

M216: Exercise sheet 10

Warmup questions

- Show that the following are bilinear maps:
 - Matrix multiplication $M_{m \times n}(\mathbb{F}) \times M_{n \times p}(\mathbb{F}) \rightarrow M_{m \times p}(\mathbb{F})$.
 - Evaluation $(\phi, v) \mapsto \phi(v) : L(V, W) \times V \rightarrow W$.
 - For $\alpha \in V^*$ and $w \in W$, define $\phi_{\alpha, w} : V \rightarrow W$ by

$$\phi_{\alpha, w}(v) = \alpha(v)w.$$

- Show that each $\phi_{\alpha, w}$ is linear.
 - Show that the map $t : V^* \times W \rightarrow L(V, W)$ given by $t(\alpha, w) = \phi_{\alpha, w}$ is bilinear.
- Let $A, B \in M_{n \times n}(\mathbb{F})$ be congruent: $B = P^T A P$, for some $P \in \text{GL}(n, \mathbb{F})$. Are the following statements true or false?
 - $\det A = \det B$.
 - A is symmetric if and only if B is symmetric.

Exam-style questions

- Compute the rank and signature of the quadratic form $Q(x) = x_1 x_2 - 4x_3 x_4$ on \mathbb{R}^4 .
- Diagonalise the quadratic form Q on \mathbb{R}^3 given by $Q(x) = x_1^2 + 2x_1 x_2 + 2x_2^2 + 2x_2 x_3 + x_3^2$. Hence, or otherwise, compute the rank and signature of Q .
- (2015/6 Exam) Let $\phi_A : \mathbb{R}^4 \rightarrow \mathbb{R}^4$ be the linear map corresponding to the matrix

$$A = \begin{pmatrix} 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Diagonalise the quadratic form given by $Q(x) = \langle \phi_A(x), x \rangle$ and hence, or otherwise, compute its signature. [Here the inner product is dot product.]

Extra questions

- Let V be a real finite-dimensional inner product space. The inner product is a non-degenerate symmetric bilinear form and so defines an isomorphism $\beta : V \rightarrow V^*$ by

$$\beta(v)(w) = \langle v, w \rangle,$$

for all $v, w \in V$.

Let us show that β relates orthogonal complements and adjoints with solution sets, annihilators and transposes:

- Let $U \leq V$ and $E \leq V^*$. Prove that

$$\begin{aligned} \text{ann } U &= \beta(U^\perp) \\ \text{sol } E &= (\beta^{-1}(E))^\perp \end{aligned}$$

- Let $\phi \in L(V)$. Show that $\beta \circ \phi^* \circ \beta^{-1} = \phi^T$.

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M216: Exercise sheet 10—Solutions

1. (a) The bilinearity amounts to:

$$\begin{aligned} A(C + \lambda D) &= AC + \lambda AD \\ (A + \lambda B)C &= AC + \lambda BC, \end{aligned}$$

for all $A, B \in M_{m \times n}(\mathbb{F})$, $C, D \in M_{n \times p}(\mathbb{F})$ and $\lambda \in \mathbb{F}$. Both of these are easy to prove. For example,

$$\begin{aligned} (A(C + \lambda D))_{ij} &= \sum_{k=1}^n A_{ik}(C + \lambda D)_{kj} = \sum_{k=1}^n A_{ik}(C_{kj} + \lambda D_{kj}) \\ &= \sum_{k=1}^n (A_{ik}C_{kj} + \lambda A_{ik}D_{kj}) = (AC)_{ij} + \lambda(AD)_{ij} = (AC + \lambda AD)_{ij}. \end{aligned}$$

- (b) Here, bilinearity reads

$$\begin{aligned} (\phi_1 + \lambda\phi_2)(v) &= \phi_1(v) + \lambda\phi_2(v) \\ \phi(u + \lambda v) &= \phi(u) + \lambda\phi(v), \end{aligned}$$

for all $\phi, \phi_1, \phi_2 \in L(V, W)$, $u, v \in V$ and $\lambda \in \mathbb{F}$. But the first of these is simply the definition of the pointwise addition and scalar multiplication in $L(V, W)$ while the second is simply the assertion that ϕ is linear!

