

High speed rotor noise

Michael Carley

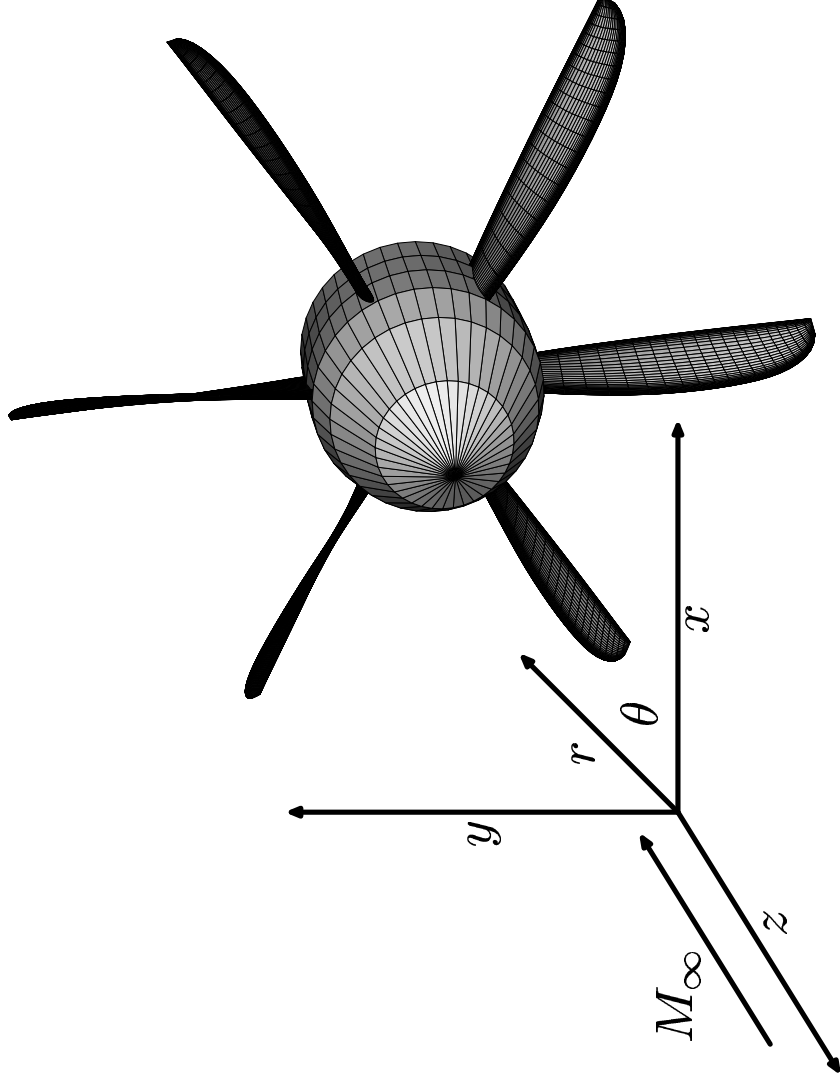
Being to treat of the Doctrine of Sounds, I hold it convenient to premise something in the general concerning this Theory; which may serve at once to engage your attention, and excuse my pains, when I shall have recommended them, as bestow'd on a subject not altogether useless and unfruitful.

- CARLEY, M. 1999, Sound radiation from propellers in forward flight, *Journal of Sound and Vibration* **225**(2):353–374.
- CARLEY, M. 2000, Propeller noise fields, *Journal of Sound and Vibration*, **233**(2):255–277.
- CARLEY, M. 2001, The structure of wobbling sound fields, to appear in *Journal of Sound and Vibration*.

Contents

- Propeller noise
- Stationary rotors:
 - acoustic integrals.
 - new computation method.
 - field structure: the acoustic orange.
- Translating propellers:
 - effect of forward flight.
 - conventional and advanced propellers.
- Rotors at incidence:
 - Green’s function expansion.
 - asymmetric field.

Basic problem



Given:

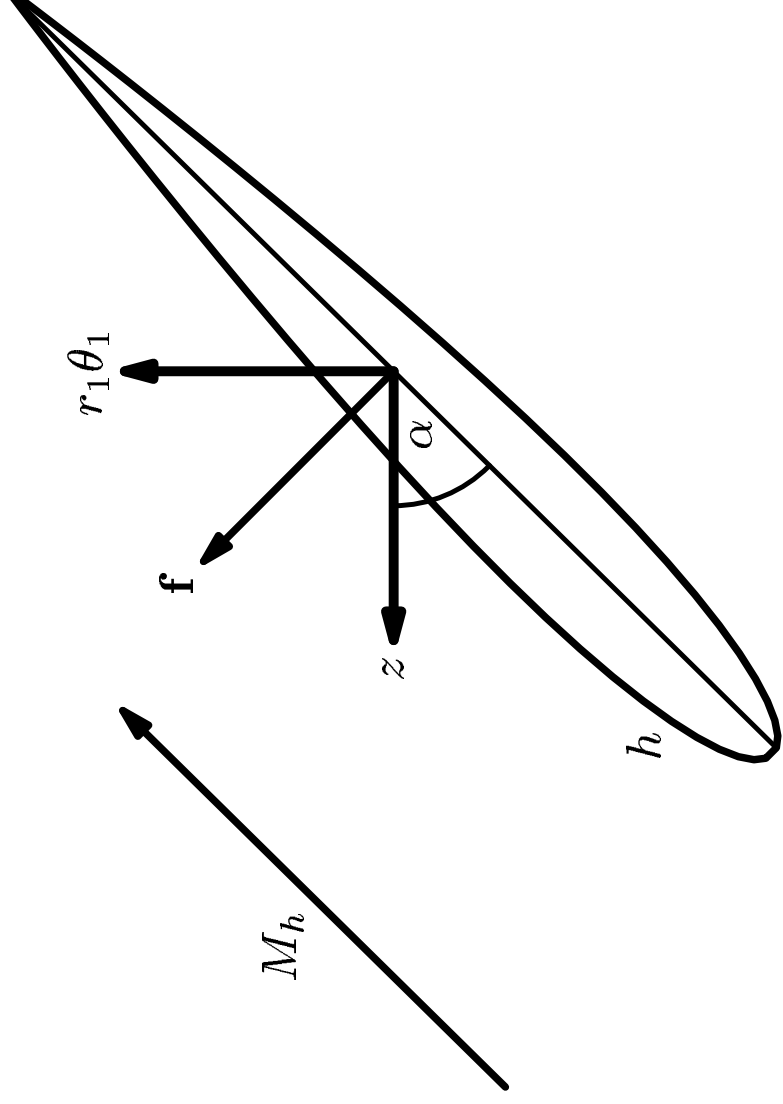
- geometry.
- loading.

Find:

- noise.

