



UNIVERSITY OF  
**BATH**

## Introduction to Monte Carlo

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## Problem statement

We are interested in integrals of the form

$$\mathbb{E}[\varphi(X)] = \int \varphi(x)\pi(dx), \quad (1)$$

where  $\pi$  is a **probability measure** defined on  $(\mathbb{X}, \mathcal{X})$ ,  $\varphi : \mathcal{X} \rightarrow \mathbb{R}$  is  $\mathcal{B}(\mathbb{R})/\mathcal{X}$ -measurable.

Typically these integrals are intractable

# Monte Carlo

Often it is simpler (than to evaluate  $\mathbb{E}[\varphi(X)]$ ) to draw a sample

$$\{X^1, \dots, X^N\} \stackrel{\text{iid}}{\sim} \pi$$

in which case we can straightforwardly calculate

$$\pi^N(\varphi) = \frac{1}{N} \sum_{i=1}^N \varphi(X^i) \approx \mathbb{E}[\varphi(X)] \quad (2)$$

There are many theoretically sound results on the approximation ' $\approx$ ' in (2).

# Validity of Monte Carlo

$$\mathbb{E} \left[ \pi^N(\varphi) \right] = \mathbb{E}[\varphi(X)] \quad (\text{Unbiased})$$

$$\mathbb{V} \left[ \pi^N(\varphi) \right] = \frac{1}{N} \mathbb{V}[\varphi(X)] \quad (\text{Error})$$

$$\pi^N(\varphi) \xrightarrow[N \rightarrow \infty]{\text{a.s.}} \mathbb{E}[\varphi(X)] \quad (\text{Convergence})$$

$$\sqrt{N} \left( \pi^N(\varphi) - \mathbb{E}[\varphi(X)] \right) \xrightarrow[N \rightarrow \infty]{d} \mathcal{N}(0, \mathbb{V}[\varphi(X)])$$

(Central limit theorem)

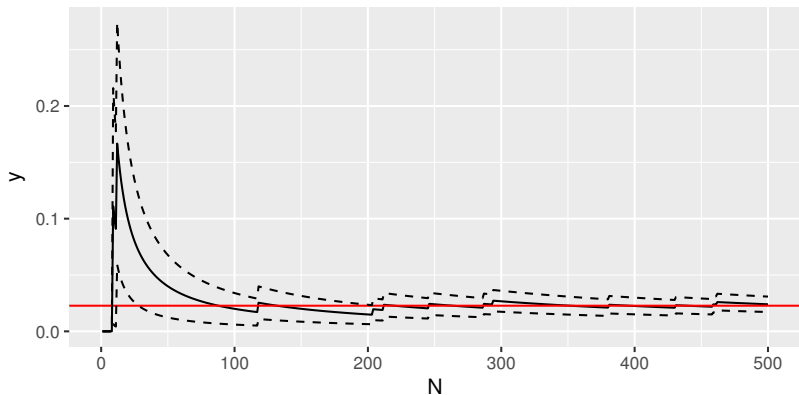
## Problems with Monte Carlo

$$\mathbb{P}[X > 2] = \mathbb{E}[\mathbb{I}(X > 2)] = \int \mathbb{I}(x > 2)\pi(dx), \quad \text{where } X \sim \mathcal{N}(0, 1)$$



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## Importance sampling

Obviously

$$\mathbb{E}_{\pi}[\varphi(\mathbf{X})] = \int \varphi(\mathbf{x})\pi(\mathbf{x})d\mathbf{x} = \int \varphi(\mathbf{x})\frac{\pi(\mathbf{x})}{\gamma(\mathbf{x})}\gamma(\mathbf{x})d\mathbf{x} = \mathbb{E}_{\gamma}\left[\varphi(\mathbf{X})\frac{\pi(\mathbf{X})}{\gamma(\mathbf{X})}\right]$$

so we can construct another approximation

$$\pi_{\text{IS}}^N(\varphi) = \frac{1}{N} \sum_{i=1}^N \varphi(\mathbf{X}^i) \frac{\pi(\mathbf{X}^i)}{\gamma(\mathbf{X}^i)} \approx \mathbb{E}_{\gamma}\left[\varphi(\mathbf{X}) \frac{\pi(\mathbf{X})}{\gamma(\mathbf{X})}\right] = \mathbb{E}_{\pi}[\varphi(\mathbf{X})],$$

