\text{CL}(f, x_0)$  (the “Cauchy Limit”) as

$$\text{CL}(f, x_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

and  $D_{\epsilon\delta}(f) = \lambda x. \text{CL}(f, x)$ . Then the following are theorems.

- $D_{\epsilon\delta}(c) = 0 \quad \forall c \text{ constants.}$
- $\text{CL}(f + g, x_0) = \text{CL}(f, x_0) + \text{CL}(g, x_0)$ , so  
 $D_{\epsilon\delta}(f + g) = D_{\epsilon\delta}(f) + D_{\epsilon\delta}(g)$ .

## $D_{\epsilon\delta}$ (for functions $\mathbf{R} \rightarrow \mathbf{R}$ )

Define  $\text{CL}(f, x_0)$  (the “Cauchy Limit”) as

$$\text{CL}(f, x_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

and  $D_{\epsilon\delta}(f) = \lambda x. \text{CL}(f, x)$ . Then the following are theorems.

- $D_{\epsilon\delta}(c) = 0 \quad \forall c \text{ constants.}$
- $\text{CL}(f + g, x_0) = \text{CL}(f, x_0) + \text{CL}(g, x_0)$ , so  
 $D_{\epsilon\delta}(f + g) = D_{\epsilon\delta}(f) + D_{\epsilon\delta}(g)$ .
- $\text{CL}(fg, x_0) = \text{CL}(f, x_0)g(x_0) + f(x_0)\text{CL}(g, x_0)$ , so  
 $D_{\epsilon\delta}(fg) = D_{\epsilon\delta}(f)g + fD_{\epsilon\delta}(g)$ .

## $D_{\epsilon\delta}$ (for functions $\mathbf{R} \rightarrow \mathbf{R}$ )

Define  $\text{CL}(f, x_0)$  (the “Cauchy Limit”) as

$$\text{CL}(f, x_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

and  $D_{\epsilon\delta}(f) = \lambda x. \text{CL}(f, x)$ . Then the following are theorems.

- $D_{\epsilon\delta}(c) = 0 \quad \forall c \text{ constants.}$
- $\text{CL}(f + g, x_0) = \text{CL}(f, x_0) + \text{CL}(g, x_0)$ , so  
 $D_{\epsilon\delta}(f + g) = D_{\epsilon\delta}(f) + D_{\epsilon\delta}(g)$ .
- $\text{CL}(fg, x_0) = \text{CL}(f, x_0)g(x_0) + f(x_0)\text{CL}(g, x_0)$ , so  
 $D_{\epsilon\delta}(fg) = D_{\epsilon\delta}(f)g + fD_{\epsilon\delta}(g)$ .
- $D_{\epsilon\delta}(\lambda x. f(g(x))) = D_{\epsilon\delta}(g)\lambda x. D_{\epsilon\delta}(f)(g(x))$ . (Chain rule)

## $D_{\text{DA}}$ (for *any* ring $R$ of characteristic 0)

Definition:  $D_{\text{DA}} : R \rightarrow R$  is a *derivation* on  $R$  if it satisfies:

## $D_{\text{DA}}$ (for any ring $R$ of characteristic 0)

Definition:  $D_{\text{DA}} : R \rightarrow R$  is a *derivation* on  $R$  if it satisfies:

- $D_{\text{DA}}(f + g) = D_{\text{DA}}(f) + D_{\text{DA}}(g)$

## $D_{\text{DA}}$ (for any ring $R$ of characteristic 0)

Definition:  $D_{\text{DA}} : R \rightarrow R$  is a *derivation* on  $R$  if it satisfies:

- $D_{\text{DA}}(f + g) = D_{\text{DA}}(f) + D_{\text{DA}}(g)$
- $D_{\text{DA}}(fg) = D_{\text{DA}}(f)g + fD_{\text{DA}}(g)$

## $D_{\text{DA}}$ (for any ring $R$ of characteristic 0)

Definition:  $D_{\text{DA}} : R \rightarrow R$  is a *derivation* on  $R$  if it satisfies:

- $D_{\text{DA}}(f + g) = D_{\text{DA}}(f) + D_{\text{DA}}(g)$
- $D_{\text{DA}}(fg) = D_{\text{DA}}(f)g + fD_{\text{DA}}(g)$



## $D_{\text{DA}}$ (for any ring $R$ of characteristic 0)

Definition:  $D_{\text{DA}} : R \rightarrow R$  is a *derivation* on  $R$  if it satisfies:

- $D_{\text{DA}}(f + g) = D_{\text{DA}}(f) + D_{\text{DA}}(g)$
- $D_{\text{DA}}(fg) = D_{\text{DA}}(f)g + fD_{\text{DA}}(g)$

**Corollaries:**

## $D_{\text{DA}}$ (for any ring $R$ of characteristic 0)

Definition:  $D_{\text{DA}} : R \rightarrow R$  is a *derivation* on  $R$  if it satisfies:

- $D_{\text{DA}}(f + g) = D_{\text{DA}}(f) + D_{\text{DA}}(g)$
- $D_{\text{DA}}(fg) = D_{\text{DA}}(f)g + fD_{\text{DA}}(g)$

**Corollaries:**

- $D_{\text{DA}}(c) = 0$  for all  $c$  algebraic over  $\langle 1 \rangle$ .