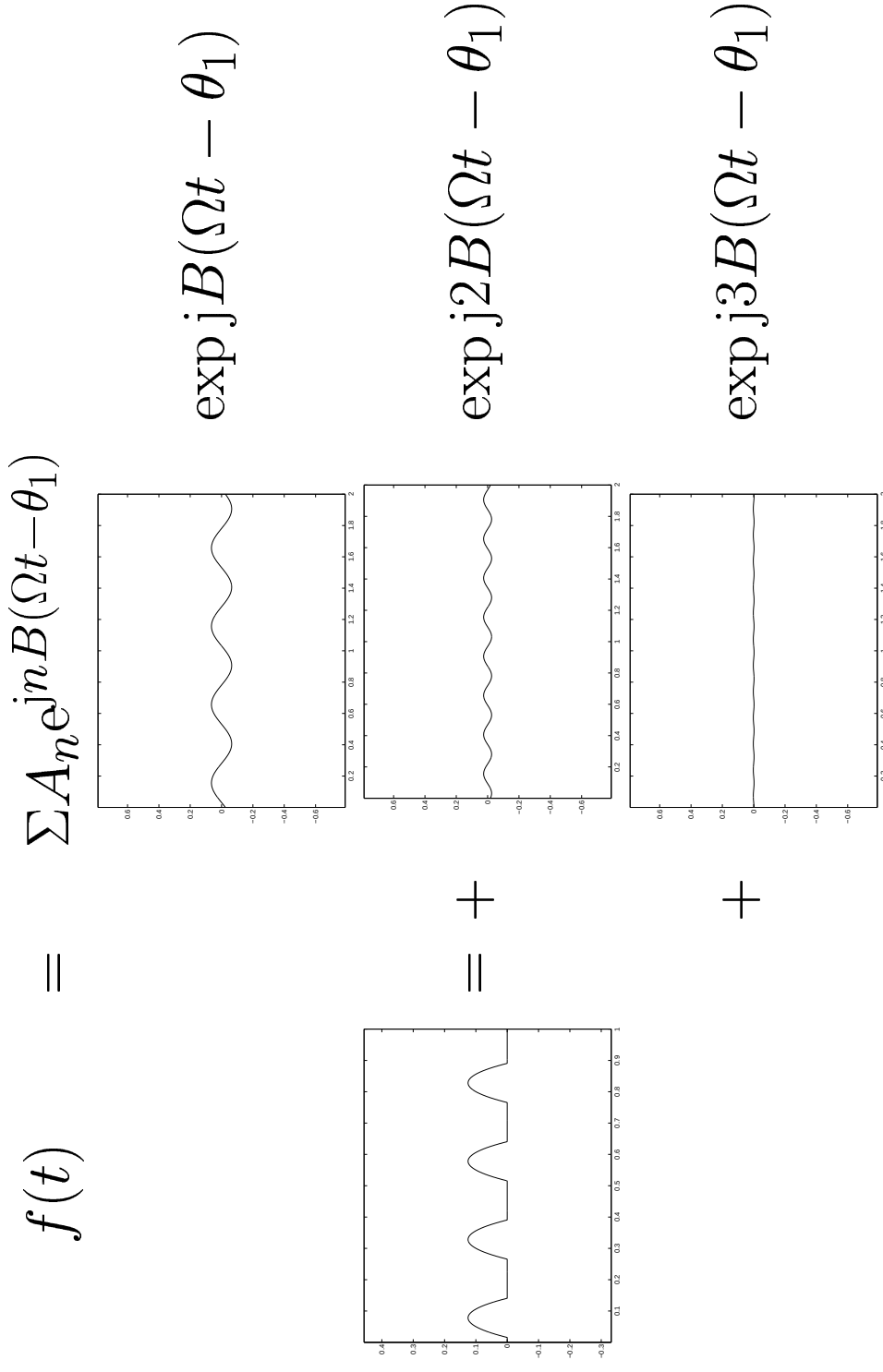


At a blade section



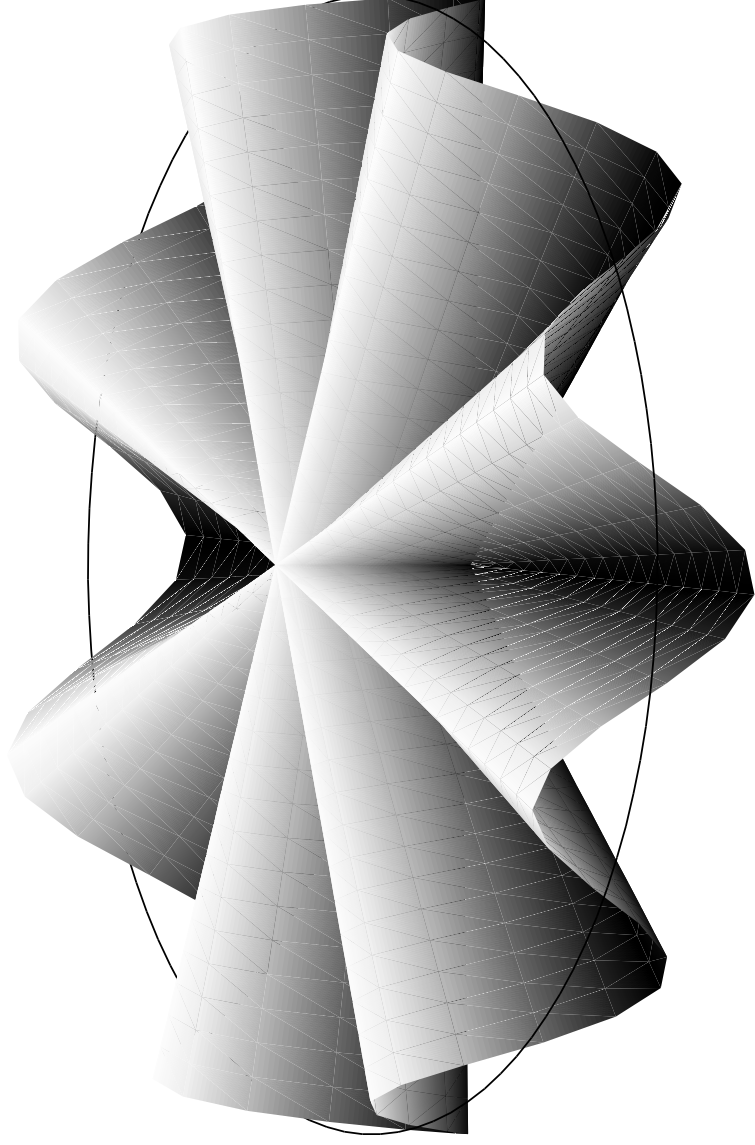
- Thickness noise: momentum injection at the surface: h , $\rho_0 v_n$.
- Loading noise: force on fluid at surface: $\mathbf{f}$.

Frequency domain decomposition



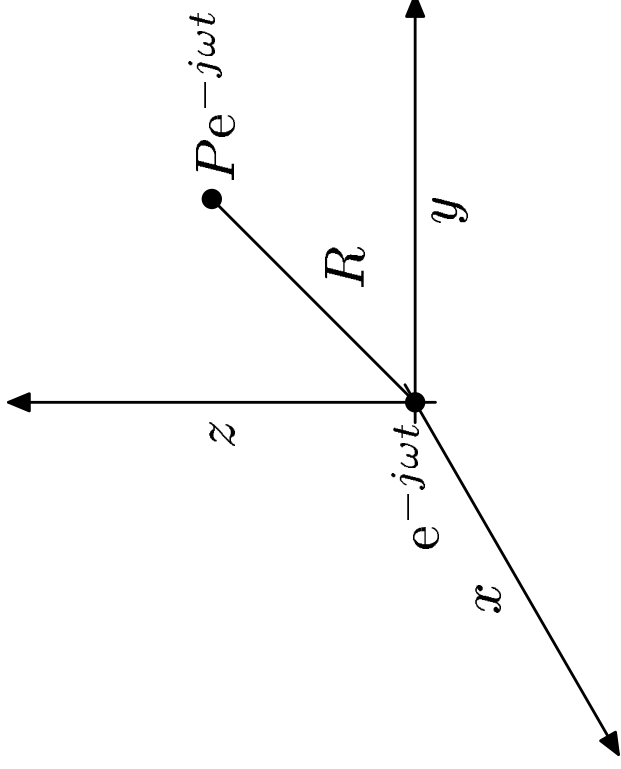
B : number of blades.

