

# On surface cluster algebras: Snake graph calculus and dreading torus

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joint work with Ralf Schiffler

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# Outline of Topics

- 1 Surface cluster algebras
- 2 Abstract Snake Graphs
- 3 Relation to Cluster Algebras
- 4 Self-crossing snake graphs
- 5 Application

# Overview

- Cluster algebras were introduced by **Fomin and Zelevinsky** [FZ1] with the desire of creating an algebraic framework for the study of (dual) canonical bases in Lie theory.
- Cluster algebras are defined by **generators** and **relations**, and the set of generators is constructed recursively from some **initial data**  $(\mathbf{x}, Q)$  called **seed**, where  $\mathbf{x} = (x_1, \dots, x_n)$  and  $Q$  is a quiver.
- Cluster algebras form a class of combinatorially defined commutative algebras, and the set of generators of a cluster algebra, **cluster variables**, is obtained by an iterative process called **seed mutation**.
- The cluster variables are **rational functions in several variables**  $x_1, x_2, \dots, x_n$  by construction.
- However, by a well-known result in [FZ1] they can be expressed as **Laurent polynomials** in  $x_1, x_2, \dots, x_n$  with integer coefficients.

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- The authors in [MSW] associate a connected graph, called the **snake graph** to each arc in the surface to obtain a direct formula, the **expansion formula**, for cluster variables of surface cluster algebras.

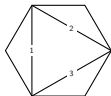
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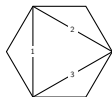


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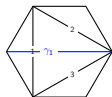


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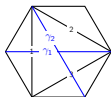


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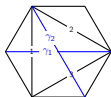


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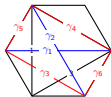


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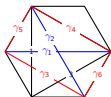
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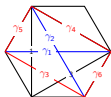
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# Motivation

Let  $\mathcal{A}(S, M)$  cluster algebra associated to a surface  $(S, M)$ .

We have the following situation:

## Question

*"How much can we recover from snake graphs themselves?"*

In particular,

- Given a cluster algebra, how can we recover the surface from the snake graphs?
- What are the snake graphs corresponding to the dual quiver?

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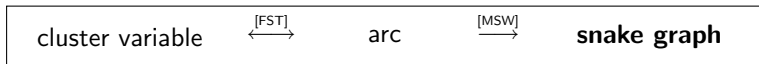
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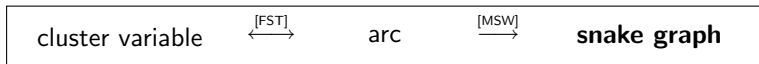
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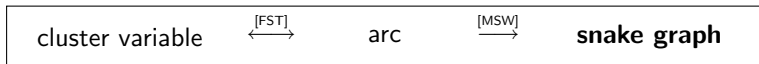
• When do the two arcs corresponding to two snake graphs cross?

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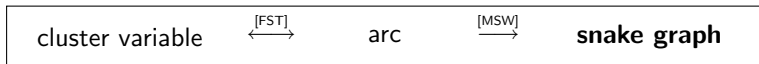
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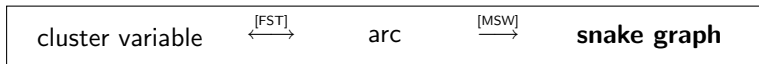
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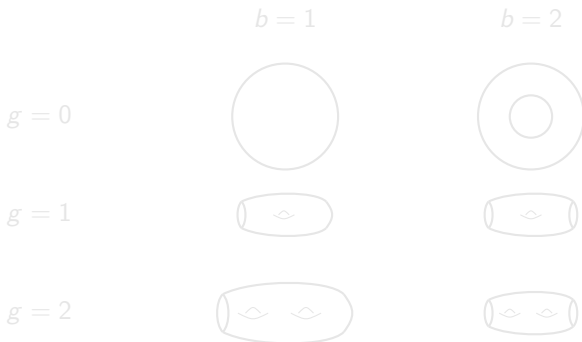
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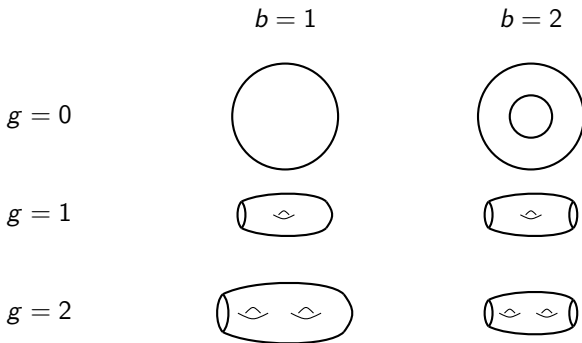
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- Let  $S$  be a connected oriented 2-dimensional Riemann surface with nonempty boundary, and let  $M$  be a nonempty finite subset of the boundary of  $S$ , such that each boundary component of  $S$  contains at least one point of  $M$ . The elements of  $M$  are called *marked points*. The pair  $(S, M)$  is called a **bordered surface with marked points**.



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Curves that connect two marked points and lie entirely on the boundary of  $S$  without passing through a third marked point are *boundary segments*. Note that **boundary segments are not arcs**.

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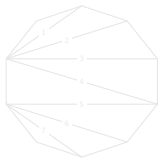
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For any two arcs  $\gamma, \gamma'$  in  $S$ , let  $e(\gamma, \gamma')$  be the **minimal number of crossings** of arcs  $\alpha$  and  $\alpha'$ , where  $\alpha$  and  $\alpha'$  range over all arcs isotopic to  $\gamma$  and  $\gamma'$ , respectively. We say that arcs  $\gamma$  and  $\gamma'$  are **compatible** if  $e(\gamma, \gamma') = 0$ .

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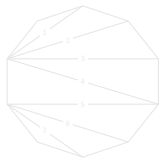
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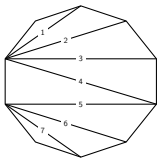
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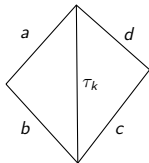
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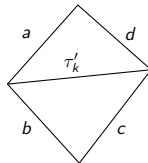
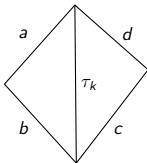
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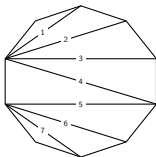
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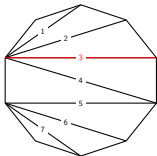
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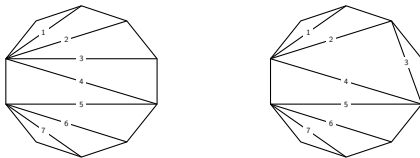
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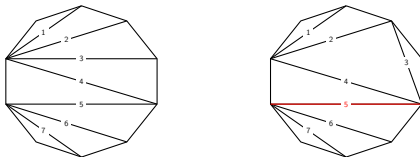
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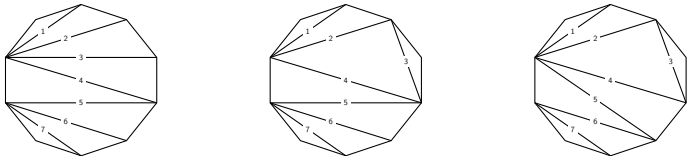
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# Surface Cluster Algebras