## $D_{\text{DA}}$ (for any ring $R$ of characteristic 0)

Definition:  $D_{\text{DA}} : R \rightarrow R$  is a *derivation* on  $R$  if it satisfies:

- $D_{\text{DA}}(f + g) = D_{\text{DA}}(f) + D_{\text{DA}}(g)$
- $D_{\text{DA}}(fg) = D_{\text{DA}}(f)g + fD_{\text{DA}}(g)$

**Corollaries:**

- $D_{\text{DA}}(c) = 0$  for all  $c$  algebraic over  $\langle 1 \rangle$ .
- $D_{\text{DA}}\left(\frac{f}{g}\right) = \frac{D_{\text{DA}}(f)g - fD_{\text{DA}}(g)}{g^2}$ .

## $D_{\text{DA}}$ (for any ring $R$ of characteristic 0)

Definition:  $D_{\text{DA}} : R \rightarrow R$  is a *derivation* on  $R$  if it satisfies:

- $D_{\text{DA}}(f + g) = D_{\text{DA}}(f) + D_{\text{DA}}(g)$
- $D_{\text{DA}}(fg) = D_{\text{DA}}(f)g + fD_{\text{DA}}(g)$

**Corollaries:**

- $D_{\text{DA}}(c) = 0$  for all  $c$  algebraic over  $\langle 1 \rangle$ .
- $D_{\text{DA}}\left(\frac{f}{g}\right) = \frac{D_{\text{DA}}(f)g - fD_{\text{DA}}(g)}{g^2}$ .
- $D_{\text{DA}}$  extends uniquely to algebraic extensions.

## $D_{\text{DA}}$ (for any ring $R$ of characteristic 0)

Definition:  $D_{\text{DA}} : R \rightarrow R$  is a *derivation* on  $R$  if it satisfies:

- $D_{\text{DA}}(f + g) = D_{\text{DA}}(f) + D_{\text{DA}}(g)$
- $D_{\text{DA}}(fg) = D_{\text{DA}}(f)g + fD_{\text{DA}}(g)$

**Corollaries:**

- $D_{\text{DA}}(c) = 0$  for all  $c$  algebraic over  $\langle 1 \rangle$ .
- $D_{\text{DA}}\left(\frac{f}{g}\right) = \frac{D_{\text{DA}}(f)g - fD_{\text{DA}}(g)}{g^2}$ .
- $D_{\text{DA}}$  extends uniquely to algebraic extensions.

## $D_{\text{DA}}$ (for any ring $R$ of characteristic 0)

Definition:  $D_{\text{DA}} : R \rightarrow R$  is a *derivation* on  $R$  if it satisfies:

- $D_{\text{DA}}(f + g) = D_{\text{DA}}(f) + D_{\text{DA}}(g)$
- $D_{\text{DA}}(fg) = D_{\text{DA}}(f)g + fD_{\text{DA}}(g)$

**Corollaries:**

- $D_{\text{DA}}(c) = 0$  for all  $c$  algebraic over  $\langle 1 \rangle$ .
- $D_{\text{DA}}\left(\frac{f}{g}\right) = \frac{D_{\text{DA}}(f)g - fD_{\text{DA}}(g)}{g^2}$ .
- $D_{\text{DA}}$  extends uniquely to algebraic extensions.

Note that there is no Chain Rule as such, since composition is not necessarily a defined concept on  $R$ .

A note on the word “constant”

## A note on the word “constant”

We said

- $D_{DA}(c) = 0$  for all  $c$  algebraic over  $\langle 1 \rangle$ .



## A note on the word “constant”

We said

- $D_{DA}(c) = 0$  for all  $c$  algebraic over  $\langle 1 \rangle$ .
- “constants differentiate to 0”

## A note on the word “constant”

We said

- $D_{DA}(c) = 0$  for all  $c$  algebraic over  $\langle 1 \rangle$ .
- “constants differentiate to 0”

## A note on the word “constant”

We said

- $D_{DA}(c) = 0$  for all  $c$  algebraic over  $\langle 1 \rangle$ .
- “constants differentiate to 0”

By **abuse** of language, we say that anything that differentiates to zero is a “constant<sub>DA</sub>”.

## How are the two subjects related?

If we define  $D_{DA}(x) = 1$ , then  $D_{DA}$  is defined on  $\mathbf{Z}[x]$ , and extends to  $\mathbf{Q}(x)$  and indeed  $\overline{\mathbf{Q}(x)}$ .

## How are the two subjects related?

If we define  $D_{\text{DA}}(x) = 1$ , then  $D_{\text{DA}}$  is defined on  $\mathbf{Z}[x]$ , and extends to  $\overline{\mathbf{Q}(x)}$  and indeed  $\overline{\mathbf{Q}(x)}$ .

