

# Yet another Talk on Multilevel Monte Carlo Different I Promise!

**Robert Scheichl**

Department of Mathematical Sciences



Joint work over 8 years with a large number of collaborators, including  
G Detommaso, I Graham, E Müller, M Parkinson & T Shardlow (all Bath);  
J Charrier (Marseille); A Cliffe †; T Dodwell (Exeter); M Giles (Oxford);  
A Teckentrup (Edinburgh); E Ullmann (TUM)

**SAMBa Integrative Think Tank 6**

BRLSI, Bath, June 5th 2017

INPUT



MODEL

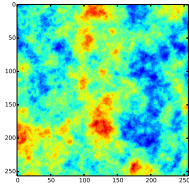


OUTPUT

INPUT

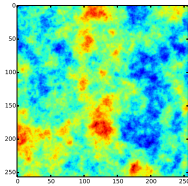
→ MODEL →

OUTPUT



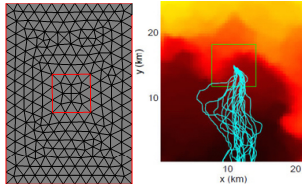
**Rock permeability**

INPUT



Rock permeability

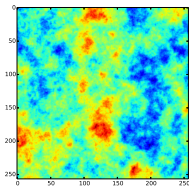
→ MODEL →



FE analysis of leaking waste

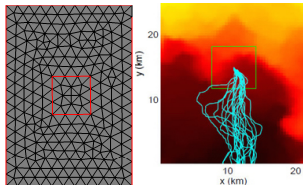
OUTPUT

INPUT



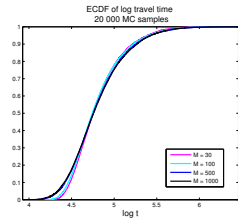
Rock permeability

→ MODEL →



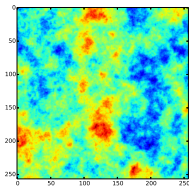
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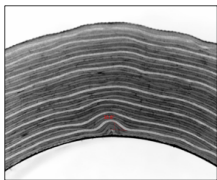


Radionuclides  
reaching drinkwater?

INPUT

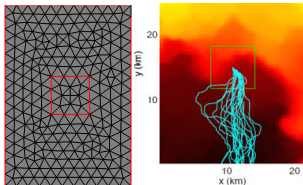


Rock permeability



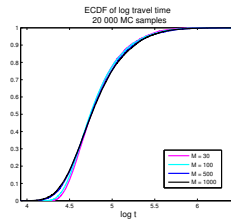
Composite material

→ MODEL →



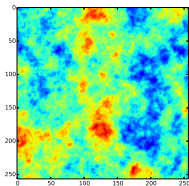
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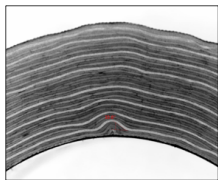


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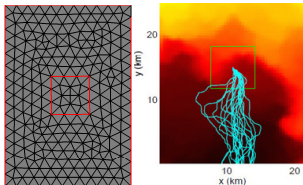


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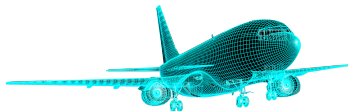


Composite material

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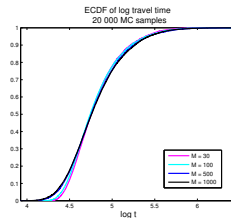


FE analysis of leaking waste



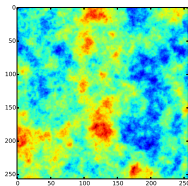
FE analysis of aircraft wing

OUTPUT

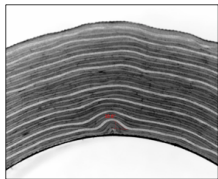


Radionuclides  
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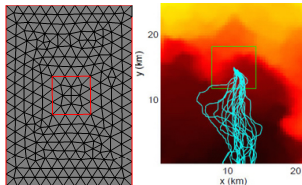


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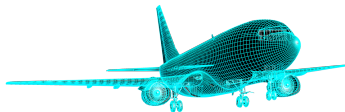


Composite material

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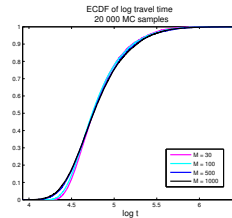


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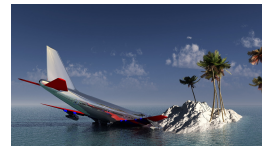


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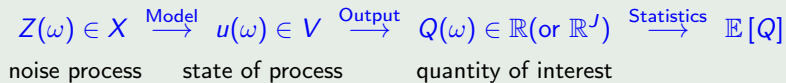
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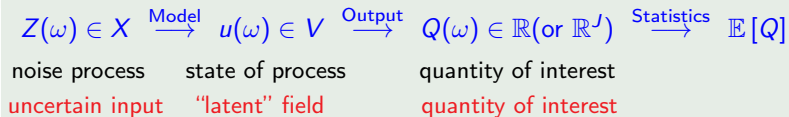
Wing failing?