## Theorem (FST, FT)

For cluster algebras from surfaces

- there are bijections

$$\begin{aligned} \{ \text{arcs} \} &\longrightarrow \{ \text{cluster variables} \} \\ \gamma &\longmapsto x_\gamma \end{aligned}$$

$$\begin{aligned} \{ \text{triangulations} \} &\longrightarrow \{ \text{clusters} \} \\ T = \{ \tau_1, \dots, \tau_n \} &\longmapsto \mathbf{x}_T = \{ x_{\tau_1}, \dots, x_{\tau_n} \} \end{aligned}$$

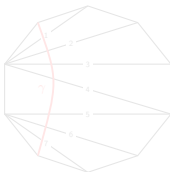
- The triangulation  $T \setminus \{ \tau_k \} \cup \{ \tau'_k \}$  obtained by flipping the arc  $\tau_k$  corresponds to the mutation  $\mu_k(\mathbf{x}_T) = \mathbf{x}_T \setminus \{ x_{\tau_k} \} \cup \{ x_{\tau'_k} \}$ .

## Definition

The **surface cluster algebra**  $\mathcal{A} = \mathcal{A}(S, M)$  associated to a surface  $(S, M)$  is a  $\mathbb{Z}$ -subalgebra of  $\mathbb{Q}(x_1, \dots, x_n)$  generated by all cluster variables  $x_\gamma$ .

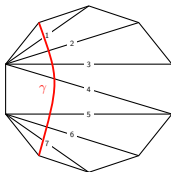
# Snake graphs and perfect matchings

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# Snake graphs and perfect matchings

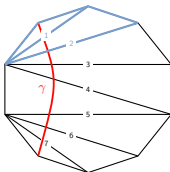
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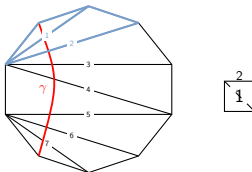
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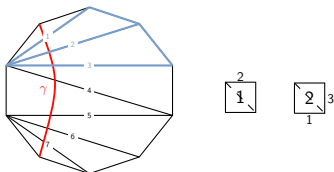
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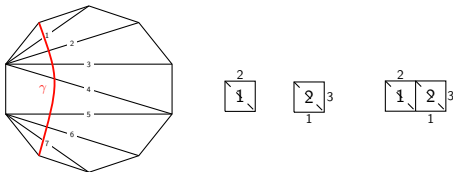
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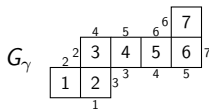
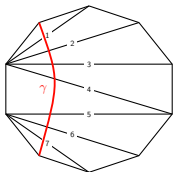
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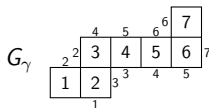
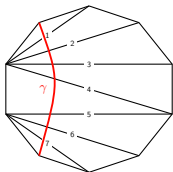


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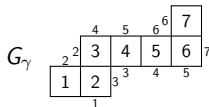
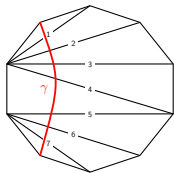
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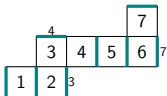
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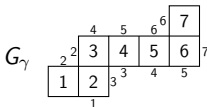
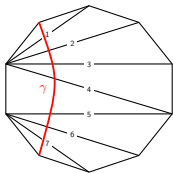


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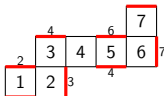
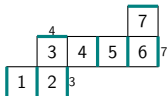


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## Expansion formula

The authors in [MSW] gives an explicit formula, called **expansion formula**, for cluster variables. The formula is given by

$$x_\gamma = \frac{1}{\text{cross}(\gamma, T)} \sum_{P \vdash G_\gamma} x(P)y(P)$$

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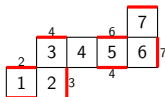
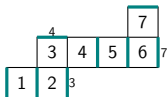


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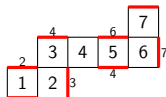
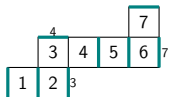


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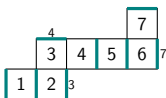
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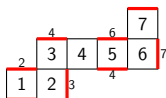
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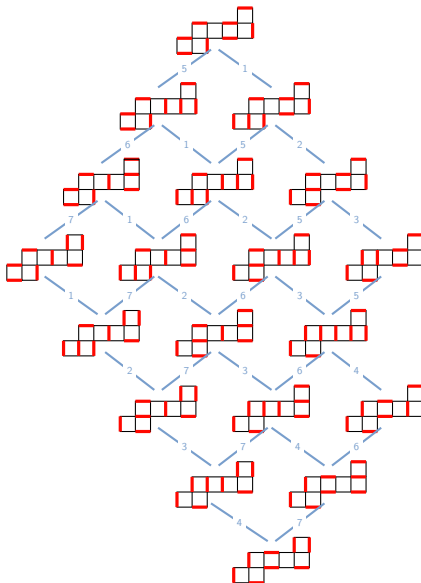
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$$x(P) = x_3 x_4 x_7$$



$$x(P) = x_2 x_3 x_4^2 x_6 x_7$$





Applying the formula, the cluster variable corresponding to the arc  $\gamma$  is given by

$$\begin{aligned}
 x_\gamma = & \frac{1}{x_1 x_2 x_3 x_4 x_5 x_6 x_7} (x_1 x_2 x_3 x_5^2 x_6 + y_4 x_1 x_2 x_5 x_6 + y_7 x_1 x_2 x_3 x_5^2 + \\
 & y_3 y_4 x_1 x_4 x_5 x_6 + y_4 y_7 x_1 x_2 x_5 + y_6 y_7 x_1 x_2 x_3 x_5 x_7 + \\
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 & y_4 y_5 y_6 y_7 x_1 x_2 x_4 x_6 x_7 + y_1 y_2 y_3 y_4 y_7 x_2 x_3 x_4 x_5 + y_2 y_3 y_4 y_6 y_7 x_3 x_4 x_7 + \\
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 \end{aligned}$$

## Our results

- We introduce the notion of an **abstract snake graph**, which is not necessarily related to an arc in a surface.
- We define what it means for two abstract **snake graphs to cross**.
- Given two crossing snake graphs, we construct the **resolution** of the crossing as two pairs of snake graphs from the original pair of crossing snake graphs.
- We then prove that there is a **bijection**  $\varphi$  between the set of perfect matchings of the two crossing snake graphs and the set of perfect matchings of the resolution.
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# Abstract Snake Graphs