If we interpret (denoted  $\mathcal{I}$ )  $\overline{\mathbf{Q}(x)}$  as functions  $\mathbf{R} \rightarrow \mathbf{R}$ , then  $D_{\text{DA}}$  can be interpreted as  $D_{\epsilon\delta}$ , i.e.

$$\mathcal{I}(D_{\text{DA}}(f)) = D_{\epsilon\delta}(\mathcal{I}(f))$$

## How are the two subjects related?

If we define  $D_{\text{DA}}(x) = 1$ , then  $D_{\text{DA}}$  is defined on  $\mathbf{Z}[x]$ , and extends to  $\mathbf{Q}(x)$  and indeed  $\overline{\mathbf{Q}(x)}$ .

If we interpret (denoted  $\mathcal{I}$ )  $\mathbf{Q}(x)$  as functions  $\mathbf{R} \rightarrow \mathbf{R}$ , then  $D_{\text{DA}}$  can be interpreted as  $D_{\epsilon\delta}$ , i.e.

$$\mathcal{I}(D_{\text{DA}}(f)) = D_{\epsilon\delta}(\mathcal{I}(f))$$

(at least up to removable singularities).

## An aside on interpretation

Consider  $L := \frac{(x-1)^2}{x^2-1}$  and  $R := \frac{x-1}{x+1}$ .

## An aside on interpretation

Consider  $L := \frac{(x-1)^2}{x^2-1}$  and  $R := \frac{x-1}{x+1}$ .

As elements of  $\mathbf{Q}(x)$  they are equal, since  $L - R = \frac{0}{x^2-1} = 0$ .



## An aside on interpretation

Consider  $L := \frac{(x-1)^2}{x^2-1}$  and  $R := \frac{x-1}{x+1}$ .

As elements of  $\mathbf{Q}(x)$  they are equal, since  $L - R = \frac{0}{x^2-1} = 0$ .

But as formulae (viewed as algorithm specifications),  $L(1)$  = “divide by zero error”, whereas  $R(1) = 0$ .

## An aside on interpretation

Consider  $L := \frac{(x-1)^2}{x^2-1}$  and  $R := \frac{x-1}{x+1}$ .

As elements of  $\mathbf{Q}(x)$  they are equal, since  $L - R = \frac{0}{x^2-1} = 0$ .

But as formulae (viewed as algorithm specifications),  $L(1)$  = “divide by zero error”, whereas  $R(1) = 0$ .

Hence the warning about removable singularities!

## An aside on interpretation

Consider  $L := \frac{(x-1)^2}{x^2-1}$  and  $R := \frac{x-1}{x+1}$ .

As elements of  $\mathbf{Q}(x)$  they are equal, since  $L - R = \frac{0}{x^2-1} = 0$ .

But as formulae (viewed as algorithm specifications),  $L(1)$  = “divide by zero error”, whereas  $R(1) = 0$ .

Hence the warning about removable singularities!

Also, note that  $-1$  is *not* a removable singularity!

## An aside on interpretation

Consider  $L := \frac{(x-1)^2}{x^2-1}$  and  $R := \frac{x-1}{x+1}$ .

As elements of  $\mathbf{Q}(x)$  they are equal, since  $L - R = \frac{0}{x^2-1} = 0$ .

But as formulae (viewed as algorithm specifications),  $L(1)$  = “divide by zero error”, whereas  $R(1) = 0$ .

Hence the warning about removable singularities!

Also, note that  $-1$  is *not* a removable singularity!

In the case of  $\mathbf{Q}(x)$ , every element has a “most continuous formula”, so interpreting this as  $\mathbf{R} \rightarrow \mathbf{R}$  can't go wrong.

## An aside on interpretation

Consider  $L := \frac{(x-1)^2}{x^2-1}$  and  $R := \frac{x-1}{x+1}$ .

As elements of  $\mathbf{Q}(x)$  they are equal, since  $L - R = \frac{0}{x^2-1} = 0$ .

But as formulae (viewed as algorithm specifications),  $L(1)$  = “divide by zero error”, whereas  $R(1) = 0$ .

Hence the warning about removable singularities!

Also, note that  $-1$  is *not* a removable singularity!

In the case of  $\mathbf{Q}(x)$ , every element has a “most continuous formula”, so interpreting this as  $\mathbf{R} \rightarrow \mathbf{R}$  can't go wrong.

We use  $\mathcal{I}^*$  to indicate “interpretation with removable singularities removed”, since there isn't always a formulaic way of doing so.

## An aside on interpretation

Consider  $L := \frac{(x-1)^2}{x^2-1}$  and  $R := \frac{x-1}{x+1}$ .

As elements of  $\mathbf{Q}(x)$  they are equal, since  $L - R = \frac{0}{x^2-1} = 0$ .

But as formulae (viewed as algorithm specifications),  $L(1) =$  “divide by zero error”, whereas  $R(1) = 0$ .

Hence the warning about removable singularities!

Also, note that  $-1$  is *not* a removable singularity!

In the case of  $\mathbf{Q}(x)$ , every element has a “most continuous formula”, so interpreting this as  $\mathbf{R} \rightarrow \mathbf{R}$  can't go wrong.

