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1. Compute $U \cap W$:

$$U = \text{span} \{(1, 1, 1), (1, 2, 1)\} = \{(1, 1, 1), (0, 1, 0)\}$$

$$= \{(\lambda, \lambda + \mu, \lambda) \mid \lambda, \mu \in \mathbb{R}\}$$

$$W = \{(x, 0, y) \mid x, y \in \mathbb{R}\}$$

$$\circ \circ (\lambda, \lambda + \mu, \lambda) \in U \cap W \Leftrightarrow \lambda + \mu = 0$$

so of form $(\lambda, 0, \lambda)$.

$$\circ \circ \text{basis is } (1, 0, 1)$$

[2]

$$U + W = \mathbb{R}^3 \text{ else } U + W = U \quad \#$$

so any basis of \mathbb{R}^3 will do.

[2]

2. Sum $\ker \phi \oplus \text{im} \phi$ direct so

$$\dim \ker \phi \oplus \text{im} \phi = \text{rank } \phi + \text{nullity } \phi$$

$$= \dim V \text{ by rank-nullity}$$

$$\circ \circ \ker \phi \oplus \text{im} \phi = V.$$

[4]

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$$3. A = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 2 \\ 1 & 0 & 0 \end{pmatrix} \text{ so } A^2 = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 2 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 2 \\ 1 & 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 2 \\ 2 & 0 & 0 \\ 0 & 1 & 1 \end{pmatrix}$$

and (3,1) slot of $a_0 I_3 + a_1 A + A^2 = 0$ gives

$$0 = 1 \neq 0 \text{ so } \deg m_A > 2.$$

$$A^3 = \begin{pmatrix} 1 & 0 & 2 \\ 2 & 0 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 2 \\ 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 2 & 1 & 1 \\ 0 & 2 & 2 \\ 1 & 0 & 2 \end{pmatrix}$$

$$= 2I_3 + A$$

$$\therefore m_A = x^3 - x - 2$$

[4]



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4, $\deg \Delta \varphi = 6$ so $\dim V = 6$

max size of 3-Jordan block is 2

max size of 2-Jordan block is 1

so $G_{\varphi}(2) = E_{\varphi}(2)$ 2-dim

so ~~poss~~ while $\dim G_{\varphi}(3) = 4$

two possibilities:

$$\overline{J}(3, 2) \oplus \overline{J}(3, 2) \oplus \overline{J}(2, 1) \oplus \overline{J}(2, 1)$$

$$\overline{J}(3, 2) \oplus \overline{J}(3, 1) \oplus \overline{J}(3, 1) \oplus \overline{J}(2, 1) \oplus \overline{J}(2, 1)$$

[4]



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(a) let $v_1, v_2 \in \ker \phi|_{V_1} \oplus \ker \phi|_{V_2}$ so

$$\phi(v_1) = \phi(v_2) = 0 \quad \circ \quad \phi(v_1 + v_2) = 0 \quad \text{i.e.}$$

$v_1 + v_2 \in \ker \phi$. Conversely, if $v \in \ker \phi$
write $v = v_1 + v_2$ with $v_i \in V_i$

$$\begin{aligned} \text{then } 0 &= \phi(v) = \phi(v_1) + \phi(v_2) \quad \text{with } \phi(v_i) \in V_i \\ &= 0 + 0 \end{aligned}$$

$\circ \circ$ since $V_1 \oplus V_2$ is direct sum $\phi(v_i) = 0 \quad i=1,2$

$$\circ \quad v \in \ker \phi|_{V_1} \oplus \ker \phi|_{V_2}.$$

[6]

(b) (i) Define $\bar{\phi} : V/U \rightarrow V/U$ by

$$\bar{\phi}(q(v)) = q(\phi(v))$$

\circ well-defined: if $q(v) = q(v')$ then

$$v - v' \in \ker q = U \quad \circ \quad \phi(v - v') \in U$$

so $q(\phi(v - v')) = 0 \quad \circ \quad q(\phi(v)) = q(\phi(v'))$
by linearity of $q \circ \phi$.

