

Regularization of Inverse Problems

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What is an Inverse Problem?

- ▶ $A : X \rightarrow Y$ mapping between Hilbert spaces X, Y
- ▶ physical model A , **cause** x and **effect** $A(x)$.

Direct / Forward Problem: given x , calculate $A(x)$.

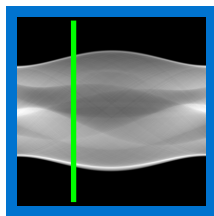
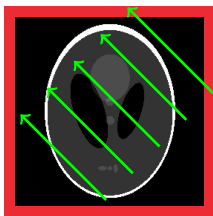
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- ▶ Example: Positron Emission Tomography (PET)
Model: X-ray Transformation

$$Ax : L \mapsto \int_L x(r) dr$$

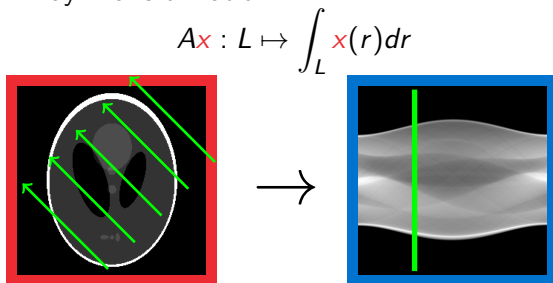


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Inverse Problem: Given y , calculate x with $A(x) = y$.

Infer from the **effect** the **cause**.

What is the problem with Inverse Problems?

Examples

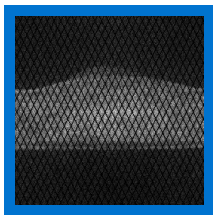
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- ▶ 2. Positron Emission Tomography

Data: PET scanner in London, model: $Ax : L \mapsto \int_L x(r) dr$

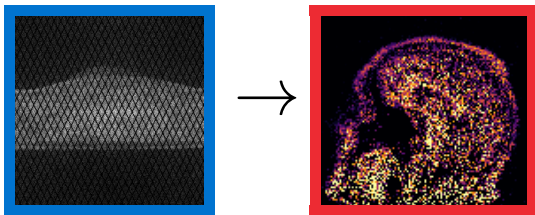


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What is the problem with Inverse Problems?

Definition (Jacques Hadamard, 1902):
An Inverse Problem " $A(x) = y$ " is called **well-posed**, if the solution

- (1) **exists**.
- (2) is **unique**.
- (3) depends **continuously** on the data.

"Small errors in y lead to small errors in x ."

Otherwise, we call it **ill-posed**.



Generalized Solutions

Definition: Let $y \in Y$. The set of all **approximate solutions** of “ $A(x) = y$ ” is

$$L := \left\{ x \in X \mid \|A(x) - y\| \leq \|A(z) - y\| \quad \forall z \in X \right\}.$$

If a solution $z \in X$ exists, $\|A(z) - y\| = 0$, then

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Definition: An approximate solution $\bar{x} \in L$ is called **minimal-norm-solution**, if

$$\|\bar{x}\| \leq \|x\| \quad \forall x \in L.$$

Properties of Minimal-Norm-Solutions

Assume: $A \in L(X, Y)$

Recall:

- ▶ Range of A : $R(A) := \{y \in Y \mid \exists x \in X : Ax = y\} \subset Y$
- ▶ Orthogonal complement: $U \subset Y$,

$$U^\perp := \{y \in Y \mid \langle y, u \rangle = 0 \quad \forall u \in U\}$$

- ▶ Minkowski sum: $U + V := \{u + v \mid u \in U, v \in V\}$

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- ▶ If the range $R(A)$ is closed, then $R(A) + R(A)^\perp = Y$, otherwise $R(A) + R(A)^\perp \subsetneq Y$.

Example: $A : \ell^2 \rightarrow \ell^2, (Ax)_j = \frac{x_j}{j}$. Range **not** closed.

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Theorem: If $R(A)$ is **not** closed, then \bar{x} **does not** depend **continuously** on y . I.e. A^\dagger is not continuous.

Regularization

Intuition: board

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Definition: A family $\{R_\alpha\}_{\alpha>0}$ is called **regularization** of A^\dagger , if for all

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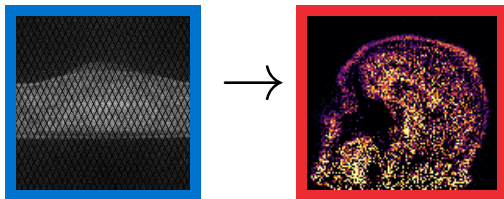
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