Nonreversible MCMC for discontinuous targets and disconnected spaces with boundaries

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Outline

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The zig-zag process on a hybrid state space

The coalescent

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Zig-zag for the coalescent

One slide on neutrons

The zig-zag process¹

- 1. Set $(x, v) \in \mathbb{R}^n \times \{-1, 1\}^n$.
- 2. Set $t \leftarrow 0$.
- 3. While t < T do
 - 3.1 Sample $Y \sim \text{Exp}(1)$. 3.2 Set ρ such that $\sum_{i=1}^{n} \int_{t}^{t+\rho} \lambda_{i}(x+sv,v) ds = Y$. 3.3 Set $x \leftarrow x + \rho v$. 3.4 Set $t \leftarrow t + \rho$. 3.5 Sample $I \sim \text{Categorical}(\lambda_{1}(x,v), \dots, \lambda_{n}(x,v))$. 3.6 Set $v_{l} \leftarrow -v_{l}$.
- Between switches, x moves with constant velocity v.

• Target density π is invariant if

$$\lambda_i(x, v) = v_i \partial_i \log \pi(x) \vee 0.$$

¹J Bierkens, P Fearnhead and G Roberts. The zig-zag process and super-efficient sampling for Bayesian analysis of big data, Ann Stat 47(3):1288–1320, 2019.

The zig-zag process



(d) 2D S-shaped density

¹J Bierkens, P Fearnhead and G Roberts. The zig-zag process and super-efficient sampling for Bayesian analysis of big data, Ann Stat 47(3):1288–1320, 2019.

Advantages and disadvantages of zig-zag

- + Avoids reversible backtracking.
- + Rejection-free.
- $+\,$ Direction of travel guided by shape of target.
- Construction only makes sense if target density is differentiable...
- $-\,$ and if the state space is one connected set.

The zig-zag process on a hybrid state space

- Target $\pi(m, x)$ on $\mathbb{F} \times \Omega \subseteq \mathbb{N} \times \mathbb{R}^n$.
- For each $m \in \mathbb{F}$ create Ω_m , a copy of Ω .
- Let Γ[±]_m be respective exit and entrance boundaries into Ω_m (which can be artificially introduced if necessary), and suppose Q is a Markov kernel from Γ⁺ = ∪_{m∈F}Γ⁺_m to Γ⁻ := ∪_{m∈F}Γ⁻_m.
- While in some Ω^o_m, let the process undergo zig-zag dynamics with target π(m, ·).
- When an exit boundary is hit, the state jumps with law Q and re-enters a different copy.

The zig-zag process on a hybrid state space

Take
$$\mathbb{F} = \{A, B\}$$
 and $\Omega = B(0, 1)$.



Piecewise deterministic Markov processes²

The generalised zig-zag process (m_t, x_t, v_t) is a PDMP with generator

$$Lf(m, x, v) := v \cdot \nabla_x f(m, x, v) + \sum_{i=1}^d \lambda_i(m, x, v) [f(m, x, F_i v) - f(m, x, v)]$$

whose domain D(L) consists of measurable functions f satisfying

$$f(m, x, v) = \int_{(j, y, w) \in \Gamma^-} f(j, y, w) Q(m, x, v; j, \mathrm{d}y, w)$$

for any $(m, x, v) \in \Gamma^+$, and some boundedness & continuity conditions.

²M Davis. Markov models and optimization, Chapman & Hall, 1993. Especially chapters 2 and 3.

Theorem³

Suppose the initial condition has a density, that \mathbb{F} is finite, that $\pi(m, \cdot) \in C^1(\Omega_m^o)$ for each $m \in \mathbb{F}$, that $\pi > 0$ on $\bigcup_{m \in \mathbb{F}} \Omega_m^o$, and 1. $\mathbb{E}_{(m,x,v)}[\#$ jumps by time $t] < \infty$ for any (m, x, v) and t > 0, 2. for each $(x, v) \in \Gamma_m^+$ and $(y, w) \in \Gamma_j^-$,

$$\pi(m,x)Q(m,x,v;j,y,w)=\pi(j,y)Q(j,y,-w;m,x,-v),$$

3. for each $(x, v) \in \Gamma_m^+$,

$$\int_{(j,y,w)\in\Gamma^{-}}(w\cdot n(j,y))Q(m,x,v;j,\mathrm{d}y,w)=-v\cdot n(m,x),$$

where n(m, x) is the unit outward normal at $x \in \partial \Omega_m$,

4. and that Q is such that jumps facing corners are a null event. Then π is a stationary distribution of (m_t, x_t, v_t) .

³J Koskela. Zig-zag sampling for discrete structures and non-reversible phylogenetic MCMC, arXiv:2004.08807.

Sketch proof

The various technical assumptions guarantee that C¹_b ∩ D(L) separates measures on the domain of the zig-zag process.

• The aim is to show
$$\mathbb{E}_{\pi}[Lf(m, x, v)] = 0$$
 for each $f \in C_b^1 \cap D(L)$.

$$\mathbb{E}_{\pi}\left[v \cdot \nabla_{x}f(m, x, v) + \sum_{i=1}^{d} \lambda_{i}(m, x, v)[f(m, x, F_{i}v) - f(m, x, v)]\right]$$

= $\mathbb{E}_{\pi}[v \cdot \{\nabla_{x}f(m, x, v) - f(m, x, v)\nabla_{x}\log \pi(m, x)\}]$
= $\mathbb{E}_{\pi}[v \cdot \nabla_{x}f(m, x, v) - v \cdot \nabla_{x}f(m, x, v) - \text{Boundary terms}].$

The defining boundary property of the domain D(L) and the two conditions on π and Q are exactly what you need to show that boundary terms vanish.