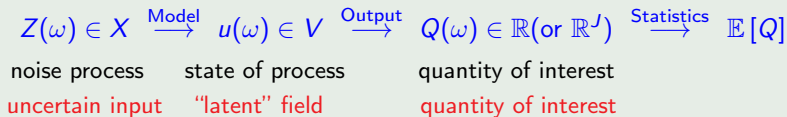
# Uncertainty Quantification / Stochastic Simulation



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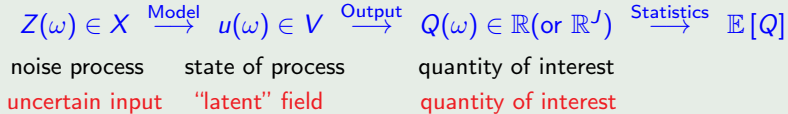


# Uncertainty Quantification / Stochastic Simulation



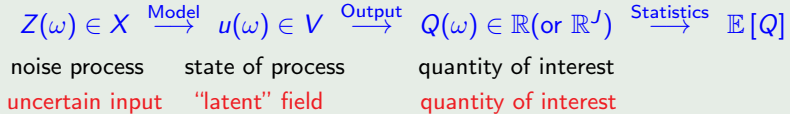
**SDE:**  $Z = Z_t$ , e.g. the driving Brownian (or Levy) process  $W_t$ ;  
 $u = u_t$ , unknown process (e.g. option price at time  $t$ );  
 $Q$  (non)linear functional of  $u_t$  (at end time  $T$  or along whole path)

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- UQ:**  $Z = Z(x)$  (or  $Z(x, t)$ ), spatial (or spatiotemporal) random field;  
 $u = u(x)$  (or  $u(x, t)$ ), model state (e.g. PDE solution);  
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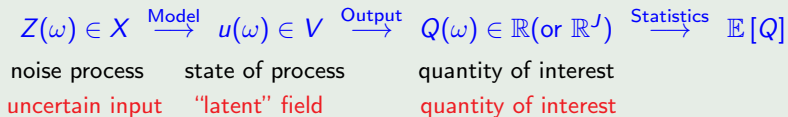


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Even though  $Q(\omega)$  may only be a **single random variable**. Its distribution is often **defined only implicitly** via the distributions of the **latent** fields  $u \in V$  and  $Z \in X$  which may be **infinite or high dimensional!**

# Practical Implementation: Discretisation / Approximation

$$Z_\ell(\omega) \in X_\ell \xrightarrow{\text{Model}^{(\ell)}} u_\ell(\omega) \in V_\ell \xrightarrow{\text{Output}} Q_\ell(\omega) \in \mathbb{R}(\text{or } \mathbb{R}^J) \xrightarrow{\text{Quadrature}} \hat{Q}_\ell$$

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**SDE:** Discretisation with step size  $h_\ell$

$Z_\ell = (\Delta W_{\ell,j})_{j=1}^{M_\ell}$  vector of Brownian increments;

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This provides us with a natural **model hierarchy** (parametrised by  $\ell$ ).

Assume, there exist  $\alpha > 0$  and  $\gamma > 0$  such that

$$\text{(A1)} \quad |\mathbb{E}[Q - Q_\ell]| = \mathcal{O}(2^{-\alpha\ell}) \quad \text{and} \quad \text{(A2)} \quad \mathbb{E}[\text{Cost}_\ell] = \mathcal{O}(2^{\gamma\ell})$$

where  $\text{Cost}_\ell$  is the cost to compute one realisation of  $Q_\ell$ .

