

# What can we do with the large scale optimal transport problem?

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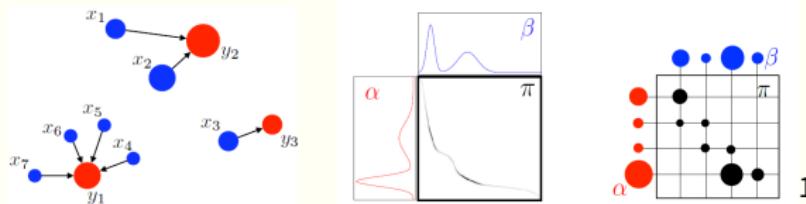
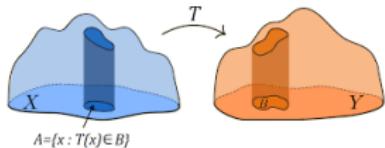
# Introduction

# What is optimal transport?

Optimal transport (OT) seeks the best way of transforming one probability distribution into another

$$\min_{\mathbf{P} \in \Pi(a,b)} \sum_{i,j} \mathbf{C}_{i,j} \mathbf{P}_{i,j},$$

where  $\mathbf{C}$  is the cost between two distributions, and the constraint set  $\Pi(\mathbf{a}, \mathbf{b}) = \{\mathbf{P} \in \mathbb{R}_+^{n \times m} : \mathbf{P}\mathbf{1} = \mathbf{a}, \mathbf{P}\mathbf{1} = \mathbf{b}\}$ .



<sup>1</sup>Gabriel Peyré, Marco Cuturi, et al. "Computational optimal transport: With applications to data science". In: *Foundations and Trends® in Machine Learning* 11.5-6 (2019), pp. 355–607.

# Applications



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<sup>2</sup>Peyré, Cuturi, et al., "Computational optimal transport: With applications to data science".

# How do we solve a OT problem?

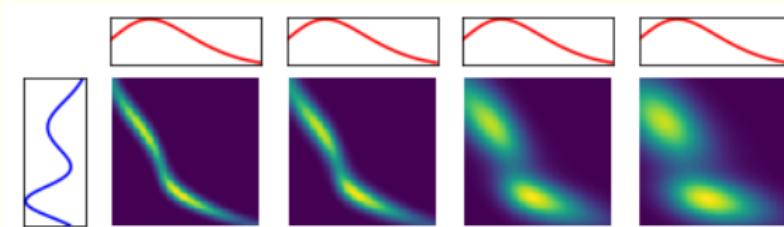
Entropic regularisation:

$$\min_{\mathbf{P} \in \Pi(\mathbf{a}, \mathbf{b})} \sum_{i,j} \mathbf{c}_{i,j} \mathbf{P}_{i,j} + \epsilon \mathbf{P}_{i,j} \log(\mathbf{P}_{i,j} - 1).$$

**Proposition:**  $\mathbf{P}_{i,j} = \mathbf{u}_i \mathbf{Kv}_j \quad \mathbf{K}_{i,j} = \exp(-\mathbf{C}_{i,k}/\epsilon)$

**Marginal constraints:**  $\mathbf{u} \odot (\mathbf{Kv}) = \mathbf{a} \quad \mathbf{v} \odot (\mathbf{K}^T \mathbf{u}) = \mathbf{b}$

**Sinkhorn iterations:**  $\mathbf{u} \leftarrow \frac{\mathbf{a}}{\mathbf{Kv}} \quad \mathbf{v} \leftarrow \frac{\mathbf{b}}{\mathbf{K}^T \mathbf{u}}$



# Online Sinkhorn

# Continuous OT

For general distributions  $\alpha, \beta$ ,

$$OT_\epsilon(\alpha, \beta) = \min_{\pi \in \Pi(\alpha, \beta)} \int c(x, y) d\pi(x, y) + \epsilon \text{KL}(\pi, \alpha \otimes \beta),$$