Calculate noise from a disc



Source term: $f_n(r_1)e^{-jnB(\Omega t + \theta_1)}$

Noise from a point source

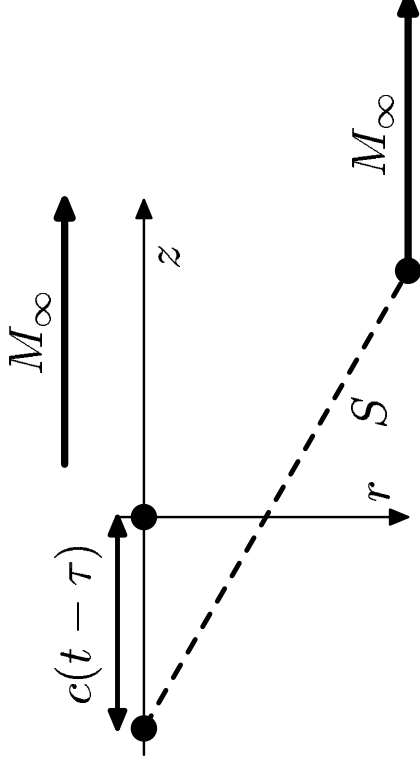


$$p(\mathbf{x}) = P e^{-j\omega t},$$

$$\tau = t - R/c, \quad (\text{retarded time})$$

$$P = \frac{e^{jkR}}{4\pi R}, \quad k = \omega/c.$$

Noise from a point source in motion



$$\tau = t - \sigma/c, \quad (\text{retarded time})$$

$$P = \frac{e^{ijk\sigma}}{4\pi S},$$

$$S = [\beta^2 r^2 + z^2]^{1/2}, \quad \sigma = (S + M_\infty z)/\beta^2,$$

$$\beta = (1 - M_\infty^2)^{1/2}.$$

Integral formula

Thickness noise:

$$\begin{aligned} p_{\text{T}} &= -jn\Omega\rho\frac{\text{D}}{\text{D}t}\int_0^a\int_0^{2\pi}\frac{\text{e}^{\text{j}(k\sigma-n\Omega t-n\theta_1)}}{4\pi S}h_n(r_1)r_1\text{d}\theta_1\text{d}r_1, \\ &= -n^2M_{\text{t}}^2\text{e}^{\text{j}n\theta}I(r,\theta,z,n,M_{\text{t}},M_{\infty}), \end{aligned}$$

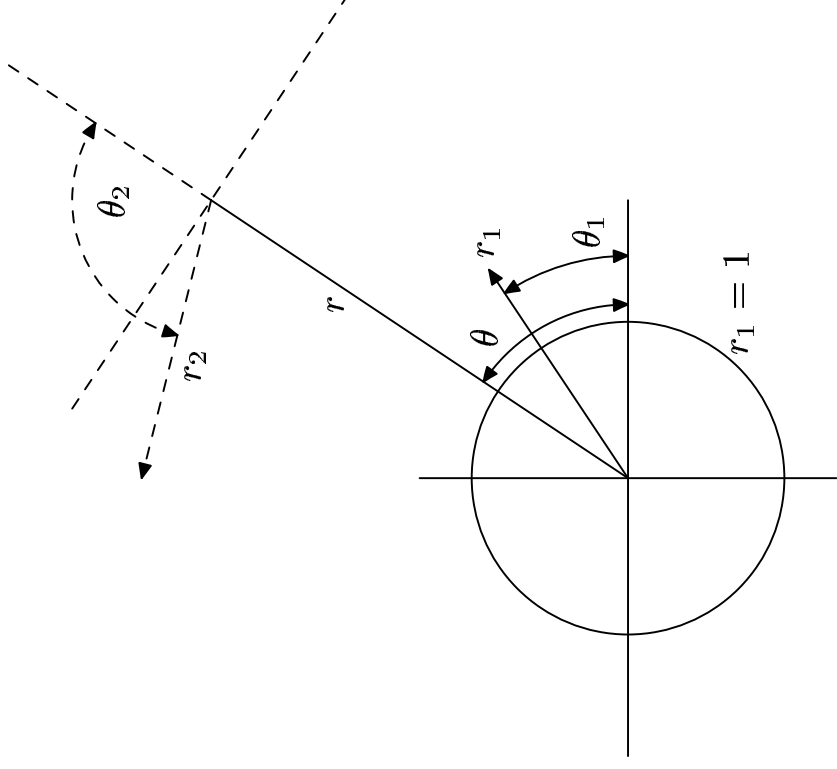
$$I = \int_0^{2\pi}\int_0^1h_n(r_1)\frac{\text{e}^{\text{j}(k\sigma-n\theta_1)}}{4\pi S^3}\left(S\sigma + \text{j}\frac{M_{\infty}z}{M_{\text{t}}n}\right)r_1\text{d}r_1\text{d}\theta_1$$

Computation

$$\begin{aligned} I &= \int_0^{2\pi} \int_0^1 \boxed{h_n(r_1) e^{-jn\theta_1}} \boxed{\frac{e^{jk\sigma}}{4\pi S^3} \left(S\sigma + j\frac{M_\infty z}{M_t n} \right)} r_1 dr_1 d\theta_1, \\ &= \iint \text{Source} \times \text{Propagation} d(\text{Area}). \end{aligned}$$

A two-dimensional integral of a highly oscillatory function: $n \simeq 6\text{--}60$.

Another view



Use coordinates centred on the sideline

F. Oberhettinger 1961, *J. Res. NBS*, **65B**:1–6.

Chapman, C. J. 1993, *Proc. R. Soc. Lond. A*, **440**:257–271.



New integrals

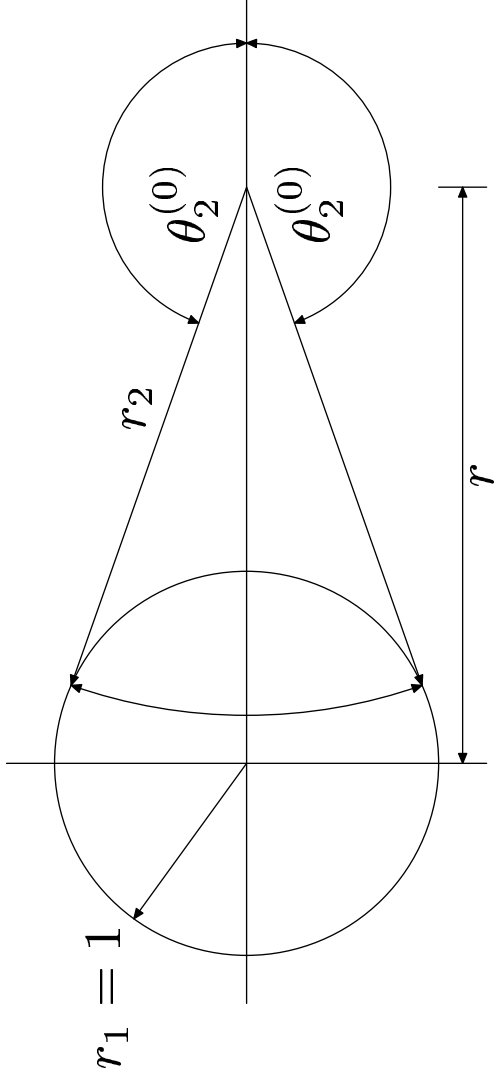
$$I = \int_{\max(0, r-1)}^{r+1} \frac{e^{j(k\sigma+n\theta)}}{S^3} \left(S\sigma + j \frac{M_\infty z}{M_t n} \right) J(r, r_2) r_2 \, dr_2,$$

$$J(r, r_2) = \frac{1}{2\pi} \int_{\theta_2^{(0)}}^{2\pi - \theta_2^{(0)}} e^{-jn\theta_1} \, d\theta_2$$

$$S = (\beta^2 r_2^2 + z^2)^{1/2}$$

Set $h_n \equiv 1$; switch coordinate systems; $J(r, r_2)$ does not depend on z .
 J can be found analytically, we only need a one-dimensional integral to calculate the noise.