where

$$\{\mathbf{X}^1, \dots, \mathbf{X}^N\} \stackrel{\text{iid}}{\sim} \gamma$$

# Validity of importance sampling

We have immediately

$$\mathbb{E} \left[ \pi_{\text{IS}}^N(\varphi) \right] = \mathbb{E}[\varphi(\mathbf{X})] \quad (\text{Unbiased})$$

$$\pi_{\text{IS}}^N(\varphi) \xrightarrow[N \rightarrow \infty]{\text{a.s.}} \mathbb{E}[\varphi(\mathbf{X})] \quad (\text{Convergence})$$

but considerations on the variance of the  $\pi_{\text{IS}}^N(\varphi)$  are somewhat more subtle. The variance may indeed be **infinite**, depending on the function  $\pi/\gamma$ .

## Theorem 1

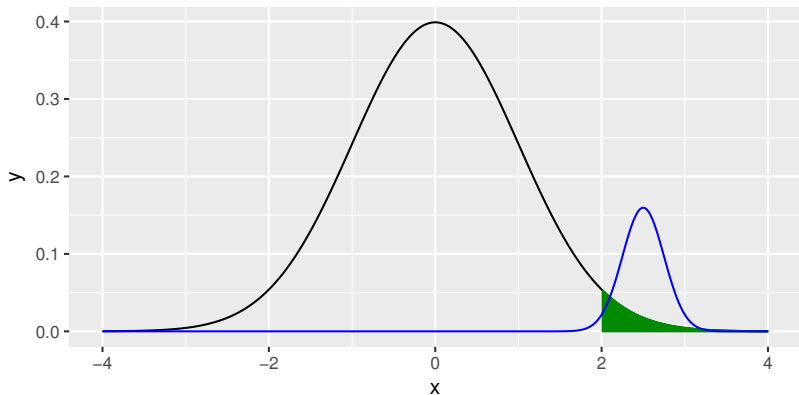
*The choice of  $\gamma$  which minimises the variance of  $\pi_{\text{IS}}^N(\varphi)$  is*

$$\gamma(x) = \frac{|\varphi(x)|\pi(x)}{\int |\varphi(x)|\pi(x)dx}$$



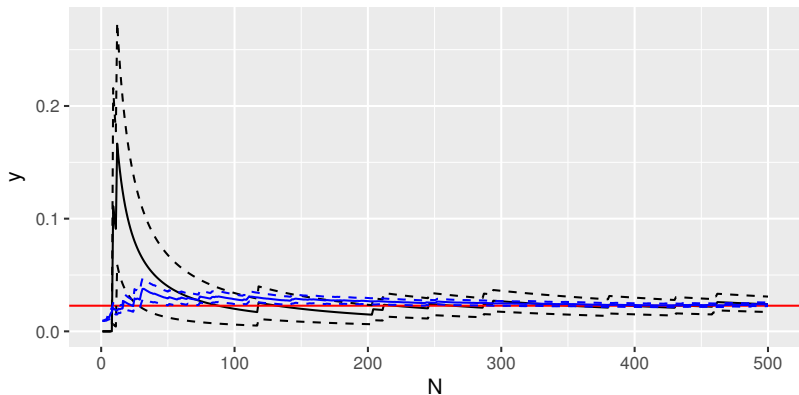
## Importance sampling for the problem above

$$\mathbb{P}[X > 2] = \mathbb{E}[\mathbb{I}(X > 2)] = \int \mathbb{I}(x > 2)\pi(dx), \quad \text{where } X \sim \mathcal{N}(0, 1)$$