- (c) (i) This comes straight from the linearity of α : for $u, v \in V$ and $\lambda \in \mathbb{F}$,

$$\phi_{\alpha, w}(u + \lambda v) = \alpha(u + \lambda v)w = \alpha(u)w + \lambda\alpha(v)w = \phi_{\alpha, w}(u) + \lambda\phi_{\alpha, w}(v).$$

- (ii) Bilinearity of t amounts to:

$$\begin{aligned} \phi_{\alpha + \lambda\beta, w} &= \phi_{\alpha, w} + \lambda\phi_{\beta, w} \\ \phi_{\alpha, w_1 + \lambda w_2} &= \phi_{\alpha, w_1} + \lambda\phi_{\alpha, w_2}, \end{aligned}$$

for all $\alpha, \beta \in V^*$, $w, w_1, w_2 \in W$ and $\lambda \in \mathbb{F}$. Each is proved by showing that both sides take the same values on each $v \in V$. For example:

$$\begin{aligned} \phi_{\alpha + \lambda\beta, w}(v) &= (\alpha + \lambda\beta)(v)w = \alpha(v)w + \lambda\beta(v)w \\ &= \phi_{\alpha, w}(v) + \lambda\phi_{\beta, w}(v) = (\phi_{\alpha, w} + \lambda\phi_{\beta, w})(v) \end{aligned}$$

2. (a) This is false: let $P = \lambda I_n$, for $\lambda \in \mathbb{F}$. Then $B = \lambda^2 A$ so that $\det B = \lambda^{2n} \det A$.

- (b) This is true: if $A^T = A$ then

$$B^T = (P^T A P)^T = P^T A^T P = P^T A P = B.$$

Conversely, if $B^T = B$ we get $P^T A^T P = P^T A P$ and multiplying by P^{-1} on the right and $(P^T)^{-1}$ on the left gives $A^T = A$.

3. The fastest way to do this is to recall that $xy = \frac{1}{4}((x+y)^2 - (x-y)^2)$ so that

$$x_1 x_2 - 4x_3 x_4 = \frac{1}{4}(x_1 + x_2)^2 - \frac{1}{4}(x_1 - x_2)^2 - (x_3 + x_4)^2 + (x_3 - x_4)^2.$$

Moreover, the four linear functionals $x_1 \pm x_2, x_3 \pm x_4$ are linearly independent: one way to see this is that $x_1 \pm x_2 = 0 = x_3 \pm x_4$ forces each $x_i = 0$ so that Corollary 5.8 applies.

Now two squares appear positively and two negatively giving signature $(2, 2)$ and so rank 4.

4. Q has polarisation $B = B_A$ where

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

so that $B(x, y) = x_1y_1 + x_1y_2 + x_2y_1 + 2x_2y_2 + x_2y_3 + x_3y_2 + x_3y_3$.

There are several ways to get a diagonalising basis:

- (i) Compute eigenvectors of A : do whatever you have to do to see that A has eigenvalues 3, 1, 0 with eigenvectors $v_1 = (1, 2, 1)$, $v_2 = (1, 0, -1)$ and $v_3 = (1, -1, 1)$. This is a diagonalising basis with respect to which B has matrix

$$\begin{pmatrix} 18 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

The i -th diagonal term is the i -th eigenvalue times the norm-squared of v_i .

- (ii) Exploit the zero in the (1, 3) slot: note that

$$Q(e_1) = Q(e_3) = 1, \quad B(e_1, e_3) = 0$$

so that we just need to find y with

$$\begin{aligned} 0 &= B(e_1, y) = y_1 + y_2 \\ 0 &= B(e_3, y) = y_2 + y_3. \end{aligned}$$

Clearly $y = (1, -1, 1)$ does the job with $B(y, y) = 0$. Thus e_1, e_3, y are a diagonalising basis with matrix

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0. \end{pmatrix}$$

Either way, we see that the signature is (2, 0) and so the rank is 2.

We could see this also by writing Q directly as a sum of squares: notice that $Q(x) = (x_1 + x_2)^2 + (x_2 + x_3)^2$ and $x_1 + x_2, x_2 + x_3$ are linearly independent since they are not scalar multiples of each other..

5. First let us compute $Q(x) = 2x_1x_2 + x_1x_3 + x_2x_4 + 2x_3x_4$ with polarisation B whose matrix with respect to the standard basis is

$$\begin{pmatrix} 0 & 1 & \frac{1}{2} & 0 \\ 1 & 0 & 0 & \frac{1}{2} \\ \frac{1}{2} & 0 & 0 & 1 \\ 0 & \frac{1}{2} & 1 & 0 \end{pmatrix} = \frac{1}{2}(A + A^T).$$

Thus $B(x, y) = x_1y_2 + x_2y_1 + x_3y_4 + x_4y_3 + \frac{1}{2}(x_1y_3 + x_3y_1 + x_2y_4 + x_4y_2)$.