Evaluation of J



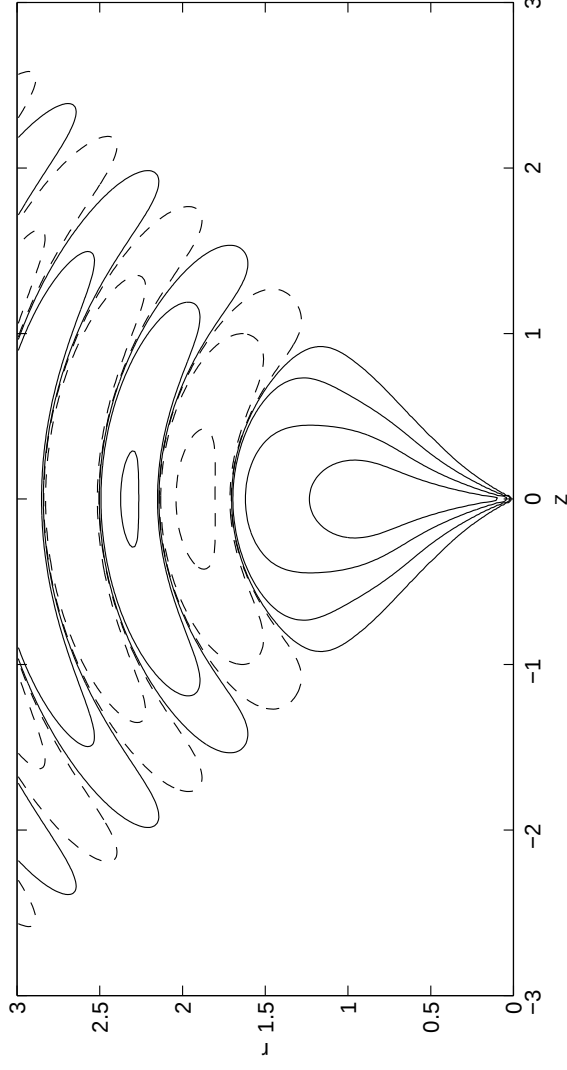
$$J(r, r_2) = \frac{1}{2\pi} \int_{\theta_2^{(0)}}^{2\pi - \theta_2^{(0)}} e^{-jn\theta_1} d\theta_2.$$

Evaluation of J

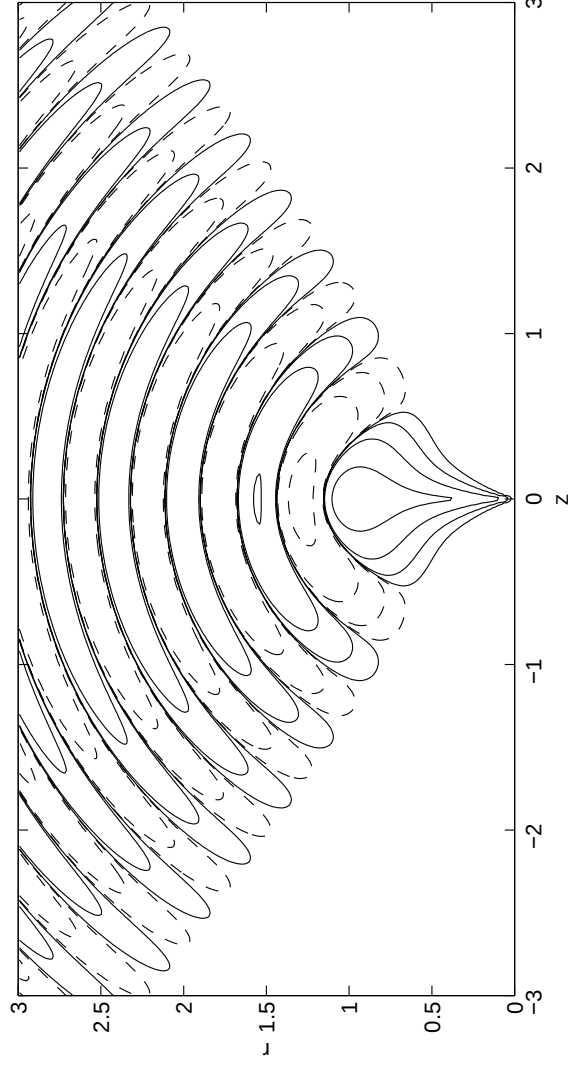
$$\begin{aligned}
 J_{2m} &= \frac{t^{-m}}{j2\pi} \int_{\mu_0}^{\mu_0^*} \frac{(\mu+t)^m}{(\mu+\eta)^m} \frac{1}{\mu^{m+1}} d\mu, \\
 &= -\frac{1}{\pi} \sum_{k=0}^m \binom{m}{k} (-t^2)^k \sum_{i=1}^{k+1} \binom{m+k-i}{m-1} (-t)^{1-i} \frac{\sin(1-i)\theta_2^{(0)}}{1-i} \\
 &\quad + \frac{1}{\pi} \sum_{k=0}^m \binom{m}{k} (-t^2)^k \sum_{i=1}^m \binom{m+k-i}{m-i} (1/r)^{1-i} \frac{\sin(1-i)\alpha}{1-i}.
 \end{aligned}$$

$$t = r_2/r, \eta = r/r_2, \mu_0 = \exp j\theta_2^{(0)}.$$

Thickness noise, $\theta = 0$



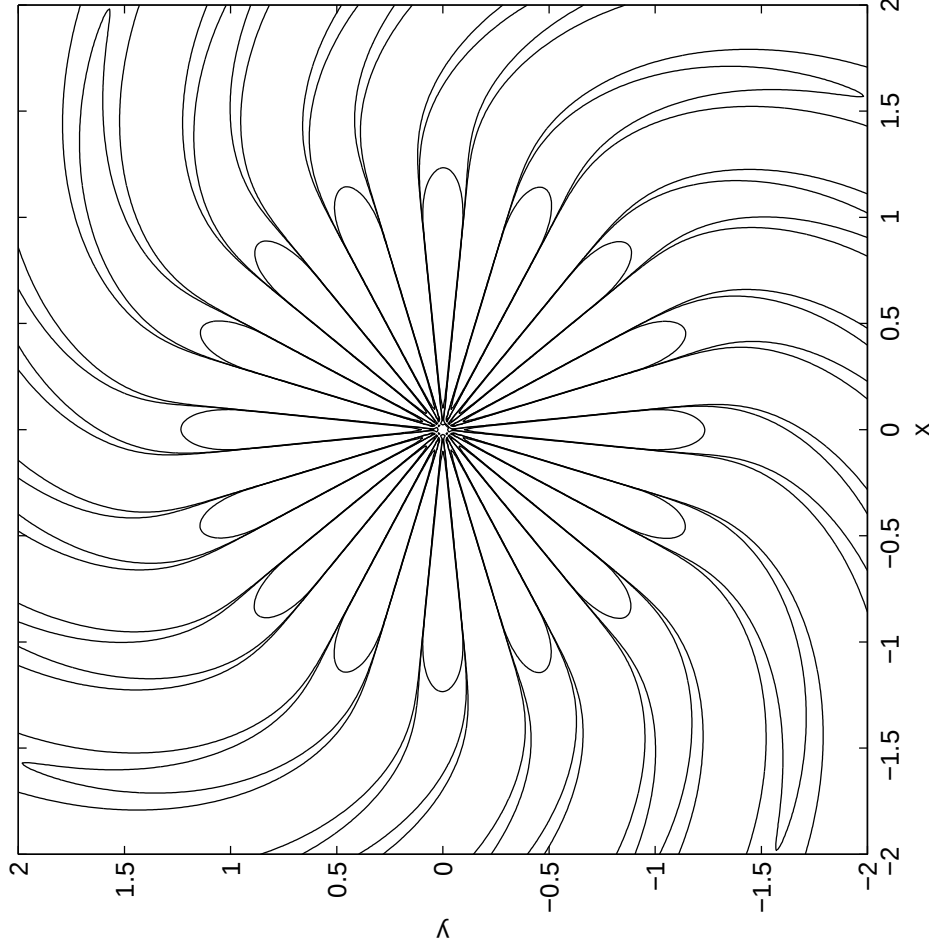
$$\begin{aligned} M_t &= 0.7 \\ M_\infty &= 0.0 \\ p &= \pm 10^{-6, -5, -4, -3}. \end{aligned}$$



$$\begin{aligned} M_t &= 1.05 \\ M_\infty &= 0.0 \\ p &= \pm 10^{-5, -4, -3, -2}. \end{aligned}$$