We use  $\mathcal{I}^*$  to indicate “interpretation with removable singularities removed”, since there isn't always a formulaic way of doing so.

Indeed, there may be *no* way of interpreting without singularities, as in  $z \mapsto \sqrt{z} : \mathbf{C} \rightarrow \mathbf{C}$ .

$\epsilon\delta$   $\int$  (for functions  $\mathbf{R} \rightarrow \mathbf{R}$ )

$\epsilon_\delta \int$  (for functions  $\mathbf{R} \rightarrow \mathbf{R}$ )

What is naturally defined is integration over an interval  $I$ . We let  $D$  stand for sub-divisions  $d_1 = a < d_2 < \cdots < d_n = b$  of  $I = [a, b]$ , and  $|D|$  for the largest distance between neighbouring points in  $D$ , i.e.  $\max_i(d_{i+1} - d_i)$ .



## $\epsilon\delta$ $\int$ (for functions $\mathbf{R} \rightarrow \mathbf{R}$ )

What is naturally defined is integration over an interval  $I$ . We let  $D$  stand for sub-divisions  $d_1 = a < d_2 < \dots < d_n = b$  of  $I = [a, b]$ , and  $|D|$  for the largest distance between neighbouring points in  $D$ , i.e.  $\max_i(d_{i+1} - d_i)$ . Let

- $\overline{S}_D = \sum_i (d_{i+1} - d_i) \max_{d_{i+1} \geq x \geq d_i} f(x)$ ;

## $\epsilon\delta$ $\int$ (for functions $\mathbf{R} \rightarrow \mathbf{R}$ )

What is naturally defined is integration over an interval  $I$ . We let  $D$  stand for sub-divisions  $d_1 = a < d_2 < \dots < d_n = b$  of  $I = [a, b]$ , and  $|D|$  for the largest distance between neighbouring points in  $D$ , i.e.  $\max_i(d_{i+1} - d_i)$ . Let

- $\overline{S}_D = \sum_i (d_{i+1} - d_i) \max_{d_{i+1} \geq x \geq d_i} f(x)$ ;
- $\underline{S}_D = \sum_i (d_{i+1} - d_i) \min_{d_{i+1} \geq x \geq d_i} f(x)$ ;

## $\epsilon\delta$ $\int$ (for functions $\mathbf{R} \rightarrow \mathbf{R}$ )

What is naturally defined is integration over an interval  $I$ . We let  $D$  stand for sub-divisions  $d_1 = a < d_2 < \dots < d_n = b$  of  $I = [a, b]$ , and  $|D|$  for the largest distance between neighbouring points in  $D$ , i.e.  $\max_i(d_{i+1} - d_i)$ . Let

- $\overline{S}_D = \sum_i (d_{i+1} - d_i) \max_{d_{i+1} \geq x \geq d_i} f(x)$ ;
- $\underline{S}_D = \sum_i (d_{i+1} - d_i) \min_{d_{i+1} \geq x \geq d_i} f(x)$ ;

**Then**  $\epsilon\delta \int_I f = \liminf_{|D| \rightarrow 0} \overline{S}_D = \limsup_{|D| \rightarrow 0} \underline{S}_D$  if both exist and are equal.

## Consequences: Fundamental Theorem of Calculus ( $\text{FTC}_{\epsilon\delta}$ )

$$\text{Define } {}_{\epsilon\delta}\int_a^b f = \begin{cases} \epsilon\delta \int_{[a,b]} f & a \leq b \\ -\epsilon\delta \int_{[b,a]} f & a > b \end{cases}$$

## Consequences: Fundamental Theorem of Calculus ( $\text{FTC}_{\epsilon\delta}$ )

$$\text{Define } \epsilon\delta \int_a^b f = \begin{cases} \epsilon\delta \int_{[a,b]} f & a \leq b \\ -\epsilon\delta \int_{[b,a]} f & a > b \end{cases}$$

(If we're not careful, we wind up saying "[2,1] is the same set as [1,2] except that if you integrate over it you have to add a – sign". What we really have here is the beginnings of contour integration.

## Consequences: Fundamental Theorem of Calculus ( $\text{FTC}_{\epsilon\delta}$ )

$$\text{Define } \int_a^b f = \begin{cases} \int_a^b f & a \leq b \\ -\int_b^a f & a > b \end{cases}$$

(If we're not careful, we wind up saying "[2,1] is the same set as [1,2] except that if you integrate over it you have to add a – sign". What we really have here is the beginnings of contour integration. Apostol theorem 1.20 states that if  $g(x) \leq f(x)$  for every  $x$  in  $[a, b]$ , then

$$\int_a^b g(x) dx \leq \int_a^b f(x) dx,$$

and here  $a < b$  is implicit.)