## Definition

A **snake graph**  $\mathcal{G}$  is a connected graph in  $\mathbb{R}^2$  consisting of a finite sequence of tiles  $G_1, G_2, \dots, G_d$  with  $d \geq 1$ , such that for each  $i = 1, \dots, d - 1$

- (i)  $G_i$  and  $G_{i+1}$  share exactly one edge  $e_i$  and this edge is either the north edge of  $G_i$  and the south edge of  $G_{i+1}$  or the east edge of  $G_i$  and the west edge of  $G_{i+1}$ .
- (ii)  $G_i$  and  $G_j$  have no edge in common whenever  $|i - j| \geq 2$ .
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## Example



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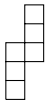
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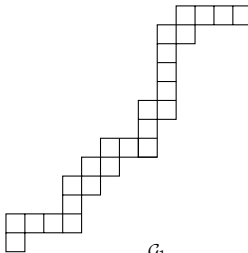


$\mathcal{G}$

# Example



$\mathcal{G}$



$\mathcal{G}_1$

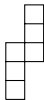
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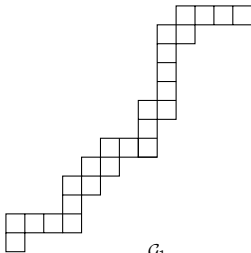
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• The number  $d$  is the number of squares between  $G_1$  and  $G_d$ .

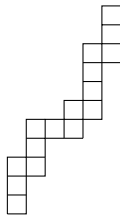
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$\mathcal{G}$



$\mathcal{G}_1$



$\mathcal{G}_2$

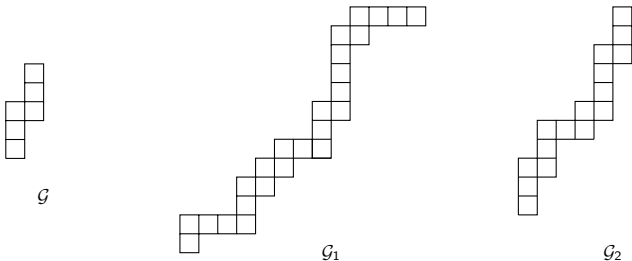
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- $\mathcal{G} = (\mathcal{G}_1, \mathcal{G}_2, \dots, \mathcal{G}_d)$

- $\mathcal{G}[i, i+t] = (\mathcal{G}_i, \mathcal{G}_{i+1}, \dots, \mathcal{G}_{i+t})$

• The length of  $\mathcal{G}$  is the number of squares between the first and last squares.

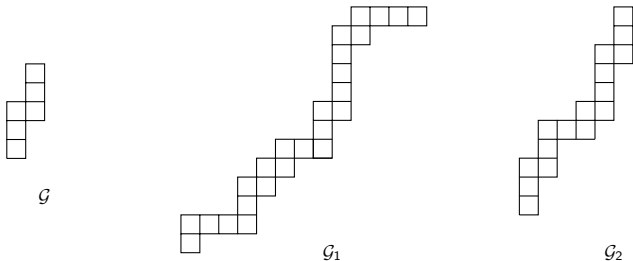
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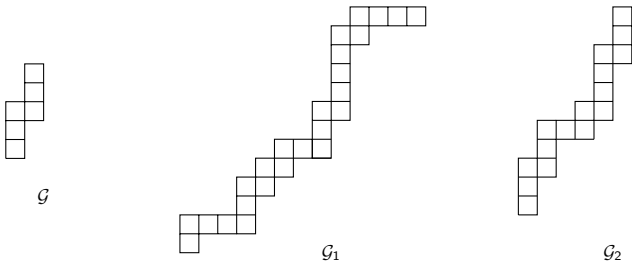
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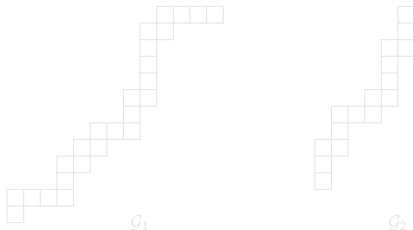
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## Definition

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## Example



Therefore  $\mathcal{G}$  is a local overlap of  $\mathcal{G}_1$  and  $\mathcal{G}_2$ .