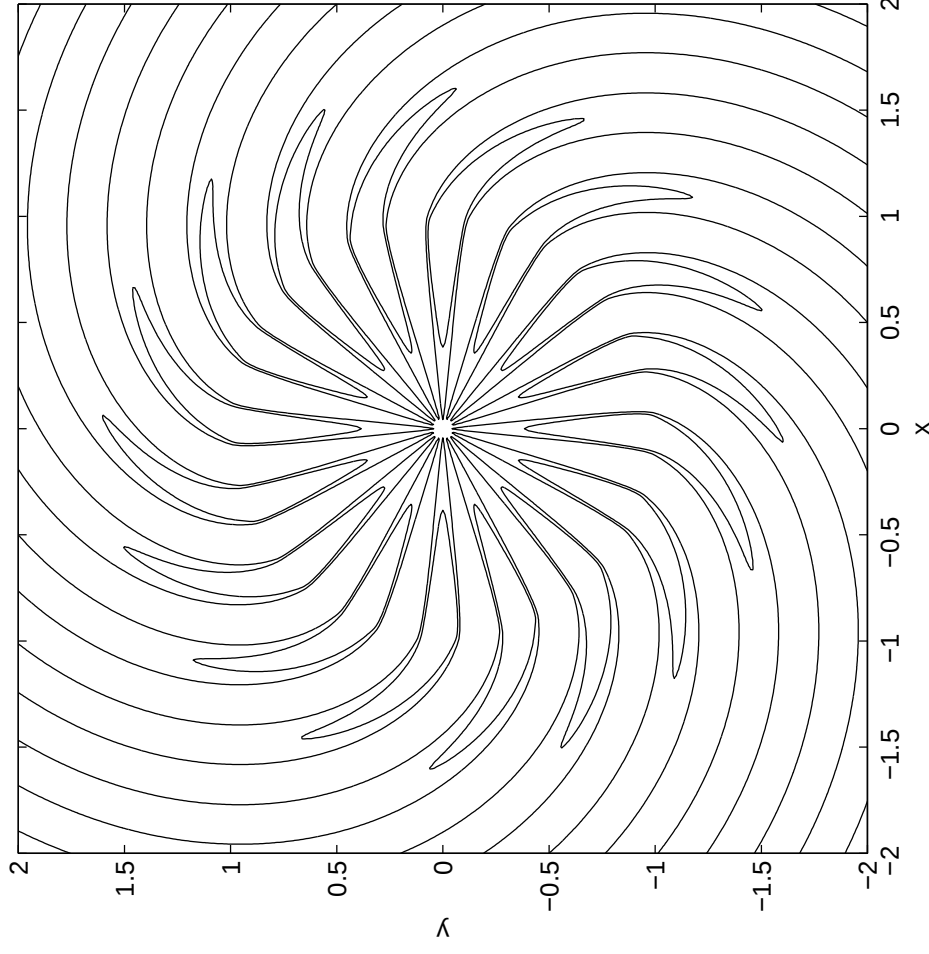


Thickness noise, $z = 0$



$$M_t = 0.7, M_\infty = 0.0$$

$$p = 10^{-5, -4, -3}$$



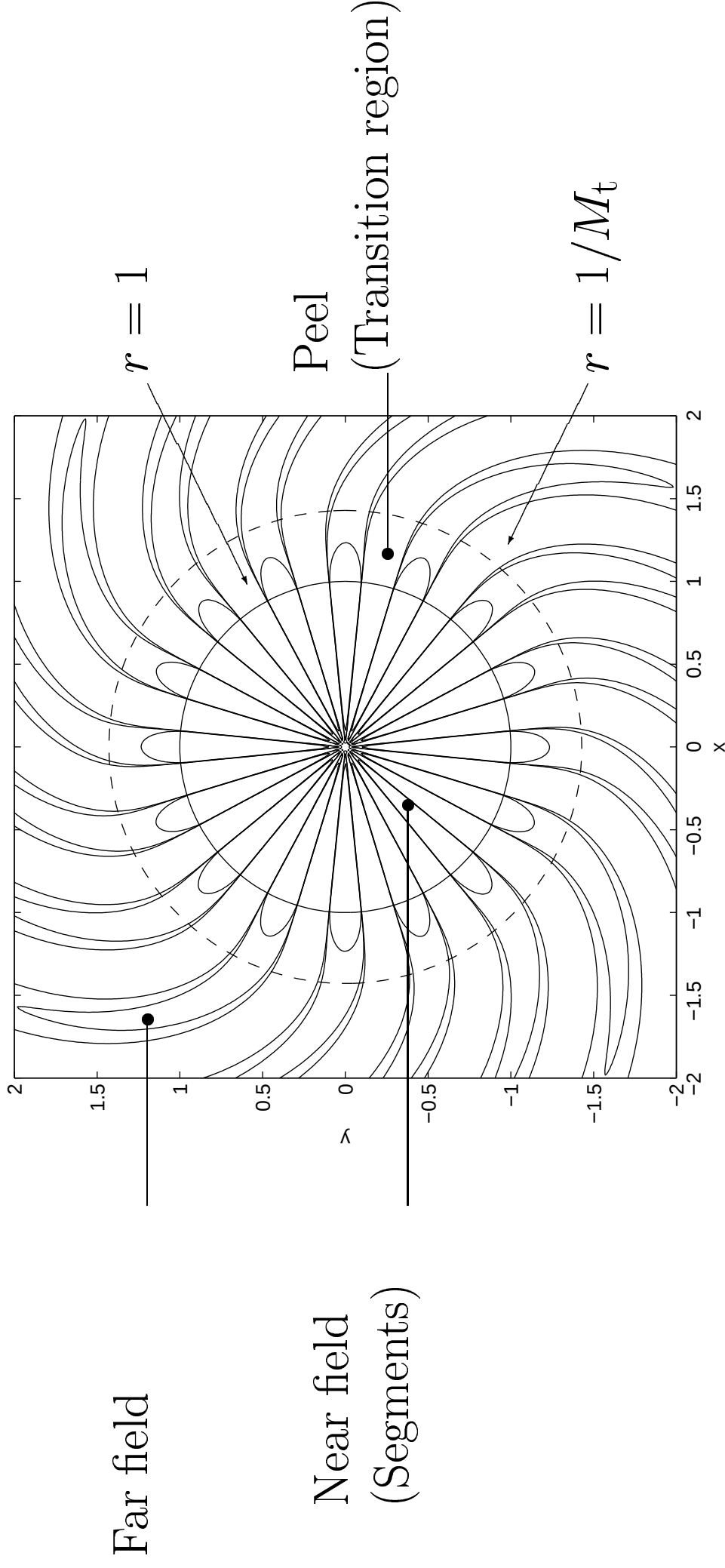
$$M_t = 1.05, M_\infty = 0.0$$

$$p = 10^{-4, -3, -2}$$

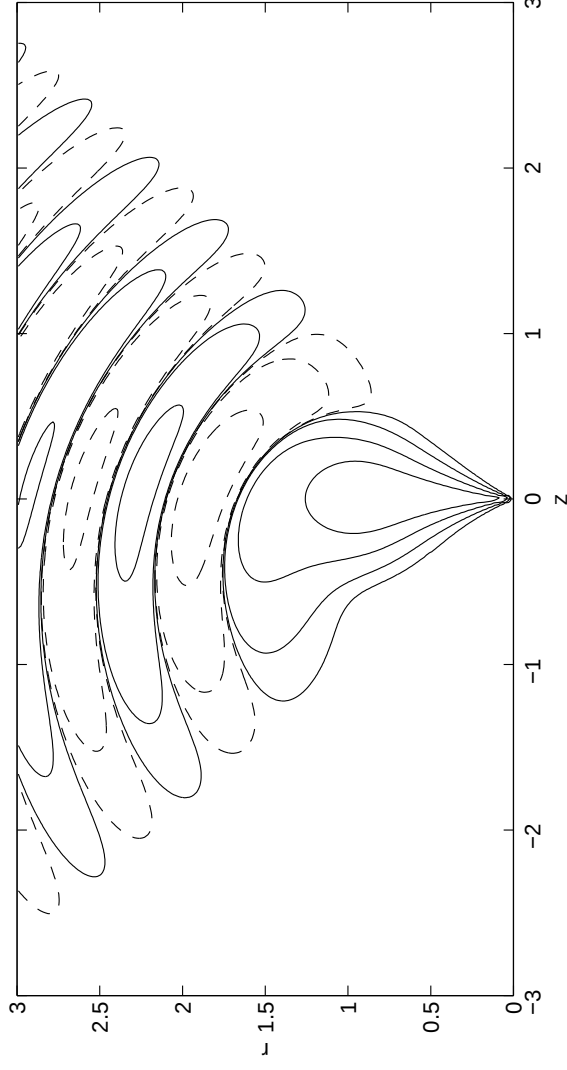


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The acoustic orange



Thickness noise, with flow, $\theta = 0$

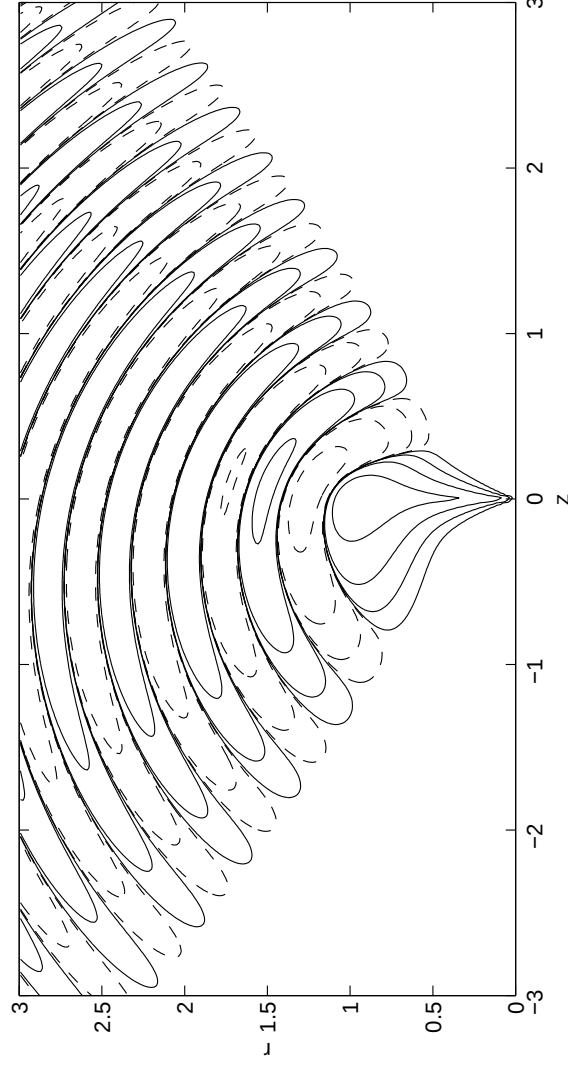


Conventional propeller
Takeoff/Landing

$$M_t = 0.7$$

$$M_\infty = 0.2$$

$$p = \pm 10^{-6, -5, -4, -3}$$



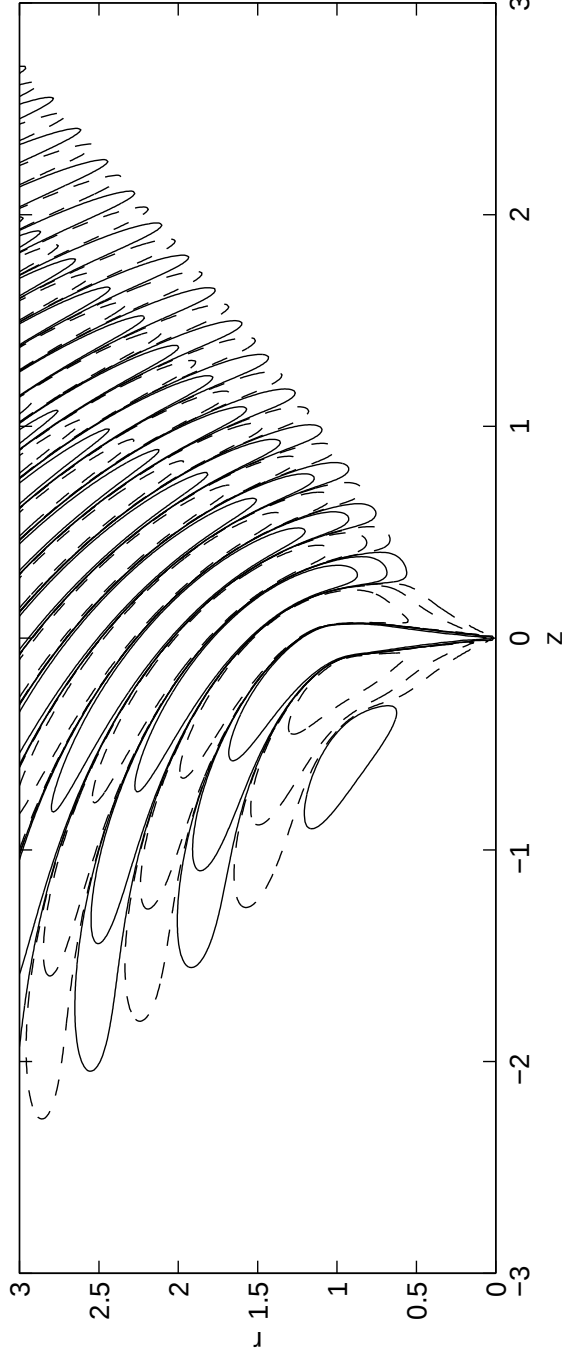
Advanced propeller
Takeoff/Landing