## Consequences: Fundamental Theorem of Calculus ( $\text{FTC}_{\epsilon\delta}$ )

$$\text{Define } \epsilon\delta \int_a^b f = \begin{cases} \epsilon\delta \int_{[a,b]} f & a \leq b \\ -\epsilon\delta \int_{[b,a]} f & a > b \end{cases}$$

(If we're not careful, we wind up saying "[2,1] is the same set as [1,2] except that if you integrate over it you have to add a – sign". What we really have here is the beginnings of contour integration. Apostol theorem 1.20 states that if  $g(x) \leq f(x)$  for every  $x$  in  $[a, b]$ , then

$$\int_a^b g(x)dx \leq \int_a^b f(x)dx,$$

and here  $a < b$  is implicit.)

$$\text{FTC}_{\epsilon\delta}: \epsilon\delta \int_{[a,b]} D_{\epsilon\delta} f = f(b) - f(a).$$

## Consequences: Fundamental Theorem of Calculus ( $\text{FTC}_{\epsilon\delta}$ )

$$\text{Define } \epsilon\delta \int_a^b f = \begin{cases} \epsilon\delta \int_{[a,b]} f & a \leq b \\ -\epsilon\delta \int_{[b,a]} f & a > b \end{cases}$$

(If we're not careful, we wind up saying "[2,1] is the same set as [1,2] except that if you integrate over it you have to add a - sign". What we really have here is the beginnings of contour integration. Apostol theorem 1.20 states that if  $g(x) \leq f(x)$  for every  $x$  in  $[a, b]$ , then

$$\int_a^b g(x) dx \leq \int_a^b f(x) dx,$$

and here  $a < b$  is implicit.)

$$\text{FTC}_{\epsilon\delta}: \epsilon\delta \int_{[a,b]} D_{\epsilon\delta} f = f(b) - f(a).$$

Or:  $D_{\epsilon\delta}(\lambda x \cdot \epsilon\delta \int_a^x f) = f$  (if the  $\epsilon\delta \int$  exists).



## Consequences: Fundamental Theorem of Calculus (FTC <sub>$\epsilon\delta$</sub> )

$$\text{Define } \epsilon\delta \int_a^b f = \begin{cases} \epsilon\delta \int_{[a,b]} f & a \leq b \\ -\epsilon\delta \int_{[b,a]} f & a > b \end{cases}$$

(If we're not careful, we wind up saying "[2,1] is the same set as [1,2] except that if you integrate over it you have to add a - sign". What we really have here is the beginnings of contour integration. Apostol theorem 1.20 states that if  $g(x) \leq f(x)$  for every  $x$  in  $[a, b]$ , then

$$\int_a^b g(x)dx \leq \int_a^b f(x)dx,$$

and here  $a < b$  is implicit.)

$$\text{FTC}_{\epsilon\delta}: \epsilon\delta \int_{[a,b]} D_{\epsilon\delta} f = f(b) - f(a).$$

Or:  $D_{\epsilon\delta}(\lambda x \cdot \epsilon\delta \int_a^x f) = f$  (if the  $\epsilon\delta \int$  exists).

(Of course, this is normally stated without the  $\lambda$ .)

$\text{DA } \int$ : FTC becomes a definition

## ${}_{DA}\int$ : FTC becomes a definition

FTC<sub>DA</sub>: **define**  ${}_{DA}\int f$  to be *any*  $g$  such that  $f = D_{DA}g$ .

## ${}_{DA}\int$ : FTC becomes a definition

FTC<sub>DA</sub>: **define**  ${}_{DA}\int f$  to be *any*  $g$  such that  $f = D_{DA}g$ .  
If  $g$  and  $h$  are two such integrals, then  $D_{DA}(g - h) = 0$ , i.e. “ $g$  and  $h$  differ by a constant”.

## $_{DA} \int$ : FTC becomes a definition

FTC $_{DA}$ : **define**  $_{DA} \int f$  to be *any*  $g$  such that  $f = D_{DA}g$ .

If  $g$  and  $h$  are two such integrals, then  $D_{DA}(g - h) = 0$ , i.e. “ $g$  and  $h$  differ by a constant”.

One difficulty is that this is really a “constant $_{DA}$ ” (something whose  $D_{DA}$  is zero), and, for example, a Heaviside function is a constant $_{DA}$ , though not a constant in the usual sense.

Will the real FTC please stand up?

Will the real FTC please stand up?

FTC (as it *should* be taught).

## Will the real FTC please stand up?

FTC (as it *should* be taught).

If  $g = {}_{\text{DA}} \int f$ , and  $\mathcal{I}(g)$  is continuous on  $[a, b]$ , then

$$\epsilon\delta \int_a^b \mathcal{I}(f) = \mathcal{I}(g)(b) - \mathcal{I}(g)(a).$$



## Will the real FTC please stand up?

FTC (as it *should* be taught).

If  $g = {}_{\text{DA}} \int f$ , and  $\mathcal{I}(g)$  is continuous on  $[a, b]$ , then

$$\epsilon\delta \int_a^b \mathcal{I}(f) = \mathcal{I}(g)(b) - \mathcal{I}(g)(a).$$

Note the caveat on continuity:  $g : x \mapsto \arctan\left(\frac{1}{x}\right)$  is discontinuous at  $x = 0$  ( $\lim_{x \rightarrow 0^-} \arctan\left(\frac{1}{x}\right) = \frac{-\pi}{2}$  whereas  $\lim_{x \rightarrow 0^+} \arctan\left(\frac{1}{x}\right) = \frac{\pi}{2}$ ),

## Will the real FTC please stand up?

FTC (as it *should* be taught).