Abstract Snake Graphs and their Relation to Cluster Algebras

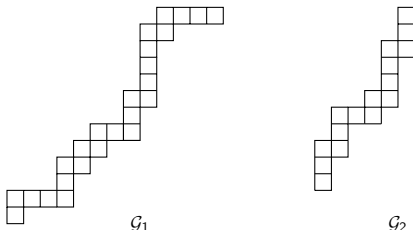
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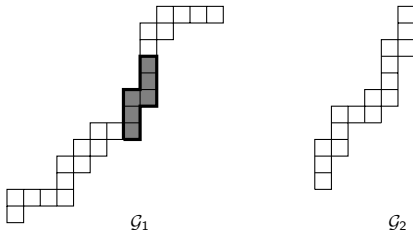
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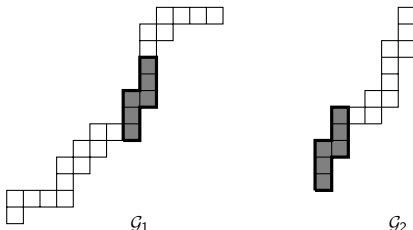
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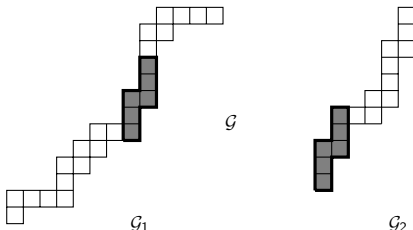
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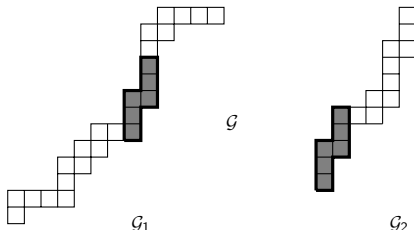
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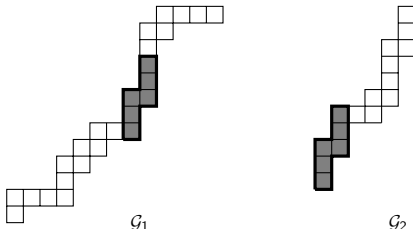
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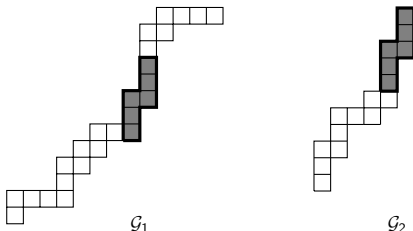
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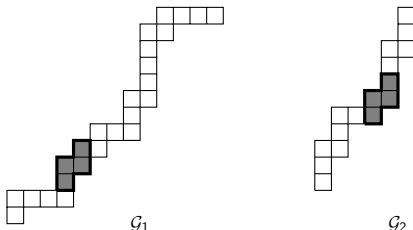
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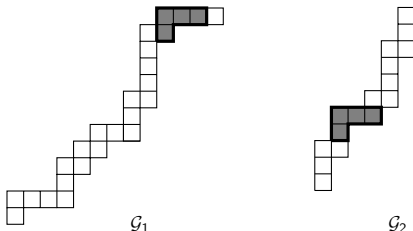
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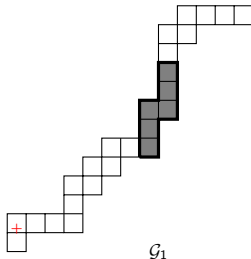
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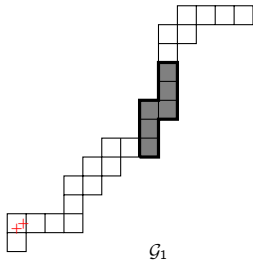
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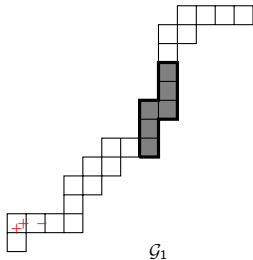
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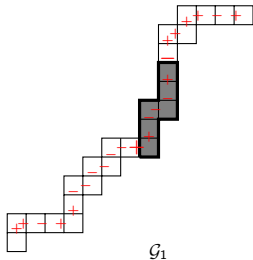
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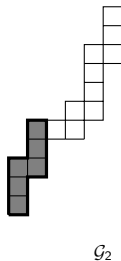
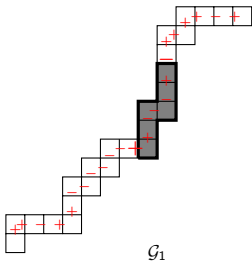
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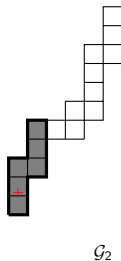
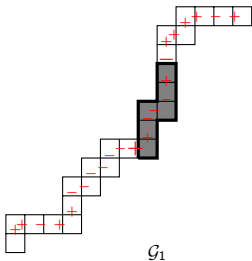
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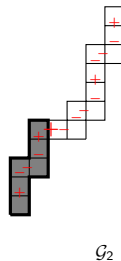
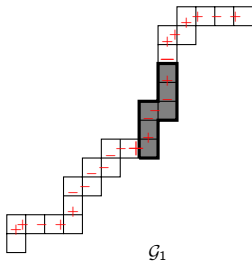
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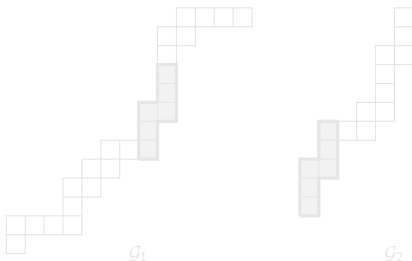
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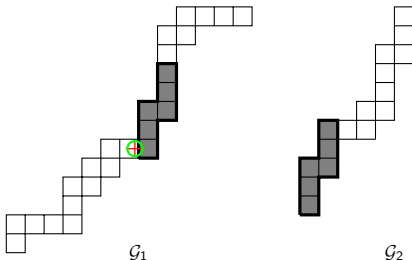
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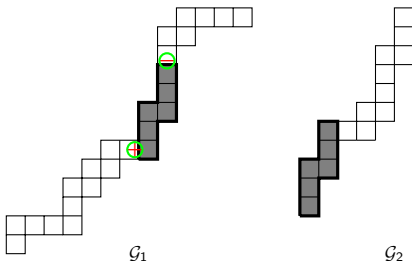
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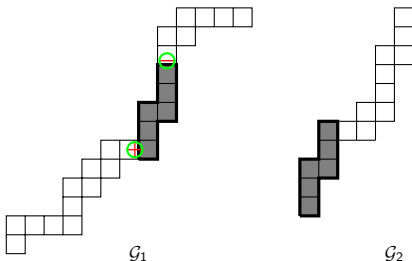
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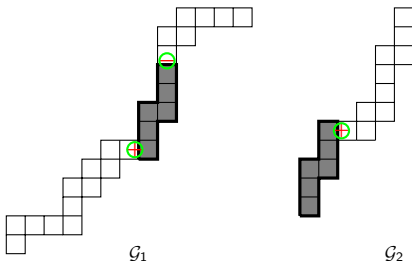
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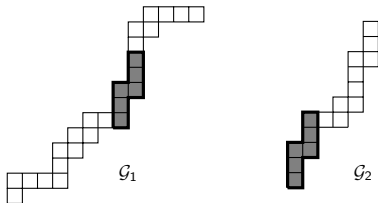
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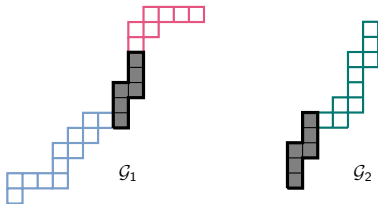
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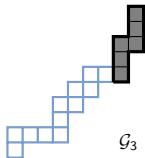
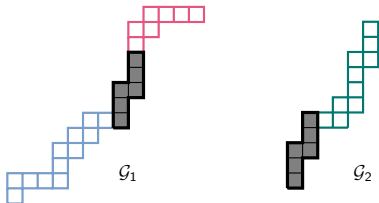
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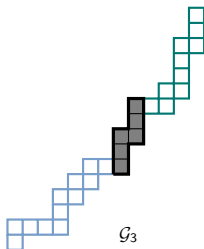
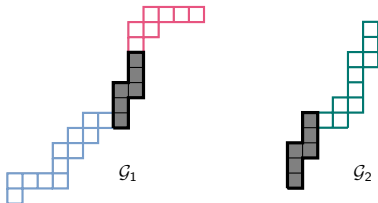


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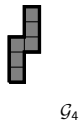
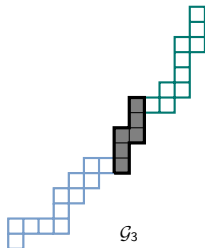
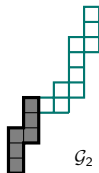
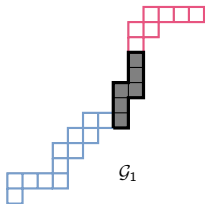