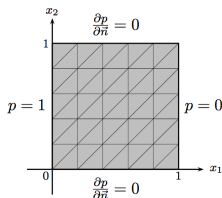
# Running Example (“Fruit fly” of UQ)

- Single-phase subsurface flow on unit square  $D$ :

$$-\nabla \cdot \left( e^{Z(\omega)} \nabla u(\omega) \right) = 0$$

subject to Neumann BC  $\nabla u \cdot \nu = 0$  (top & bottom)

& Dirichlet BC  $u = 1$  (left) and  $u = 0$  (right)

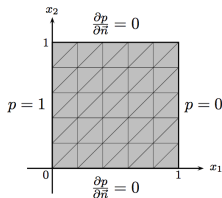


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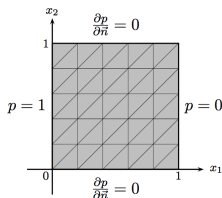
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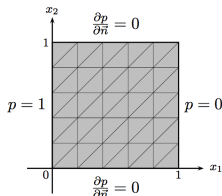
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- FE discretisation:  $u_\ell \in V_\ell \subset V$  (e.g. continuous p.w. linears w.r.t.  $\mathcal{T}_\ell$  with mesh size  $h_\ell = 2^{-\ell+1/2}$ ):

$$\int_D \nabla_{v_\ell} \cdot \left( e^{Z_\ell(\omega)} \nabla u_\ell(\omega) \right) = 0 \quad \forall v_\ell \in V_\ell \quad \Leftrightarrow \quad A_\ell(\omega) U_\ell(\omega) = b$$

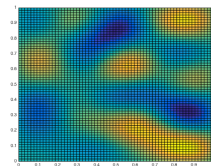
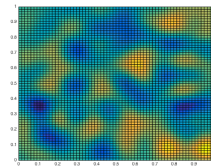
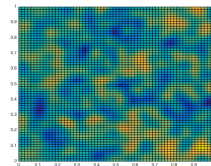
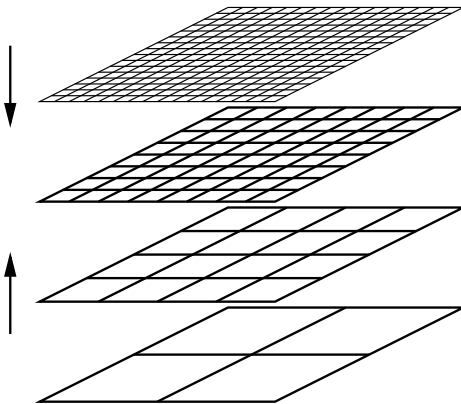
$M_\ell \times M_\ell$  random lin. sys.

# Running Example – Model Hierarchy

$L$

$V_\ell$

$X_\ell$



$0$

Here  $\alpha \approx 1$  (smooth functionals) and  $\gamma \approx 2$  (with AMG)



- The **standard Monte Carlo** estimator for  $\mathbb{E}[Q]$  is

$$\hat{Q}_L^{\text{MC}} := \frac{1}{N} \sum_{i=1}^N Q_L^{(i)}, \quad Q_L^{(i)} \text{ i.i.d. samples with Model}(L)$$

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- Convergence of plain vanilla MC (**mean square error**):

$$\underbrace{\mathbb{E}[(\hat{Q}_L^{\text{MC}} - \mathbb{E}[Q])^2]}_{=: \text{MSE}} = \underbrace{\frac{\mathbb{V}[Q_L]}{N}}_{\text{sampling error}} + \underbrace{(\mathbb{E}[Q_L - Q])^2}_{\text{model error ("bias")}}$$

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For **fruit fly**:  $\text{Cost}(\hat{Q}_L^{\text{MC}}) \approx \mathcal{O}(\varepsilon^{-4})$  **Prohibitively expensive!**

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Assume approximation error  $\mathcal{O}(2^{-\alpha\ell})$ , Cost/sample  $\mathcal{O}(2^{\gamma\ell})$  and

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Then there exist  $L$ ,  $\{N_\ell\}_{\ell=0}^L$  to obtain  $\text{MSE} = \mathcal{O}(\varepsilon^2)$  with

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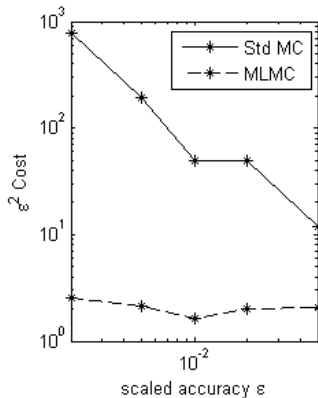
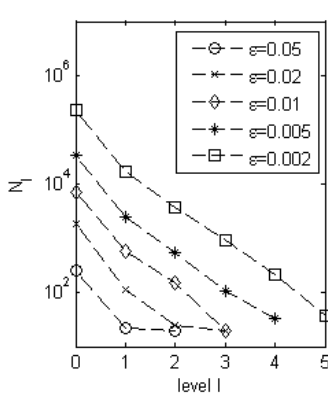
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**Optimality:** Asymptotic cost of one deterministic solve (to tol =  $\varepsilon$ ) !

