Physical model for air quality prediction

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- distinguishes between vehicle emissions and city imissions
- allows vehicle management in real time and helps to direct local policy decisions

Use a physical model to predict pollutant concentrations and use data to calibrate the model

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- Advection Diffusion Equations

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$$\frac{\partial}{\partial x}(hu) + \frac{\partial}{\partial y}(hv) = 0$$

$$\downarrow$$

$$\frac{\partial}{\partial x}(h\varphi_x) + \frac{\partial}{\partial y}(h\varphi_y) = 0$$

Fluid model - Case 1

Topography:

$$h = c \cdot e^{-(x^2 + y^2)^2}$$

- $\bullet~61$ $\times~81$ grid
- Finite difference method
- Boundary condition: fixed $\mathbf{u} = (u, v)^T$

Advection - Diffusion

$$\frac{\partial C}{\partial t} + \mathbf{u} \cdot \nabla C = D \nabla^2 C + f$$

- $\bullet~61$ $\times~81$ grid
- Finite difference method
- Initial condition C_o
- Diffusion coefficient D = 0.1

Fluid model - Case 2

Invented some topography

- $\bullet~61$ $\times~81$ grid
- Finite difference method
- Boundary condition:
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- Use sensor data to adjust the model
- Inform us of the best places to introduce sensors