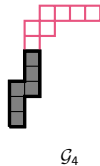
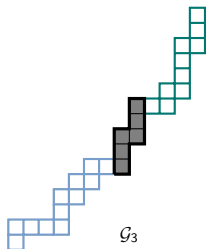
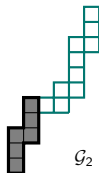
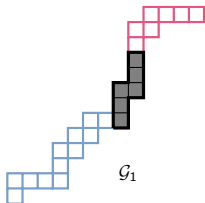
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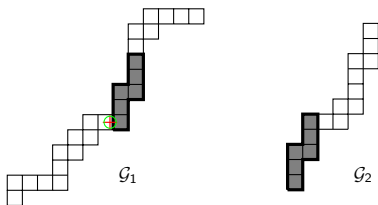
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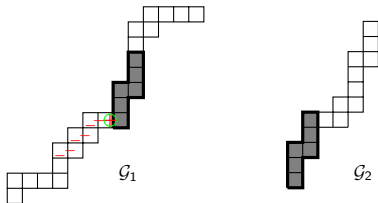
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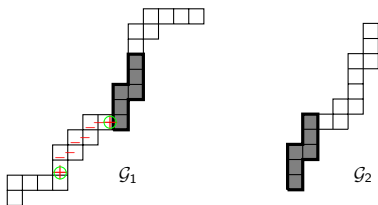
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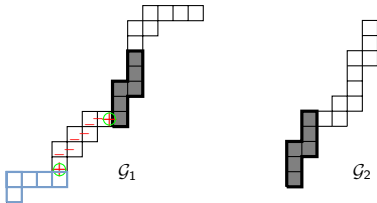
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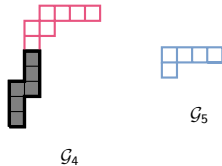
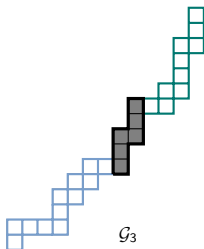
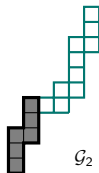
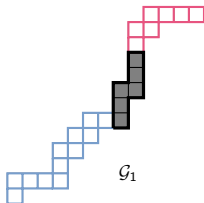
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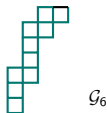
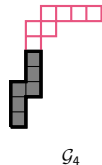
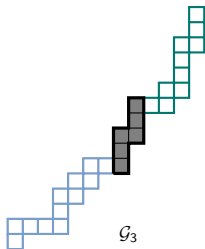
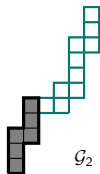
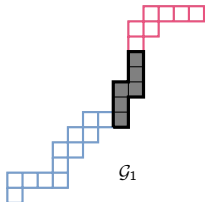


# Example: Resolution (Continued)

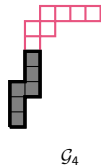
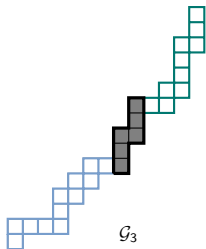
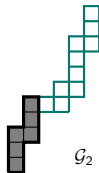
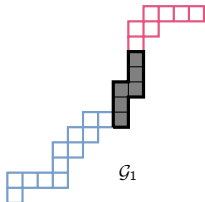




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## Resolution: Definition

**Assumption:** We will assume that  $s > 1$ ,  $t < d$ ,  $s' = 1$  and  $t' < d'$ . For all other cases, see [CS].

We define four connected snakegraphs as follows.

- $\mathcal{G}_3 = \mathcal{G}_1[1, s] \cup \mathcal{G}_2[t', d']$ ,
- $\mathcal{G}_4 = \mathcal{G}_2[1, t'] \cup \mathcal{G}_1[t+1, d]$ ,
- $\mathcal{G}_5 = \mathcal{G}_1[1, k]$  where  $k < s-1$  is the largest integer such that the sign on the interior edge between tiles  $k$  and  $k+1$  is the same as the sign on the interior edge of tiles  $s-1$  and  $s$ ,
- $\mathcal{G}_6 = \overline{\mathcal{G}_2}[d', t'+1] \cup \mathcal{G}_1[t+1, d]$  where the two subgraphs are glued along the south  $\mathcal{G}_{t+1}$  and the north of  $\mathcal{G}'_{t'+1}$  if  $\mathcal{G}_{t+1}$  is north of  $\mathcal{G}_t$  in  $\mathcal{G}_1$ .

## Definition

The **resolution of the crossing** of  $\mathcal{G}_1$  and  $\mathcal{G}_2$  in  $\mathcal{G}$  is defined to be  $(\mathcal{G}_3 \sqcup \mathcal{G}_4, \mathcal{G}_5 \sqcup \mathcal{G}_6)$  and is denoted by  $\text{Res}_{\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2)$ .

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# Bijection of Perfect Matchings

- Let  $\text{Match}(G)$  denote the set of all perfect matchings of the graph  $G$  and  

$$\text{Match}(\text{Res}_G(\mathcal{G}_1, \mathcal{G}_2)) = \text{Match}(\mathcal{G}_3 \sqcup \mathcal{G}_4) \cup \text{Match}(\mathcal{G}_5 \sqcup \mathcal{G}_6).$$

## Theorem (CS)

*Let  $\mathcal{G}_1, \mathcal{G}_2$  be two snake graphs. Then there is a bijection*

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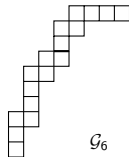
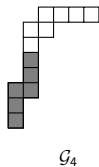
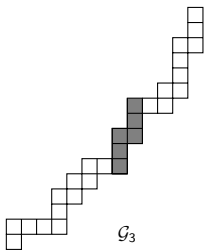
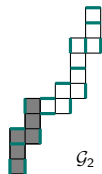
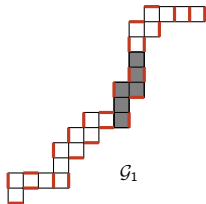
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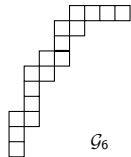
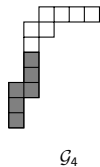
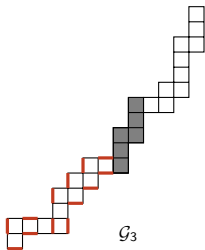
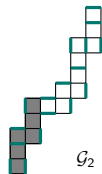
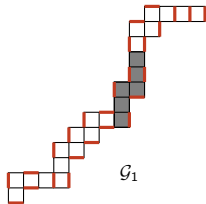
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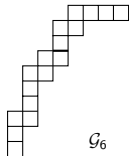
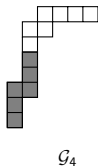
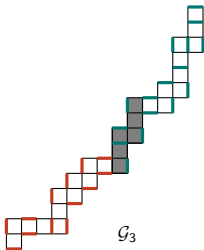
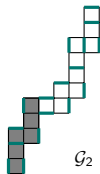
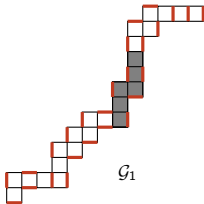
# 'Idea' of proof