# Numerical Example (Multilevel MC)

Fruit fly with  $Q = \|u\|_{L_2(D)}$  & circulant embedding with  $s_\ell = \mathcal{O}(M_\ell)$



$$\sigma^2 = 1, \quad \lambda = 0.3, \quad h_0 = \frac{1}{8}$$

# Observations, Extensions and Applications

- **Gains** even for small number of levels (**see below**).
- Substantial **practical gains** (not only asymptotic as  $\varepsilon \rightarrow 0$ )
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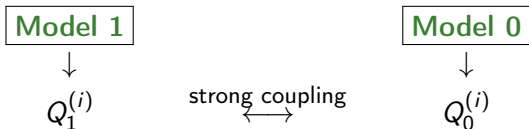
**Strong (sample-wise) coupling is key:**  $\mathbb{V}[Q_\ell - Q_{\ell-1}] \ll \mathbb{V}[Q_\ell]$

**Not always easy!!**

Refs.: [https://people.maths.ox.ac.uk/gilesm/mlmc\\_community.html](https://people.maths.ox.ac.uk/gilesm/mlmc_community.html)

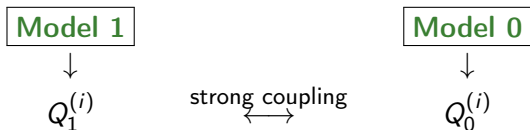
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(for simplicity consider only two levels)



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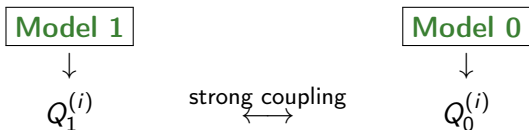


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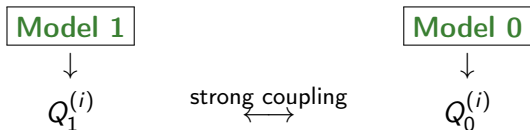
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$$\text{Gain} = \frac{\text{Cost}(\hat{Q}_1^{\text{MC}})}{\text{Cost}(\hat{Q}_1^{\text{MLMC}})} = \frac{1}{X + Y^2(1 + X)}$$

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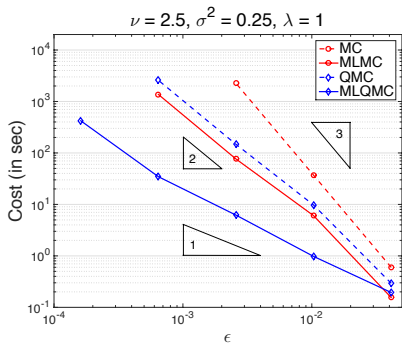
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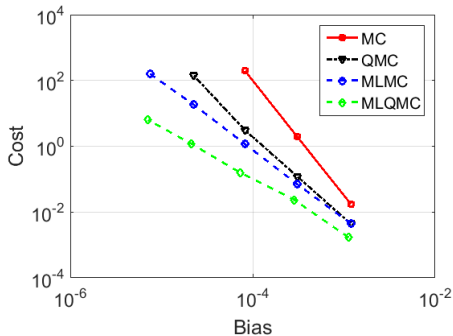
Examples / Gains	$X$	$Y = 0.5$	$Y = 0.1$	$Y = 0.05$
2D elliptic ( $h_0 = 2h_1$ )	1/4	1.8	3.8	4.0
3D elliptic ( $h_0 = 2h_1$ )	1/8	2.4	7.1	8.0
3D parab. ( $h_0 = 2h_1$ )	1/16	3.0	13.7	15.9
3D elliptic ( $h_0 = 4h_1$ )	1/64	3.7	38.8	62.4

Even higher gains with multiple levels!

# Numerical Evidence



Fruit fly (with Matern covariance)  
[Kuo, RS, Schwab, Sloan, Ullmann, '17]



Neutron transport (Boltzmann)  
[Graham, Parkinson, RS, '17(pre)]



$$Z(\omega) \in X \xrightarrow{\text{Model}} u(\omega) \in V \xrightarrow{\text{Output}} Q(\omega) \in \mathbb{R}(\text{or } \mathbb{R}^J) \xrightarrow{\text{Statistics}} \mathbb{E}_\pi[Q]$$

conditioned on data  $y^{\text{obs}}$  posterior expectation

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**Similar gains possible!** More difficult to achieve **both**  
**consistency** (collapsing sum) + **variance reduction** (strong coupling).