$$M_t = 1.05$$

$$M_\infty = 0.2$$

$$p = \pm 10^{-5, -4, -3, -2}$$

Thickness noise, with flow, $\theta = 0$



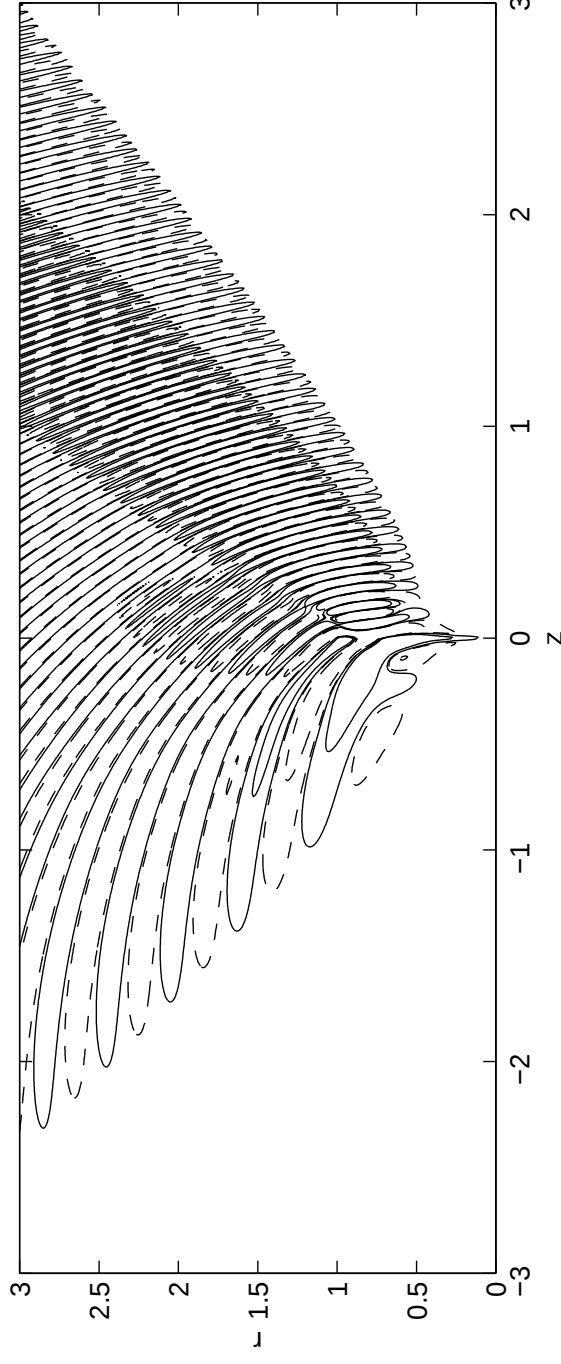
Conventional propeller

Cruise

$$M_t = 0.7$$

$$M_\infty = 0.7$$

$$p = \pm 10^{-6}, -5, -4, -3$$



Advanced propeller

Cruise

$$M_t = 1.05$$

$$M_\infty = 0.8$$

$$p = \pm 10^{-4}, -3, -2$$



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$$I_c(r_1) = \int_0^{r_1} \int_0^{2\pi} \frac{e^{j(k\sigma - n\theta_1)}}{4\pi S^3} \left(S\sigma + j \frac{M_\infty z}{M_t n} \right) d\theta_1 r'_1 dr'_1 \quad 0 \leq r_1 \leq 1.$$

differentiating and reinserting