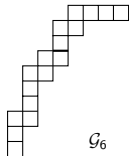
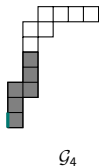
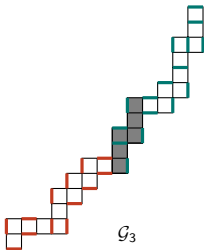
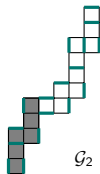
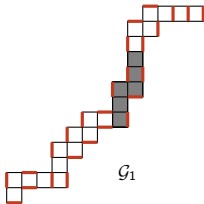
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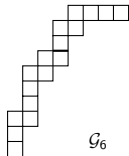
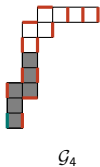
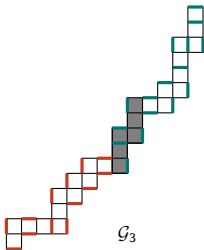
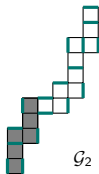
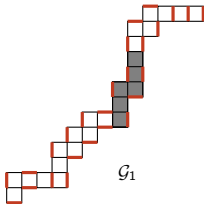
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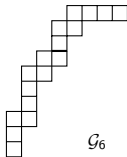
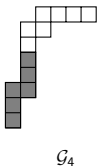
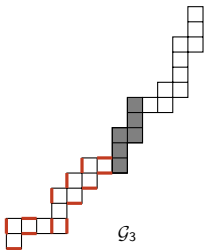
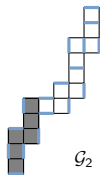
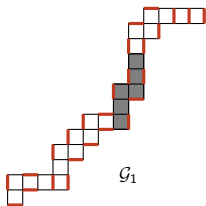


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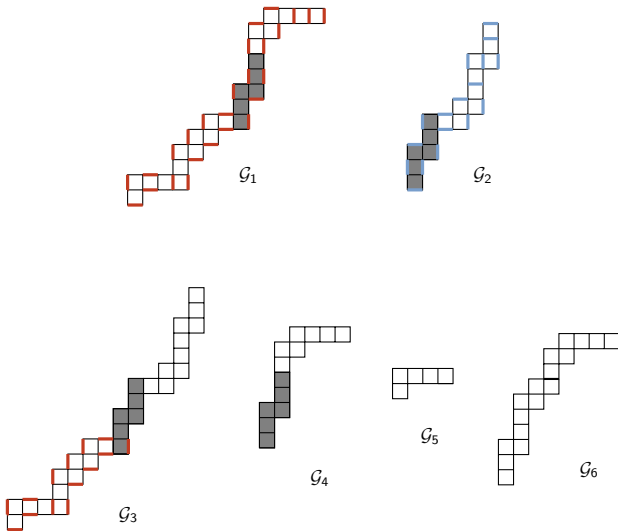


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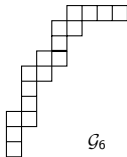
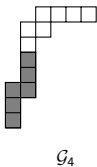
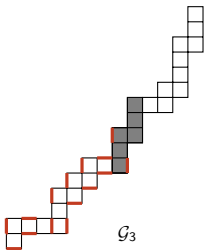
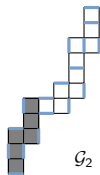
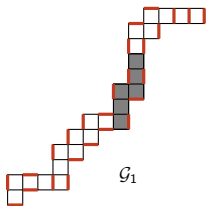




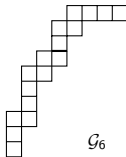
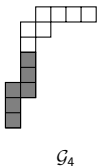
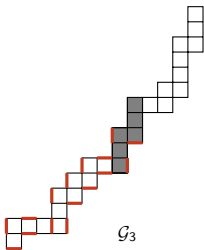
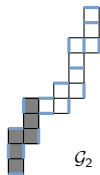
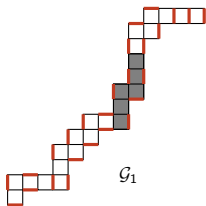
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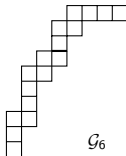
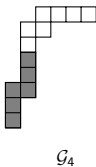
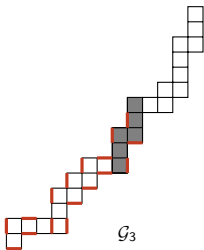
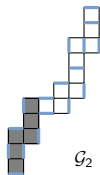
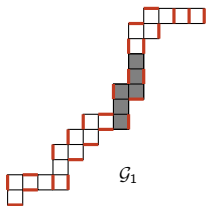
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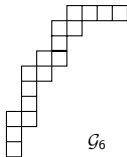
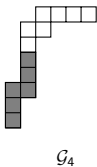
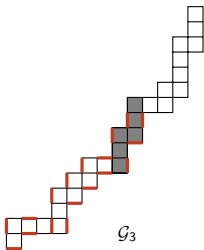
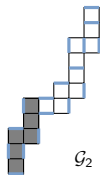
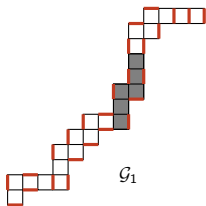
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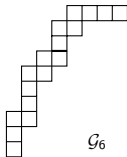
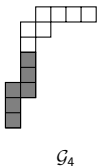
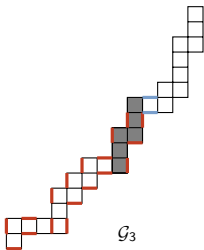
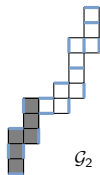
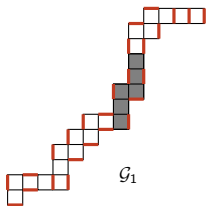
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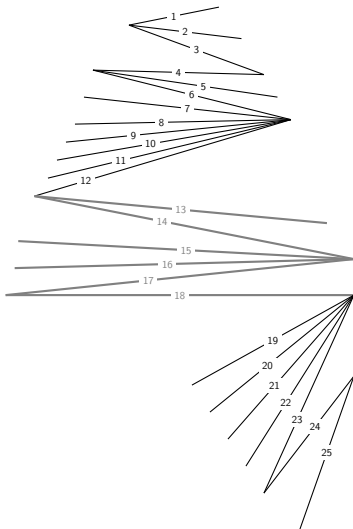