**Posterior distribution (Bayes):**

$$\pi^\ell(\mathbf{Z}_\ell | \mathbf{y}^{\text{obs}}) \approx \exp(-\|\mathbf{y}^{\text{obs}} - F_\ell(\mathbf{Z}_\ell)\|_{\Sigma^{\text{obs}}}^2) \pi_{\text{prior}}(\mathbf{Z}_\ell)$$

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$$\hat{Q}_{h,s}^{\text{MLMetH}} := \frac{1}{N_0} \sum_{n=1}^{N_0} Q_0(\mathbf{Z}_{0,0}^n) + \sum_{\ell=1}^L \frac{1}{N_\ell} \sum_{n=1}^{N_\ell} (Q_\ell(\mathbf{Z}_{\ell,\ell}^n) - Q_{\ell-1}(\mathbf{Z}_{\ell,\ell-1}^n))$$

**chains strongly coupled!**



# MLMCMC – Numerical Example

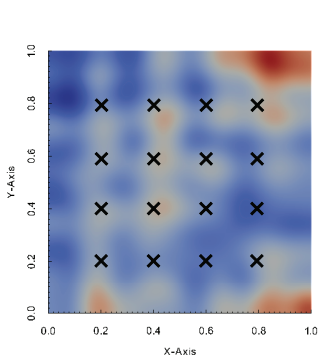
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- **Prior:** Separable exponential covariance with  $\sigma^2 = 1$ ,  $\lambda = 0.5$ .

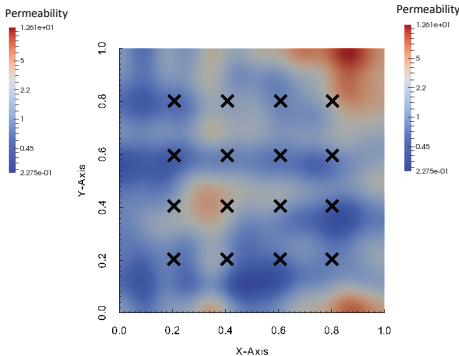
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- **“Data”**  $\mathbf{y}^{\text{obs}}$ : Pressure at 16 points  $\mathbf{x}_j^* \in D$  and  $\Sigma^{\text{obs}} = 10^{-4}I$ .



Data

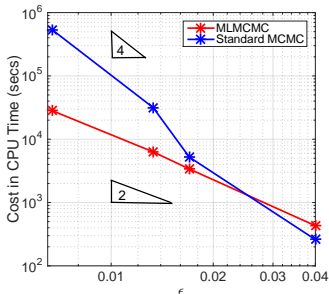
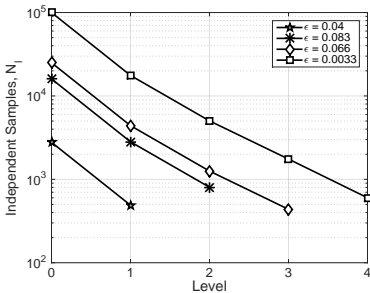


Posterior Sample

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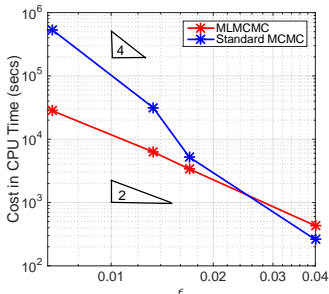
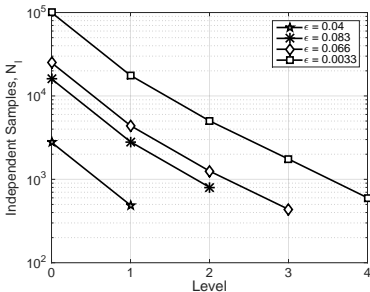
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- #independent samples =  $\frac{N_l}{t_l}$  (w.  $t_l \dots$  integrated autocorrelation time)

Level $l$	0	1	2	3	4
a.c. time $t_l$	136.23	3.66	2.93	1.46	1.23

# Overall Summary

- **Huge potential** for **multilevel Monte Carlo & model hierarchies** (in general) in stochastic simulation and in UQ
- A vibrant research area with **many open questions**
- A **“no-brainer”** in practice (if you have a model hierarchy)
- Many **new application areas** await exploration
- I believe, we have only **scratched the surface**, especially in context of **Bayesian inference & data assimilation**
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## Thank You !