$$\frac{dI_c}{dr_1} = \int_0^{2\pi} \frac{e^{j(k\sigma - n\theta_1)}}{4\pi S^3} \left(S\sigma + j \frac{M_\infty z}{M_t n} \right) d\theta_1 r_1,$$

integrating by parts

$$I = h_n(1)I_c(1) - h_n(r_0)I_c(r_0) - \int_{r_0}^1 \frac{dh_n}{dr_1} I_c(r_1) dr_1.$$

Propeller noise

Subsonic propeller noise is

- tip dominated;
- depends on ν with $s \sim S(1 - r_1)^\nu$ near the tip

Supersonic propeller noise is

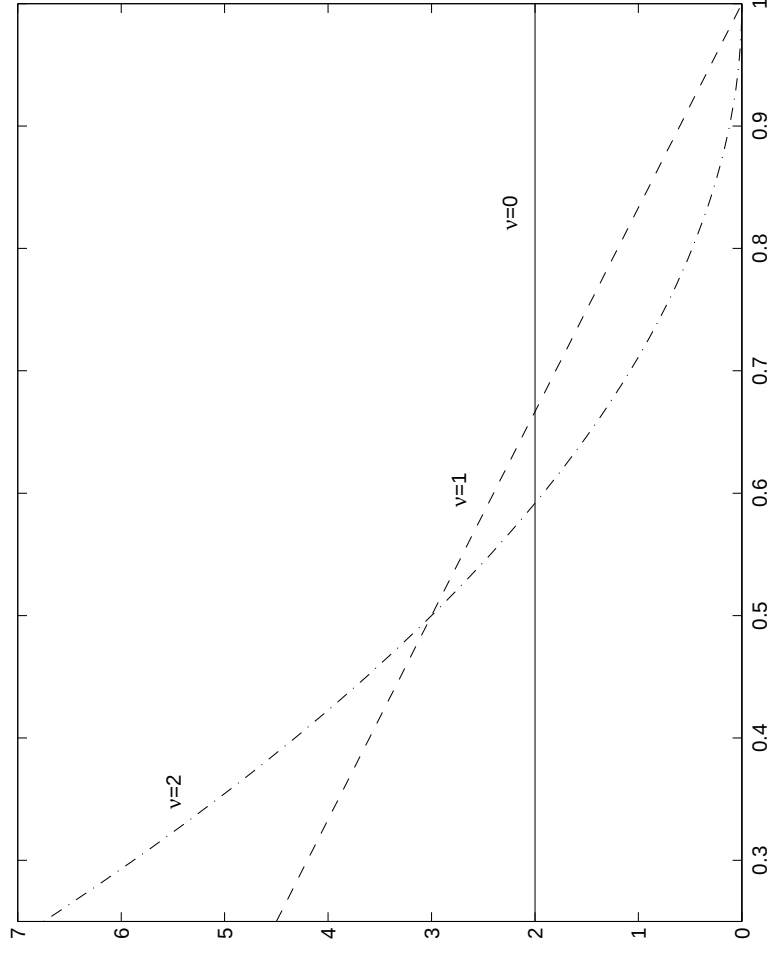
- Mach radius dominated;
- depends on source at Mach radius.

Parametric study

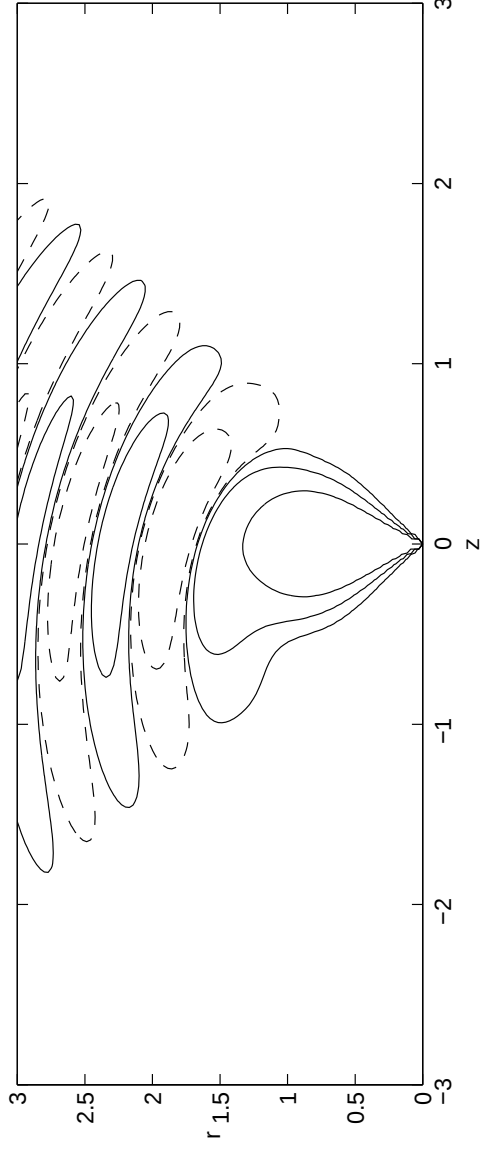
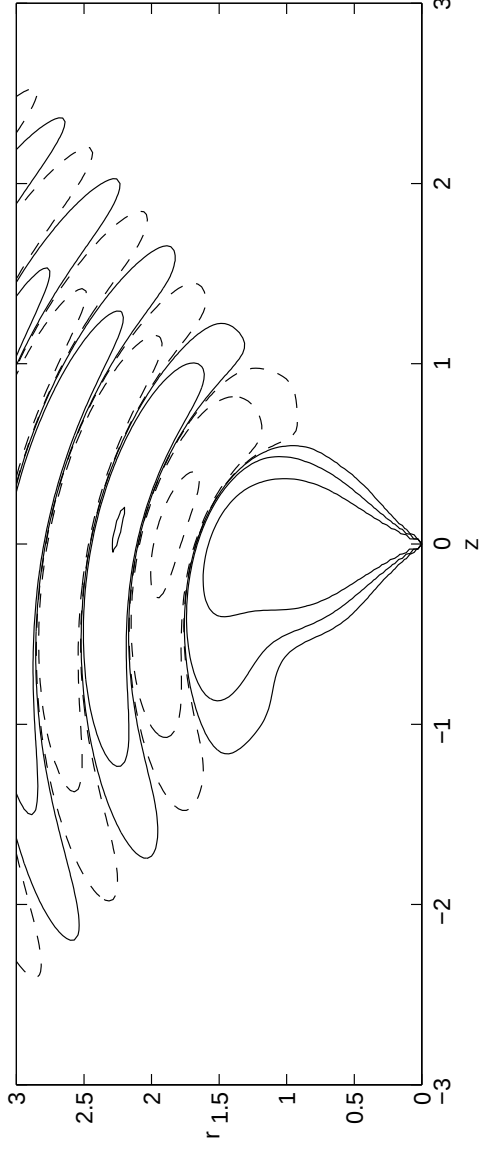
Set source