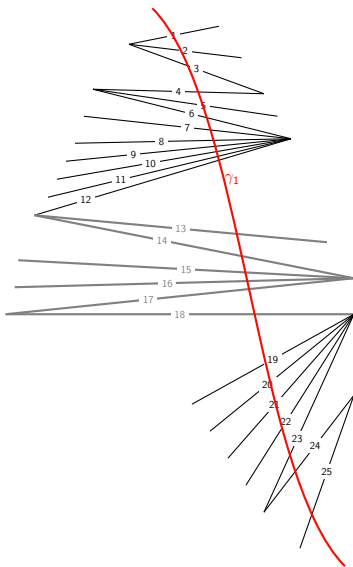




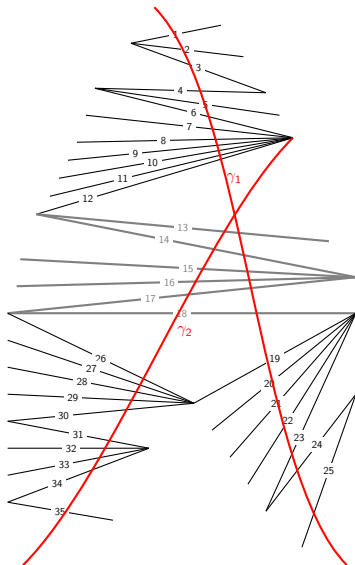
# Surface Example

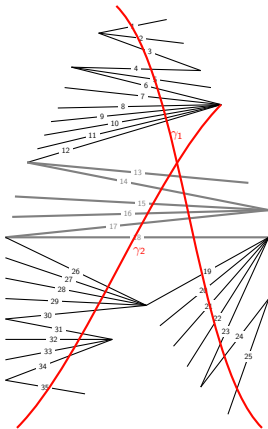


# Surface Example

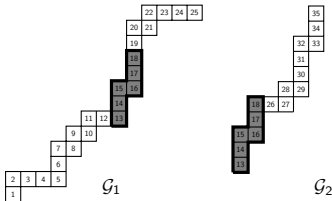


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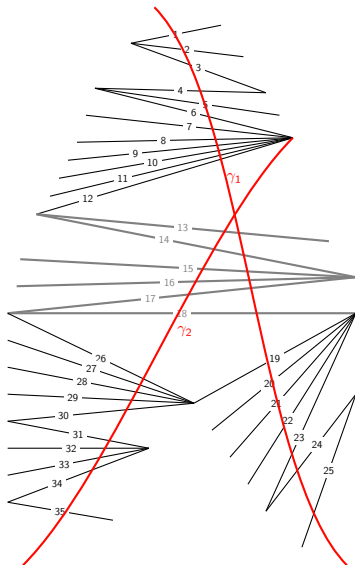




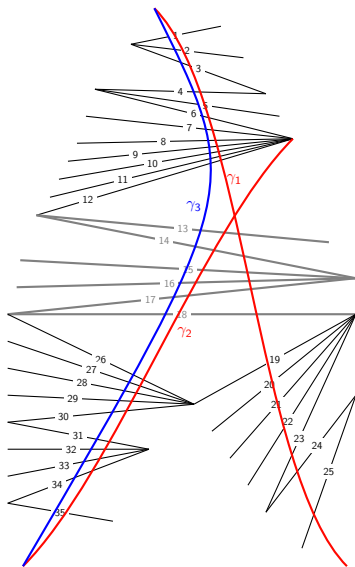
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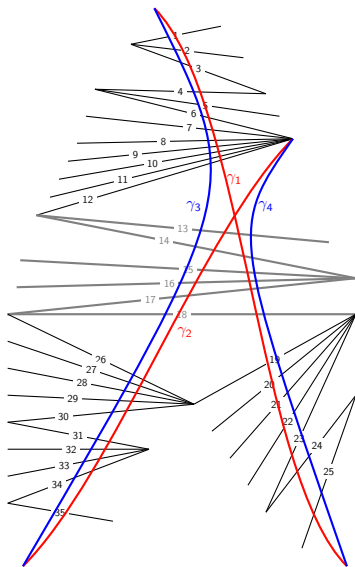


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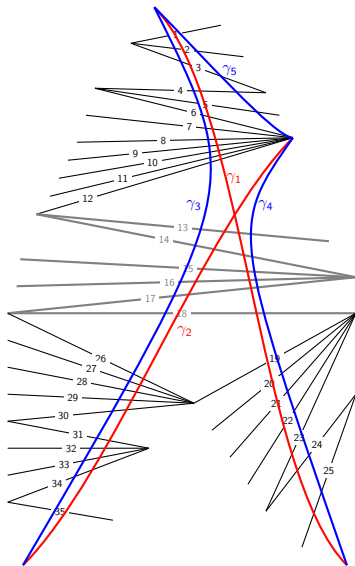




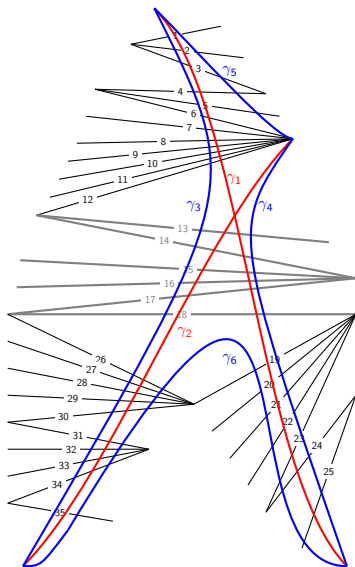
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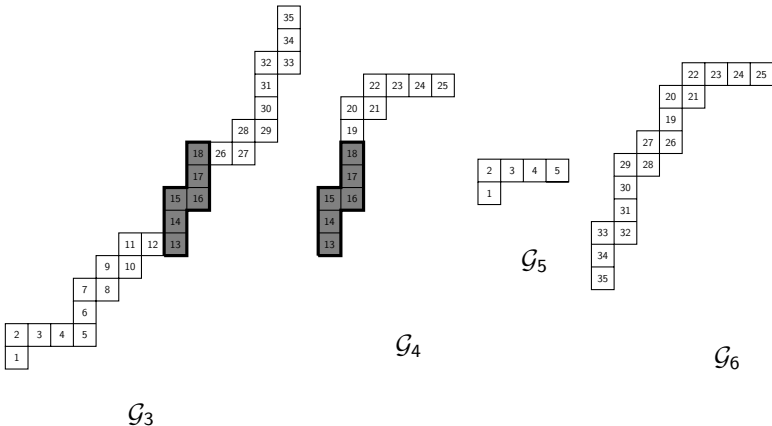
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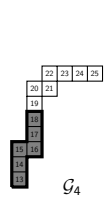
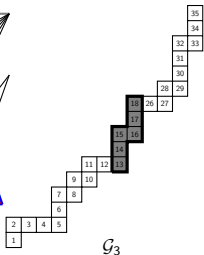
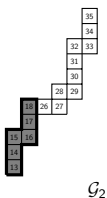
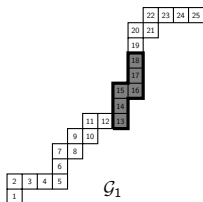
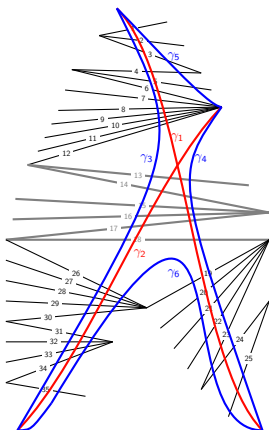
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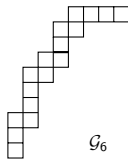
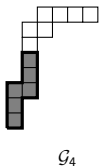
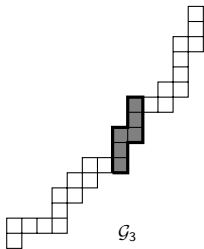
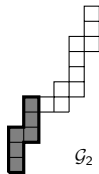
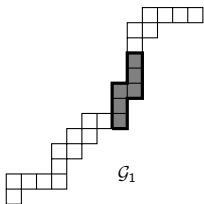
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# Relation to Cluster Algebras

Let  $\gamma_1$  and  $\gamma_2$  be two arcs and  $\mathcal{G}_1$  and  $\mathcal{G}_2$  their corresponding snake graphs.