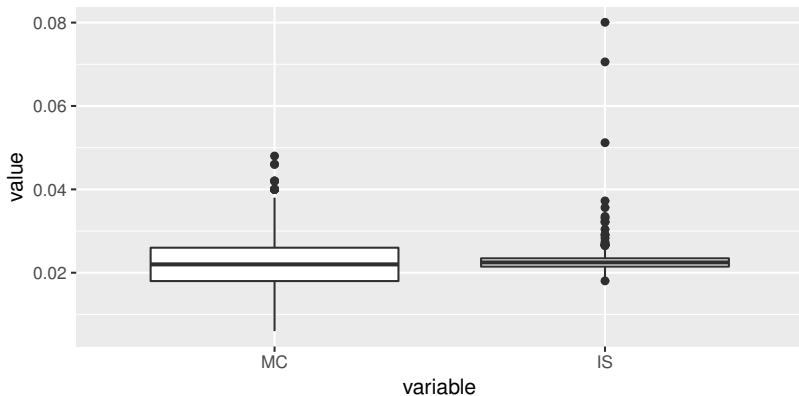
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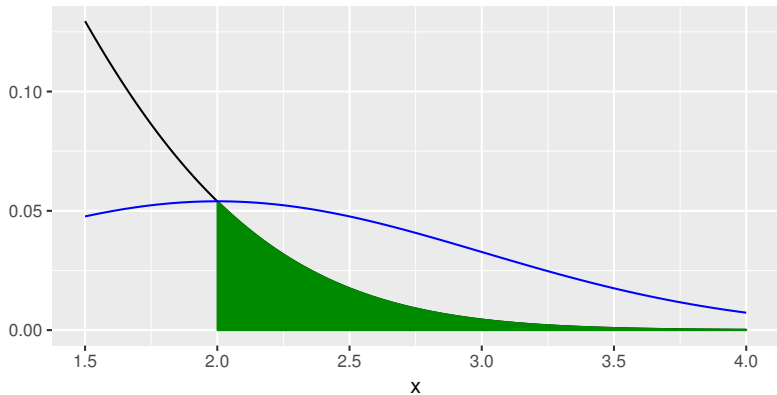


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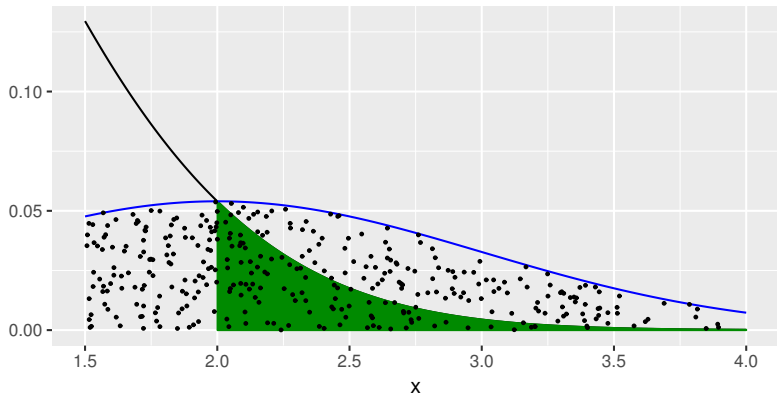
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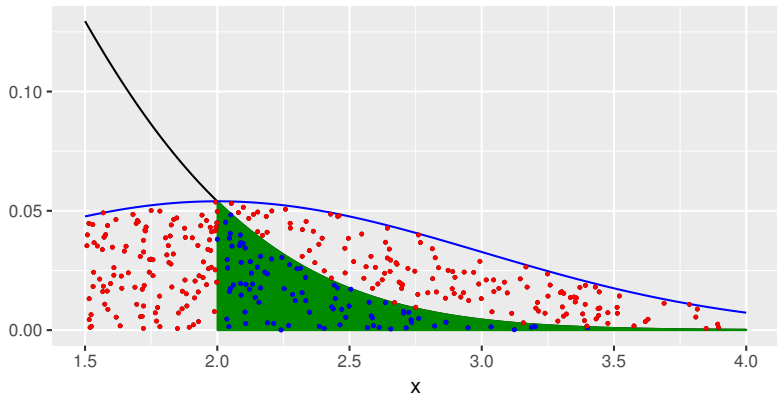
# Accept reject method