As usual, there are different ways to find a diagonalising basis:

- (i) Find eigenvectors of this symmetric matrix: you should get eigenvalues $\pm\frac{1}{2}, \pm\frac{3}{2}$ with eigenvectors forming a diagonalising basis

$$\begin{aligned} v_1 &= (1, 1, -1, -1) \\ v_2 &= (1, -1, 1, -1) \\ v_3 &= (1, 1, 1, 1) \\ v_4 &= (1, -1, -1, 1) \end{aligned}$$

with respect to which B has matrix

$$\begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & -6 \end{pmatrix}.$$

- (ii) Use a little ingenuity: observe that all those zeros tell us that, with $U = \text{span}\{e_1, e_4\}$ and $W = \text{span}\{e_2, e_3\}$, Q , and so B , vanishes on U and W . So, for any $u \in U$, $w \in W$,

$$Q(u+w) = 2B(u, w), \quad Q(u-w) = -2B(u, w), \quad B(u+w, u-w) = 0.$$

Inspired by this, set $v_1 = (1, 1, 0, 0) = e_1 + e_2$ and $v_2 = (1, -1, 0, 0)$ to get $Q(v_1) = 2 = -Q(v_2)$ and $B(v_1, v_2) = 0$. Now seek $y \in \mathbb{R}^4$ with

$$\begin{aligned} 0 &= B(v_1, y) = y_2 + y_1 + \frac{1}{2}(y_3 + y_4) \\ 0 &= B(v_2, y) = y_2 - y_1 + \frac{1}{2}(y_3 - y_4) \end{aligned}$$

One possibility is $y = (1, 1, -2, -2)$ with $Q(y) = 6$ so put $v_3 = y = (1, 1, 2, -2)$ and seek another y that additionally has $0 = B(v_3, y) = y_2 + y_1 - 2y_4 - 2y_3 + \frac{1}{2}(y_3 - 2y_1 + y_4 - 2y_2)$

$$0 = B(v_3, y) = y_2 + y_1 - 2y_4 - 2y_3 + \frac{1}{2}(y_3 - 2y_1 + y_4 - 2y_2) = -\frac{3}{2}(y_4 + y_3).$$

The solution is $y = (-1, 1, 2, -2)$ with $Q(y) = -14$. So put $v_4 = (-1, 1, 2, -2)$ to get a diagonalising basis with matrix

$$\begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & -14 \end{pmatrix}.$$

We can check our answer: let P have the v_j as columns and check that $P^T \frac{1}{2}(A + A^T)P$ is diagonal:

$$\begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 1 & 1 & -2 & -2 \\ -1 & 1 & 2 & -2 \end{pmatrix} \begin{pmatrix} 0 & 1 & \frac{1}{2} & 0 \\ 1 & 0 & 0 & \frac{1}{2} \\ \frac{1}{2} & 0 & 0 & 1 \\ 0 & \frac{1}{2} & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 & -1 \\ 1 & -1 & 1 & 1 \\ 0 & 0 & -2 & 2 \\ 0 & 0 & -2 & -2 \end{pmatrix} = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & -14 \end{pmatrix}$$

Whatever diagonalising basis we find, we see that Q has signature $(2, 2)$ and so rank 4.

6. (a) Let $\alpha \in V^*$. Then $\alpha = \beta(w)$, for some $w \in V$, and $\alpha \in \text{ann } U$ if and only if $\alpha(u) = 0$, for all $u \in U$, if and only if $\beta(w)(u) = 0$, for all $u \in U$, or, equivalently, $\langle w, u \rangle = 0$, for all $u \in U$, that is $w \in U^\perp$.

Let $v \in V$. For $\alpha \in V^*$, note that $\langle \beta^{-1}(\alpha), v \rangle = \beta(\beta^{-1}(\alpha))(v) = \alpha(v)$. Thus $v \in (\beta^{-1}(E))^\perp$ if and only if $\alpha(v) = \langle \beta^{-1}(\alpha), v \rangle = 0$, for all $\alpha \in E$, that is, $v \in \text{sol } E$.

- (b) We prove that $\beta \circ \phi^* = \phi^T \circ \beta$. So let $v \in V$. We want to show that

$$\beta(\phi^*(v)) = \phi^T(\beta(v)),$$

or, equivalently, for all $w \in V$,

$$\beta(\phi^*(v))(w) = \phi^T(\beta(v))(w).$$

However, the left hand side of this is

$$\langle \phi^*(v), w \rangle = \langle v, \phi(w) \rangle = \beta(v)(\phi(w)) = (\beta(v) \circ \phi)(w) = (\phi^T(\beta(v)))(w),$$

as required.

Note that, in all of this, the only place where we used that V was finite-dimensional was to know that β was an isomorphism. Thus our arguments apply in infinite-dimensional settings (such as Hilbert spaces) where β is also an isomorphism.