

A very brief overview of population dynamics models

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Population dynamics models can be:

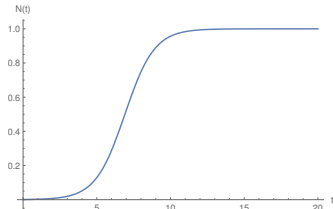
- Continuous / Discrete
- Deterministic / Stochastic
- Well-mixed / Spatial / Network
- Single-type / Multi-type

Logistic model

Continuous, deterministic, well-mixed, single-type.

$$\frac{dN}{dt} = rN \left(1 - \frac{N}{K} \right)$$

N - size of population, r - growth rate, K - carrying capacity



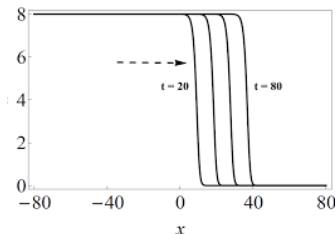
Unstable steady state at $N = 0$, stable steady state at $N = K$.

Fisher KolmogorovPetrovskyPiskunov (FKPP) model

Continuous, deterministic, spatial, single-type.

$$\frac{\partial N}{\partial t} = rN \left(1 - \frac{N}{K} \right) + D \frac{\partial N}{\partial x^2}$$

D - diffusion rate



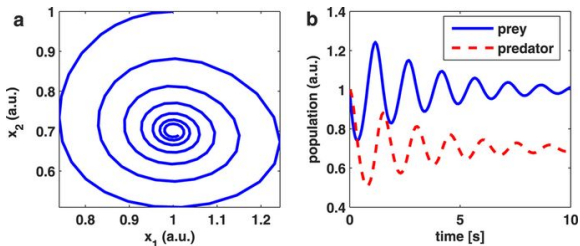
Travelling wave solutions propagating into unstable $N = 0$ state.

Generalised Lotka-Volterra model

Continuous, deterministic, well-mixed, multi-type.

$$\frac{dN_i}{dt} = N_i f_i(\mathbf{N}), \quad \mathbf{f} = \mathbf{r} + \mathbf{A}\mathbf{N}$$

N_i - size of population i , \mathbf{r} - growth rates, \mathbf{A} - community matrix



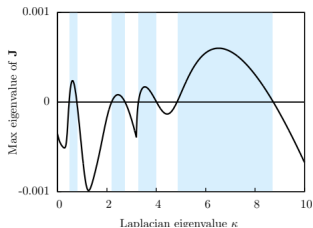
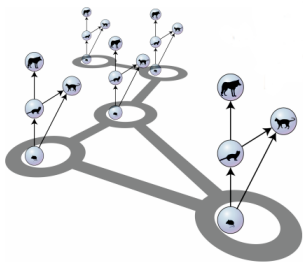
Point attractors, limit cycles, chaos, etc.

Metapopulation models

Continuous, deterministic, networked, multi-type.

$$\frac{d\mathbf{N}}{dt} = \mathbf{N} \circ (\mathbf{r} + \mathbf{A}\mathbf{N}) + D\Delta\mathbf{N},$$

Δ - graph Laplacian (transport matrix), \circ - Hadamard product



Stability depends on population-network interaction.

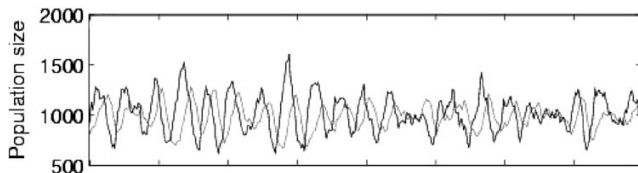
Stochastic Lotka Volterra models

Discrete, stochastic, well-mixed, multi-type.



$$\Rightarrow dN_i = N_i(r_i - d_i) dt + \sqrt{\frac{N_i(r_i + d_i)}{V}} dW_i.$$

X_i - type i , r_i - birth rate, $d_i(\mathbf{x})$ - death rate, V - volume



Quasicycles, extinction, etc.