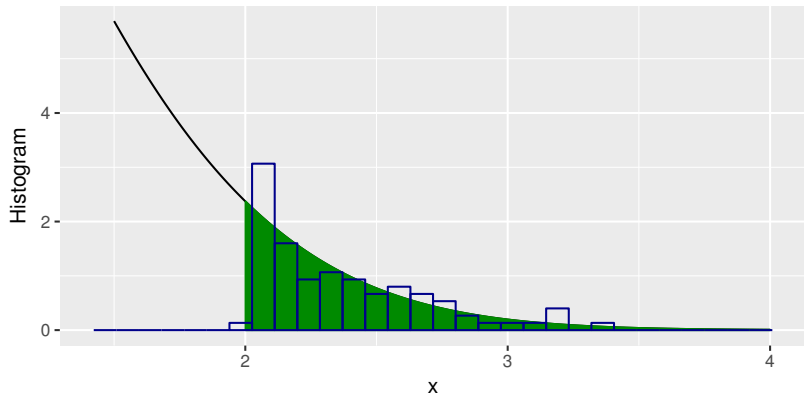
# Accept reject method



# Accept reject method



# Accept reject method



# Multilevel Monte Carlo (MLMC)

Consider a situation where we are interested in an expectation

$$\mathbb{E}[\varphi(X)] = \int \varphi(x)\pi(dx),$$

where  $\varphi : \mathbb{X} \rightarrow \mathbb{R}$  is **uniformly Lipschitz**, but  $X$  cannot be simulated exactly from  $\pi$ . Instead we have approximations  $\{\pi_1, \dots, \pi_L\}$  of different levels of accuracy of  $\pi$  that are **easy to sample from**. We also assume that for  $\ell_1 < \ell_2$ ,  $\pi_{\ell_1}$  is **less expensive** to simulate from than  $\pi_{\ell_2}$  but also a **worse approximation** of  $\pi$ .



# Multilevel Monte Carlo

Define

$$\hat{P}_\ell = \varphi(X_\ell), \quad \text{where } X_\ell \sim \pi_\ell \text{ and } \ell \in \{1, \dots, L\}.$$

Clearly

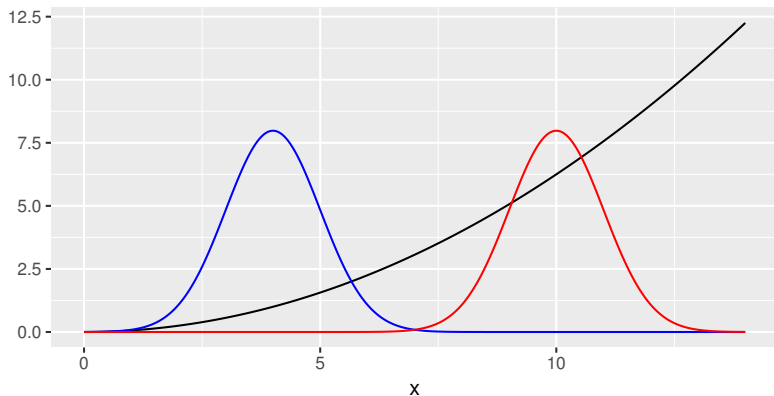
$$\mathbb{E}[\hat{P}_L] = \mathbb{E}[\hat{P}_0] + \sum_{\ell=1}^L \mathbb{E}[\hat{P}_\ell - \hat{P}_{\ell-1}]$$

For each of the expectations above we can construct the approximations

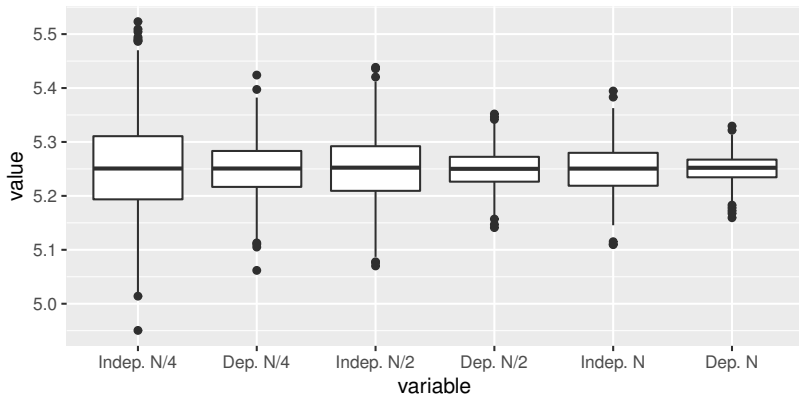
$$\hat{Y}_0 = \frac{1}{N_\ell} \sum_{i=1}^{N_\ell} \hat{P}_0^i \quad \text{and} \quad \hat{Y}_\ell = \frac{1}{N_\ell} \sum_{i=1}^{N_\ell} (\hat{P}_\ell^i - \hat{P}_{\ell-1}^i)$$

## Variance reduction by control variates

$$\mathbb{E}[(X_2/4)^2 - (X_1/4)^2], \quad \text{where } X_1 \sim \mathcal{N}(4, 1), \quad X_2 \sim \mathcal{N}(10, 1)$$



# Variance reduction by control variates



$N = 1000$