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**Sinkhorn iterations:**

$$\begin{aligned} u_{t+1} &= \int \frac{1}{v_t} \exp(c/\epsilon) d\beta \\ v_{t+1} &= \int \frac{1}{u_t} \exp(c/\epsilon) d\alpha, \end{aligned}$$

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which can be rewritten as

$$(u_{t+1}, v_{t+1}) = (u_t, v_t) - \mathcal{F}_{\alpha, \beta}(u_t, v_t),$$

where  $\mathcal{F}_{\alpha, \beta}(u, v) = (u - \int \frac{1}{v} \exp(c/\epsilon) d\beta, v - \int \frac{1}{u} \exp(c/\epsilon) d\alpha).$

# Development of Online Sinkhorn

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<sup>3</sup>Arthur Mensch and Gabriel Peyré. “Online Sinkhorn: Optimal Transport distances from sample streams”. In: *arXiv e-prints* (2020), arXiv–2003.

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The Randomised Sinkhorn<sup>3</sup> with samples newly drawn i.i.d. from  $\alpha$  and  $\beta$ :

$$(u_{t+1}, v_{t+1}) = (u_t, v_t) - \mathcal{F}_{\hat{\alpha}_t, \hat{\beta}_t}(u_t, v_t),$$

where  $\hat{\alpha}_t = \frac{1}{n_t} \sum_{i=1}^{n_t} \delta_{x_i}$ ,  $\hat{\beta}_t = \frac{1}{n_t} \sum_{i=1}^{n_t} \delta_{y_i}$ .

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⇒ Introduce the learning rate  $\eta_t$ :

$$(u_{t+1}, v_{t+1}) = (u_t, v_t) - \eta_t \mathcal{F}_{\hat{\alpha}_t, \hat{\beta}_t}(u_{t+1}, v_t).$$

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# Low Rank OT

# Problem formulation

Consider the low rank OT (LR-OT) problem in the following form

$$\min_{U, V \in \mathbb{R}_+^{n \times r}} \langle C, UV^T \rangle \text{ s.t. } (UV^T)\mathbb{1} = a \quad \text{and} \quad (VU^T)\mathbb{1} = b.$$

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Further consider the regularised LR-OT problem:

$$\min_{U,V \in \mathbb{R}_+^{n \times r}} \langle C, UV^T \rangle + \epsilon(H(U) + H(V)) \text{ s.t. } (UV^T)\mathbb{1} = a \quad \text{and} \quad (VU^T)\mathbb{1} = b,$$

where  $H(x) = x \log(x - 1)$  is the entropy regularisation.

# Results

We propose to Alternating Minimisation to solve the problem above:

1: **for**  $i = 1$  to  $N$  **do**

2:    $U^{k+1} \leftarrow \min_U \langle C, UV^{kT} \rangle$  s.t.  $(UV^{kT})\mathbb{1} = a, (V^k U^T)\mathbb{1} = b$

$V^{k+1} \leftarrow \min_V \langle C, U^{k+1} V^T \rangle$  s.t.  $(U^{k+1} V^T)\mathbb{1} = a, (V U^{k+1T})\mathbb{1} = b$

3: **end for**

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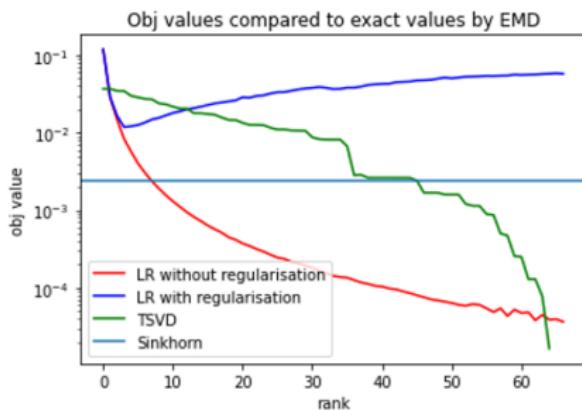
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# Main Takeaways

1. Introduction to optimal transport
2. Online Sinkhorn – for continuous OT
3. Low rank OT – to reduce the complexity

# Thank you!