If  $g = \text{DA} \int f$ , and  $\mathcal{I}(g)$  is continuous on  $[a, b]$ , then

$$\epsilon_\delta \int_a^b \mathcal{I}(f) = \mathcal{I}(g)(b) - \mathcal{I}(g)(a).$$

Note the caveat on continuity:  $g : x \mapsto \arctan\left(\frac{1}{x}\right)$  is discontinuous at  $x = 0$  ( $\lim_{x \rightarrow 0^-} \arctan\left(\frac{1}{x}\right) = \frac{-\pi}{2}$  whereas  $\lim_{x \rightarrow 0^+} \arctan\left(\frac{1}{x}\right) = \frac{\pi}{2}$ ), which accounts for the invalidity of deducing that the integral of a negative function is positive —

$$\int_{-1}^1 \frac{-1}{x^2 + 1} = \mathcal{I}(g)(1) - \mathcal{I}(g)(-1) = \frac{\pi}{4} - \frac{-\pi}{4} = \frac{\pi}{2} > 0.$$

## Rescuing the Fundamental Theorem of Calculus

Of course, another  $\text{DA} \int \frac{-1}{x^2+1}$  is  $h(x) = \arctan\left(\frac{1}{x}\right) + H(x)$  where

$H(x) = \begin{cases} 0 & x < 0 \\ -\pi & x > 0 \end{cases}$  is a constant $_{\text{DA}}$ . This has a removable singularity at  $x = 0$ .

## Rescuing the Fundamental Theorem of Calculus

Of course, another  $\text{DA} \int \frac{-1}{x^2+1}$  is  $h(x) = \arctan\left(\frac{1}{x}\right) + H(x)$  where

$H(x) = \begin{cases} 0 & x < 0 \\ -\pi & x > 0 \end{cases}$  is a constant $_{\text{DA}}$ . This has a removable singularity at  $x = 0$ .

$\mathcal{I}^*(h)$  is continuous, so FTC is appropriate and

$$\int_{-1}^1 \frac{-1}{x^2+1} = \mathcal{I}(h)(1) - \mathcal{I}(h)(-1) = \left(\frac{\pi}{4} - \pi\right) - \frac{-\pi}{4} = -\frac{\pi}{2} < 0.$$

## “Most continuous expressions” revisited

$\arctan\left(\frac{1}{x}\right) + H(x)$  can also be rewritten as  $\frac{\pi}{2} - \arctan(x)$ .

## “Most continuous expressions” revisited

$\arctan\left(\frac{1}{x}\right) + H(x)$  can also be rewritten as  $\frac{\pi}{2} - \arctan(x)$ .  
*In this case*  $\frac{\pi}{2} - \arctan(x)$  is a “most continuous formula”.

## “Most continuous expressions” revisited

$\arctan\left(\frac{1}{x}\right) + H(x)$  can also be rewritten as  $\frac{\pi}{2} - \arctan(x)$ .  
*In this case*  $\frac{\pi}{2} - \arctan(x)$  is a “most continuous formula”.  
(except at  $\infty$ , where the original  $\arctan\left(\frac{1}{x}\right)$  is continuous!).

## “Most continuous expressions” revisited

$\arctan\left(\frac{1}{x}\right) + H(x)$  can also be rewritten as  $\frac{\pi}{2} - \arctan(x)$ .  
*In this case*  $\frac{\pi}{2} - \arctan(x)$  is a “most continuous formula”.  
(except at  $\infty$ , where the original  $\arctan\left(\frac{1}{x}\right)$  is continuous!).  
What about  $\arctan\left(\frac{z-1}{z+1}\right)$ ?



## “Most continuous expressions” revisited

$\arctan\left(\frac{1}{x}\right) + H(x)$  can also be rewritten as  $\frac{\pi}{2} - \arctan(x)$ .  
*In this case*  $\frac{\pi}{2} - \arctan(x)$  is a “most continuous formula”.  
(except at  $\infty$ , where the original  $\arctan\left(\frac{1}{x}\right)$  is continuous!).  
What about  $\arctan\left(\frac{z-1}{z+1}\right)$ ? An equivalent is

$$\arctan\left(\frac{z-1+\sqrt{z^2+6z-7}}{2(z-1)}\right) - \arctan\left(\frac{z-1+\sqrt{z^2+6z-7}}{2(z-1)} + 1\right)$$

## “Most continuous expressions” revisited

$\arctan\left(\frac{1}{x}\right) + H(x)$  can also be rewritten as  $\frac{\pi}{2} - \arctan(x)$ .  
*In this case*  $\frac{\pi}{2} - \arctan(x)$  is a “most continuous formula”.  
(except at  $\infty$ , where the original  $\arctan\left(\frac{1}{x}\right)$  is continuous!).