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• $\bar{\varphi}$ linear:

$$\bar{\varphi}(q(v) + \lambda q(w)) \stackrel{\uparrow}{=} \bar{\varphi}(q(v + \lambda w))$$

$$\stackrel{\uparrow}{=} \underset{\text{def of } \bar{\varphi}}{q}(\varphi(v + \lambda w)) \stackrel{\uparrow}{=} \underset{q \text{ linear}}{q}(\varphi(v) + \lambda \varphi(w))$$

$$= \bar{\varphi}(q(v)) + \lambda \bar{\varphi}(q(w)) \checkmark$$

[6]

(C) It suffices to show that $u_1, \dots, u_k, v_1, \dots, v_{n-k}$ lin. indep since $\dim V = n$

$$\text{If } \lambda_1 u_1 + \dots + \lambda_k u_k + \mu_1 v_1 + \dots + \mu_{n-k} v_{n-k} = 0$$

take q of both sides

$$0 + \mu_1 q(v_1) + \dots + \mu_{n-k} q(v_{n-k}) = 0$$

$\Rightarrow \mu_i = 0 \ 1 \leq i \leq n-k$ since $q(v_i)$ lin. indep.

$$\therefore \lambda_1 u_1 + \dots + \lambda_k u_k = 0 \Rightarrow \lambda_j = 0 \ 1 \leq j \leq k$$

since the u_i lin. indep.

[6]



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<p>(a) Since $m_A \Delta_A$ either $m_A = (x-2)(x+1)$ or $m_A = (x-2)(x+1)^2$. Check $(x-2)(x+1)$:</p> $(A-2I) = \begin{pmatrix} -1 & -1 & 2 \\ -3 & -3 & -3 \\ 1 & 1 & -2 \end{pmatrix} \quad (A+I) = \begin{pmatrix} 2 & -1 & 2 \\ -3 & 0 & -3 \\ 1 & 1 & 1 \end{pmatrix}$ <p>$\circ \circ (A-2I)(A+I) = \begin{pmatrix} 3 & & \\ & * & \\ & & \end{pmatrix} \neq 0$</p> <p>$\circ \circ m_A = (x-2)(x+1)^2$ [5]</p>			
<p>(b) From m_A we see that \exists at least one $J(-1, 2)$ or $J(2, 1)$ $\circ \circ JNF = J(-1, 2) \oplus J(2, 1)$ [4]</p>			
<p>(c) For Jordan basis, first compute $G_A(-1) = \text{Ker}(A+I)^2$</p> $(A+I)^2 = \begin{pmatrix} 2 & -1 & 2 \\ -3 & 0 & -3 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & -1 & 2 \\ -3 & 0 & -3 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 9 & 0 & 9 \\ -9 & 0 & -9 \\ 0 & 0 & 0 \end{pmatrix}$ <p>$\text{Ker}(A+I)^2 = \{ (x, y, -x) \mid x, y \in \mathbb{R} \}$ $\text{Ker}(A+I) = \{ (x, y, -x) \mid 2x - y - 2x = 0 \text{ ie } y=0 \} = \text{span}\{(1, 0, -1)\}$</p>			
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<p>Now need $x \in \ker(A+I)^2$ s.t. $(A+I)x = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ or $x = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$ clearly works</p> <p>∴ Jordan basis of $\mathcal{G}_A(-1) = (1, 0, -1), (0, -1, 0)$</p> <p>Finally $x \in \ker(A-2I) \neq \emptyset$ $-x_1 - x_2 + 2x_3 = 0 \Rightarrow 3x_3 = 0$ $x_1 + x_2 + x_3 = 0 \Rightarrow x_3 = 0$ + then $x_1 = -x_2$ ∴ $(1, -1, 0)$ is basis.</p> <p>Thus Jordan basis is</p> <p>$(1, 0, -1), (0, -1, 0), (1, -1, 0)$.</p>			
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(a) (i) No: $\text{rank} = 4 + 2 = 6 > 5$ ✗ [2]

(ii) No: $p, q \geq 0$ being dimensions [2]

(iii) Yes: eg $q(x) = x_1^2 + x_2^2 - x_3^2$ [2]

(iv) Yes: eg $q(x) = x_1^2 + x_2^2 - x_3^2 - x_4^2 - x_5^2$ [2]

(b) Find a diag basis for A_t & use it as cols of P_t :

Exploit zero in (2,1) slot to see that e_1, e_2 are start of diag. basis, & So need $y = v_3$ s.t

$$\begin{pmatrix} 1 & 0 & 0 \end{pmatrix} A_t \underline{y} = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & t \\ -t & t & 0 \end{pmatrix} \underline{y} = \begin{pmatrix} 1 & 0 & -1 \end{pmatrix} \underline{y} \\ = y_1 - y_3 = 0$$

$$\begin{pmatrix} 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & t \\ -1 & t & 0 \end{pmatrix} \underline{y} = \begin{pmatrix} 0 & 2 & t \end{pmatrix} \underline{y} = 2y_2 + ty_3 = 0$$

∴ $v_3 = (2 - t \ 2)$ will do

∴ $P_t = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & -t \\ 0 & 0 & 2 \end{pmatrix}$ has $P_t^T A_t P_t$ diagonal. [10]