## Theorem (CS)

$\gamma_1$  and  $\gamma_2$  **cross** if and only if  $\mathcal{G}_1$  and  $\mathcal{G}_2$  **cross** as snake graphs.

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If  $\gamma_1$  and  $\gamma_2$  cross, then the snake graphs of the four arcs obtained by **smoothing the crossing** are given by the **resolution**  $\text{Res}_{\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2)$  of the crossing of the snake graphs  $\mathcal{G}_1$  and  $\mathcal{G}_2$  at the overlap  $\mathcal{G}$ .

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We do not assume that  $\gamma_1$  and  $\gamma_2$  cross only once. If the arcs cross multiple times the theorem can be used to resolve any of the crossings.

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# Skein Relations

As a corollary we obtain a new proof of the skein relations [MW].

## Corollary (CS)

*Let  $\gamma_1$  and  $\gamma_2$  be two arcs which cross and let  $(\gamma_3, \gamma_4)$  and  $(\gamma_5, \gamma_6)$  be the two pairs of arcs obtained by smoothing the crossing. Then*

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where  $\tilde{\mathcal{G}} = (\mathcal{G}_3 \cup \mathcal{G}_4) \setminus (\mathcal{G}_5 \cup \mathcal{G}_6)$  and  $y(\tilde{\mathcal{G}}) = \prod_{\mathcal{G}_i \text{ a tile in } \tilde{\mathcal{G}}} y_i$ .

## Remark

- Note that Musiker and Williams in [MW] use hyperbolic geometry to prove the skein relations.
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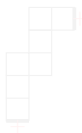
# Self-crossing snake graphs and band graphs

- Self-crossing arcs and closed loops appear naturally in the process of smoothing crossings. Consider the following example.

## Example

In this example we resolve two crossings of the following arcs.

## Example (Band graph)





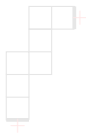
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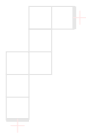
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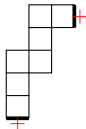
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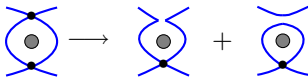


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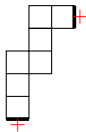
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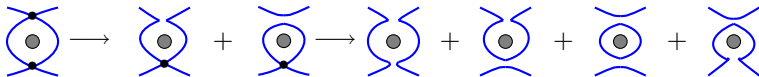


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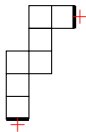
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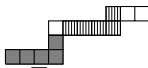
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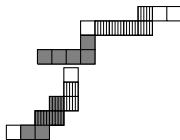
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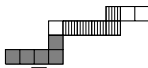
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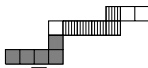
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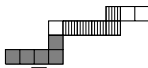
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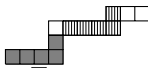
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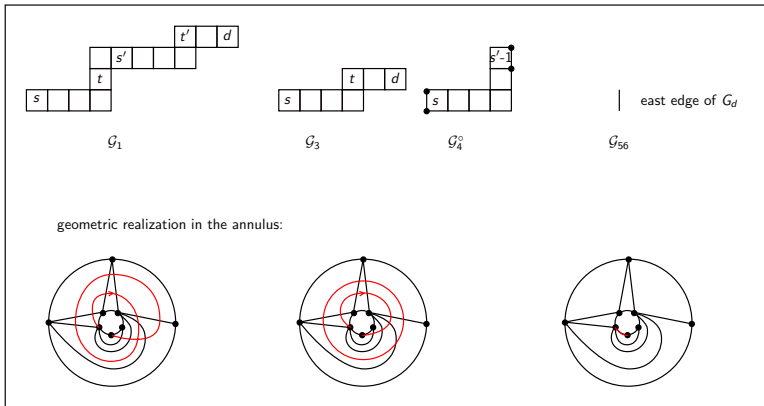
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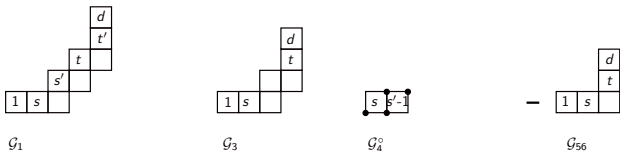
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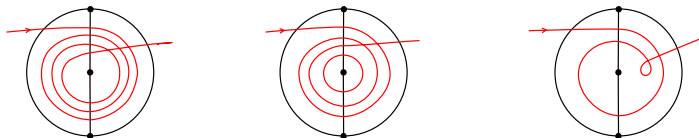




**Figure:** Example of resolution of selfcrossing when  $s' < t$  and  $s = 1$  together with geometric realization on the annulus. Here the snake graph  $G_{56}$  is a single edge and the corresponding arc in the surface is a boundary segment.



geometric realization in the punctured disk:



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## Dreaded torus

## Definition (Upper cluster algebra)

$$\mathcal{U} = \bigcap_{\mathbf{x} \text{ seed}} \mathbb{Z}[\mathbf{x}].$$

## Theorem (C, Kyungyong Lee, S)

Let  $\mathcal{A}$  be the cluster algebra associated to the dreaded torus and  $\mathcal{U}$  be its upper cluster algebra. Then  $\mathcal{A} = \mathcal{U}$ .

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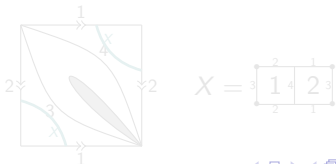
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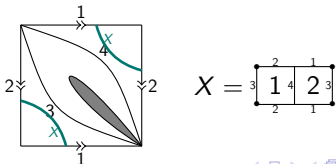
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**Sketch of proof.** By [MM], it suffices to show that three particular Laurent polynomials given by the band graphs of three loops  $X, Y, Z$  belong to the cluster algebra.



$$X = \begin{array}{|c|c|c|} \hline 2 & 1 & \\ \hline 3 & 1 & 2 \\ \hline & 2 & 1 \\ \hline \end{array}$$

## Dreaded torus

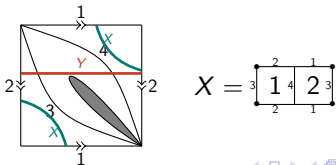
## Definition (Upper cluster algebra)

$$\mathcal{U} = \bigcap_{\mathbf{x} \text{ seed}} \mathbb{Z}[\mathbf{x}].$$

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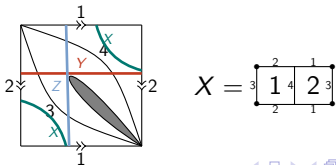
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