What about  $\arctan\left(\frac{z-1}{z+1}\right)$ ? An equivalent is

$$\arctan\left(\frac{z-1+\sqrt{z^2+6z-7}}{2(z-1)}\right) - \arctan\left(\frac{z-1+\sqrt{z^2+6z-7}}{2(z-1)} + 1\right)$$

or  $-\arctan\left(\frac{2z-1+z^2}{-2z-1+z^2}\right) - \arctan(z)$ , where the singularities are at  $-1 \pm \sqrt{2}$  (and  $\infty$ ), or ....

## “Most continuous expressions” revisited

$\arctan\left(\frac{1}{x}\right) + H(x)$  can also be rewritten as  $\frac{\pi}{2} - \arctan(x)$ .  
*In this case*  $\frac{\pi}{2} - \arctan(x)$  is a “most continuous formula”.  
(except at  $\infty$ , where the original  $\arctan\left(\frac{1}{x}\right)$  is continuous!).

What about  $\arctan\left(\frac{z-1}{z+1}\right)$ ? An equivalent is

$$\arctan\left(\frac{z-1+\sqrt{z^2+6z-7}}{2(z-1)}\right) - \arctan\left(\frac{z-1+\sqrt{z^2+6z-7}}{2(z-1)} + 1\right)$$

or  $-\arctan\left(\frac{2z-1+z^2}{-2z-1+z^2}\right) - \arctan(z)$ , where the singularities are at  $-1 \pm \sqrt{2}$  (and  $\infty$ ), or . . . .

Still an unsolved problem (Rioboo, . . .).

But I'm not interested in all this DA stuff

## But I'm not interested in all this DA stuff

- Surely most people (even engineers) do  $\epsilon\delta \int$  etc.

## But I'm not interested in all this DA stuff

- Surely most people (even engineers) do  $\epsilon\delta \int$  etc.
- They may *think* they do, but in practice they *do*  $DA \int$  even when intending to do  $\epsilon\delta \int$ .

## But I'm not interested in all this DA stuff

- Surely most people (even engineers) do  $\epsilon\delta \int$  etc.
- They may *think* they do, but in practice they *do*  $_{DA} \int$  even when intending to do  $\epsilon\delta \int$ .
- What is  $\lim_{h \rightarrow 0} \frac{1}{h} ((1+h) \cos^2(1+h) - \cos^2 1)$ ?

## But I'm not interested in all this DA stuff

- Surely most people (even engineers) do  $\epsilon\delta \int$  etc.
- They may *think* they do, but in practice they *do*  $_{DA} \int$  even when intending to do  $\epsilon\delta \int$ .
- What is  $\lim_{h \rightarrow 0} \frac{1}{h} ((1+h) \cos^2(1+h) - \cos^2 1)$ ?
- If you immediately said  $\cos^2(1) - 2 \sin(1) \cos(1)$



## But I'm not interested in all this DA stuff

- Surely most people (even engineers) do  $\epsilon\delta \int$  etc.
- They may *think* they do, but in practice they *do*  $D_{DA} \int$  even when intending to do  $\epsilon\delta \int$ .
- What is  $\lim_{h \rightarrow 0} \frac{1}{h} ((1+h) \cos^2(1+h) - \cos^2 1)$ ?
- If you immediately said  $\cos^2(1) - 2 \sin(1) \cos(1)$
- I bet you *actually* did  $D_{DA}(x \cos^2 x)|_{x=1}$ .

## But I'm not interested in all this DA stuff

- Surely most people (even engineers) do  $\epsilon\delta \int$  etc.
- They may *think* they do, but in practice they *do*  $D_{DA} \int$  even when intending to do  $\epsilon\delta \int$ .
- What is  $\lim_{h \rightarrow 0} \frac{1}{h} ((1+h) \cos^2(1+h) - \cos^2 1)$ ?
- If you immediately said  $\cos^2(1) - 2 \sin(1) \cos(1)$
- I bet you *actually* did  $D_{DA}(x \cos^2 x)|_{x=1}$ .
- (If you said  $-.617370845$ , you probably had Maple on your Blackberry, and *it* did that.)

## Conclusions

# Conclusions

- We already know that  $\epsilon\delta \int$  is a powerful world model

# Conclusions

- We already know that  ${}_{\epsilon\delta}f$  is a powerful world model
- ${}_{DA}f$  is well-implemented and very powerful

# Conclusions

- We already know that  $\epsilon\delta \int$  is a powerful world model
- ${}_{DA} \int$  is well-implemented and very powerful
- “ $e^{-x^2}$  has no integral” means “has no  ${}_{DA} \int$  in terms of already known functions”

# Conclusions

- We already know that  ${}_{\epsilon\delta} \int$  is a powerful world model
- ${}_{DA} \int$  is well-implemented and very powerful
- “ $e^{-x^2}$  has no integral” means “has no  ${}_{DA} \int$  in terms of already known functions”
- $\mathcal{I}$  does map from one to the other, often very effectively

# Conclusions

- We already know that  ${}_{\epsilon\delta}\int$  is a powerful world model
- ${}_{DA}\int$  is well-implemented and very powerful
- “ $e^{-x^2}$  has no integral” means “has no  ${}_{DA}\int$  in terms of already known functions”
- $\mathcal{I}$  does map from one to the other, often very effectively
- but not always!