Ergodicity

If \mathbb{F} is finite and the process restricted to a single domain Ω_m with target $\pi(m, \cdot)$ is ergodic for each $m \in \mathbb{F}$, then the full process is ergodic provided

$$\int_{(x,v)\in\Gamma_m^+}\int_{(y,v)\in\Gamma_j^-}Q(m,x,v;j,\mathrm{d} y,w)\pi(m,x)>0$$

for enough ordered pairs $(m, j) \in \mathbb{F}^2$ to form a tour.

Some criteria for ergodicity of a single-domain process are known⁴.

⁴J Bierkens, G Roberts and P-A Zitt. Ergodicity of the zig-zag process, Ann Appl Probab 29(4):2266–2301, 2019.

The coalescent⁵

- $(\Pi_t)_{t\geq 0}$ with $\Pi_0 = \{\{1\}, \ldots, \{n\}\}.$
- Holding times $T_k \sim \operatorname{Exp}\left(\binom{k}{2}\right)$.
- At jump times, two randomly chosen blocks merge.
- $i \sim j$ in $\Pi_t \Leftrightarrow i$ and j have a common ancestor at time t.
- Mutations as a Poisson point process with rate θ/2 on the branches of the tree.

⁵J F C Kingman. The coalescent, Stoch Proc Appl 13(3):235–248, 1982.

The coalescent



The coalescent as missing data



A geometric embedding of coalescent trees⁶

- Encode a tree as (E_n, \mathbf{t}_n) .
- ▶ $\mathbf{t}_n := (t_1, \dots, t_{n-1}) \in \mathbb{R}^{n-1}_+$ are the times between successive mergers.
- E_n is the ranked topology: an ordered set of nodes specifying the exact merger events.
- τ -space: separate copy of \mathbb{R}^{n-1}_+ for each distinct E_n .
- Glue common faces of separate orthants together to form a connected space.

•
$$\#E_n = \frac{(n-1)!n!}{2^{n-1}}.$$

⁶A Gavryushkin and A J Drummond. The space of ultrametric phylogenetic trees, J Theor Biol 403:197–208, 2016.

The three leaf $\tau\text{-space}$



:

One third of the four leaf τ -space



 ^{6}A Gavryushkin and A J Drummond. The space of ultrametric phylogenetic trees, J Theor Biol 403:197–208, 2016.

The infinite sites coalescent posterior

Regard E_n as a set of edges.

- Given n observed sequences and a putative ancestral tree (E_n, t_n), for an edge γ ∈ E_n, define:
 - $m_{\gamma} :=$ number of mutations on γ .
 - $t_i \in \gamma$ if γ spans the *i*th interval.
 - $\ell_{\gamma} := \sum_{i:t_i \in \gamma} t_i$ be the branch length.

$$\pi(\theta, E_n, \mathbf{t}_n) \propto \left\{ \prod_{\gamma \in E_n} \frac{1}{m_{\gamma}!} \left(\frac{\theta \ell_{\gamma}}{2}\right)^{m_{\gamma}}
ight\}
onumber \ imes \exp\left(-\sum_{i=1}^{n-1} \frac{(n+1-i)(n+ heta-i)}{2} t_i
ight).$$

Flip rates

$$egin{aligned} &\lambda_i(E_n,\mathbf{t}_n, heta;\mathbf{v}):=\mathbf{v}_iigg(rac{(n+1-i)(n+ heta-i)}{2}-\sum_{\gamma\in E_n:t_i\in\gamma}rac{m_\gamma}{\ell_\gamma}igg)ee 0,\ &\lambda_ heta(E_n,\mathbf{t}_n, heta;\mathbf{v}):=\mathbf{v}_ hetaigg(\sum_{i=1}^{n-1}rac{n+1-i}{2}t_i-rac{1}{ heta}\sum_{\gamma\in E_n}m_\gammaigg)ee 0. \end{aligned}$$

Important: $v_i = \pm 1/\binom{n+1-i}{2}$.

Ranked topology crossings

- Exit and entrance boundaries := faces at which $t_i = 0$ or $\theta = 0$.
- Define the jump kernel Q via the orthants which intersect at a face.
- π is continuous at the boundaries of ranked topologies.
- Crossing into uniformly chosen adjacent topology when a boundary is hit satisfies the conditions on Q.
- So does reflecting at the $t_1 = 0$ and $\theta = 0$ boundaries.

Simulation study⁷



Figure 3. Perfect phylogeny of the Griffiths and Tavaré (1994) data set.

⁸A Hobolth, M K Uyenoyama and C Wiuf. Importance sampling for the infinite sites model, Stat Appl Genet Mol Biol 7(1) Article 32, 2008.

⁸R C Griffiths and S Tavaré. Ancestral inference in population genetics, Stat Sci 9:307–319, 1994.

⁸R H Ward, B L Frazier, K Dew and S Pääbo. Extensive mitochondrial diversity within a single Amerindian tribe, Proc Natl Acad Sci USA 88:8720–8724, 1991.

Mutation rate



Tree height



Mutation rate, sample size = 550



Tree height, sample size = 550



Mutation rate, $\theta = 55$



Tree height, $\theta = 55$



What about a nuclear reactor?