$\mathcal{I}$  crops up elsewhere

$\mathcal{I}$  crops up elsewhere

Claim  $\sqrt{1 - z^2} = \sqrt{1 - z}\sqrt{1 + z}$ .

## $\mathcal{I}$ crops up elsewhere

Claim  $\sqrt{1 - z^2} = \sqrt{1 - z}\sqrt{1 + z}$ .

Squaring both sides gives  $1 - z^2 = (1 - z)(1 + z)$ , so there is *some* interpretation in which it is true.

## $\mathcal{I}$ crops up elsewhere

Claim  $\sqrt{1 - z^2} = \sqrt{1 - z}\sqrt{1 + z}$ .

Squaring both sides gives  $1 - z^2 = (1 - z)(1 + z)$ , so there is *some* interpretation in which it is true.

What about  $\sqrt{z^2 - 1} \stackrel{?}{=} \sqrt{z - 1}\sqrt{z + 1}$ .

## $\mathcal{I}$ crops up elsewhere

Claim  $\sqrt{1 - z^2} = \sqrt{1 - z}\sqrt{1 + z}$ .

Squaring both sides gives  $1 - z^2 = (1 - z)(1 + z)$ , so there is *some* interpretation in which it is true.

What about  $\sqrt{z^2 - 1} \stackrel{?}{=} \sqrt{z - 1}\sqrt{z + 1}$ .

The same arguments apply and there is *some* interpretation of  $\sqrt{z^2 - 1}$ ,  $\sqrt{z - 1}$  and  $\sqrt{z + 1}$  in which it is true, *but*

## $\mathcal{I}$ crops up elsewhere

Claim  $\sqrt{1 - z^2} = \sqrt{1 - z}\sqrt{1 + z}$ .

Squaring both sides gives  $1 - z^2 = (1 - z)(1 + z)$ , so there is *some* interpretation in which it is true.

What about  $\sqrt{z^2 - 1} \stackrel{?}{=} \sqrt{z - 1}\sqrt{z + 1}$ .

The same arguments apply and there is *some* interpretation of  $\sqrt{z^2 - 1}$ ,  $\sqrt{z - 1}$  and  $\sqrt{z + 1}$  in which it is true, *but* when  $z = -2$  we get  $\sqrt{3} = \sqrt{-3}\sqrt{-1}$ , so there is *no* interpretation of  $\sqrt{\quad}$  as such, consistent with  $\sqrt{-n} = \sqrt{-1}\sqrt{n}$  even for  $n \in \mathbf{N}$ , for which it is true.

## $\mathcal{I}$ crops up elsewhere

Claim  $\sqrt{1 - z^2} = \sqrt{1 - z}\sqrt{1 + z}$ .

Squaring both sides gives  $1 - z^2 = (1 - z)(1 + z)$ , so there is *some* interpretation in which it is true.

What about  $\sqrt{z^2 - 1} \stackrel{?}{=} \sqrt{z - 1}\sqrt{z + 1}$ .

The same arguments apply and there is *some* interpretation of  $\sqrt{z^2 - 1}$ ,  $\sqrt{z - 1}$  and  $\sqrt{z + 1}$  in which it is true, *but* when  $z = -2$  we get  $\sqrt{3} = \sqrt{-3}\sqrt{-1}$ , so there is *no* interpretation of  $\sqrt{\quad}$  as such, consistent with  $\sqrt{-n} = \sqrt{-1}\sqrt{n}$  even for  $n \in \mathbf{N}$ , for which it is true.

There is *no* interpretation of  $\sqrt{\quad}$  as such for which both are true.

## $\mathcal{I}$ crops up elsewhere

Claim  $\sqrt{1 - z^2} = \sqrt{1 - z}\sqrt{1 + z}$ .

Squaring both sides gives  $1 - z^2 = (1 - z)(1 + z)$ , so there is *some* interpretation in which it is true.

What about  $\sqrt{z^2 - 1} \stackrel{?}{=} \sqrt{z - 1}\sqrt{z + 1}$ .

The same arguments apply and there is *some* interpretation of  $\sqrt{z^2 - 1}$ ,  $\sqrt{z - 1}$  and  $\sqrt{z + 1}$  in which it is true, *but* when  $z = -2$  we get  $\sqrt{3} = \sqrt{-3}\sqrt{-1}$ , so there is *no* interpretation of  $\sqrt{\quad}$  as such, consistent with  $\sqrt{-n} = \sqrt{-1}\sqrt{n}$  even for  $n \in \mathbf{N}$ , for which it is true.

There is *no* interpretation of  $\sqrt{\quad}$  as such for which both are true.  $\mathcal{I}$  interprets individual functions, such as  $\sqrt{1 + z}$ , and there is no general composition.