$$s = (\nu + 1)(\nu + 2)(1 - r_1)^\nu,$$

s is normalized to give a constant area-weighted source.



Thickness noise: $\nu = 1, 2, M_t = 0.7, M_\infty = 0.2$.



$$p = \pm 10^{-6, -5, -4}$$

Asymptotic theory

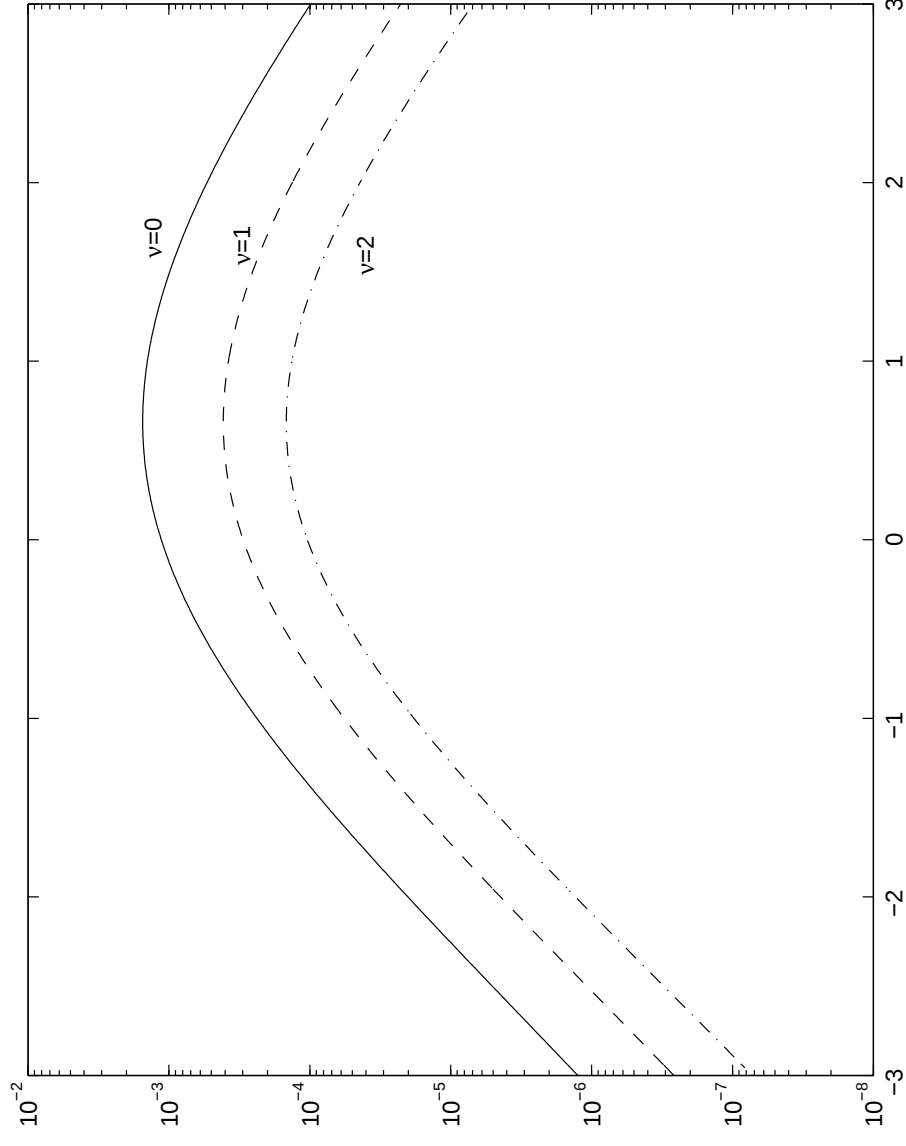
The asymptotic theory for the far-field amplitude predicts:

$$p_n \sim \frac{1}{1 - M_\infty \cos \phi} \frac{(\nu + 2)!}{(n \tanh \gamma)^{\nu+1} (n \tanh \gamma)^{1/2}} e^{n(\tanh \gamma - \gamma)},$$

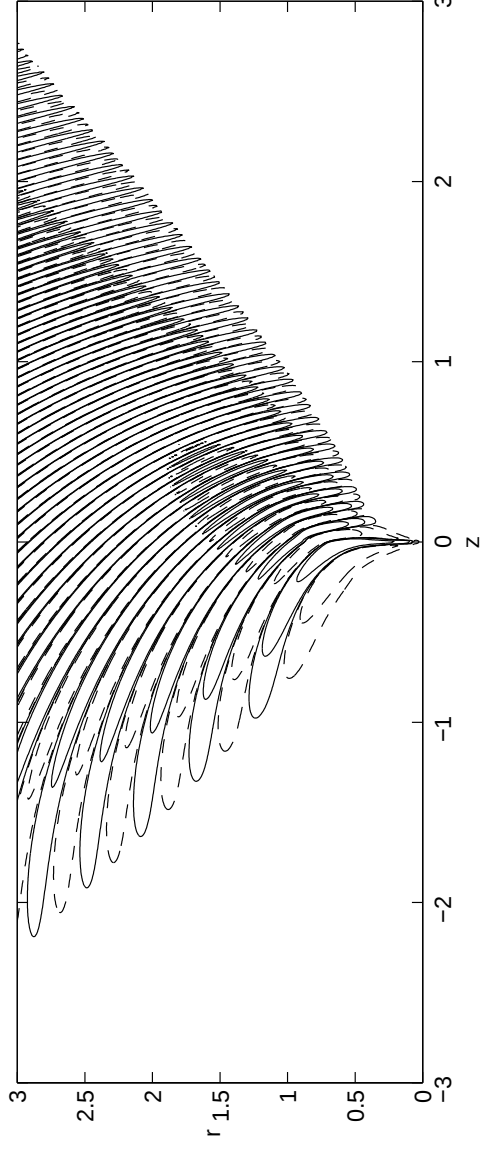
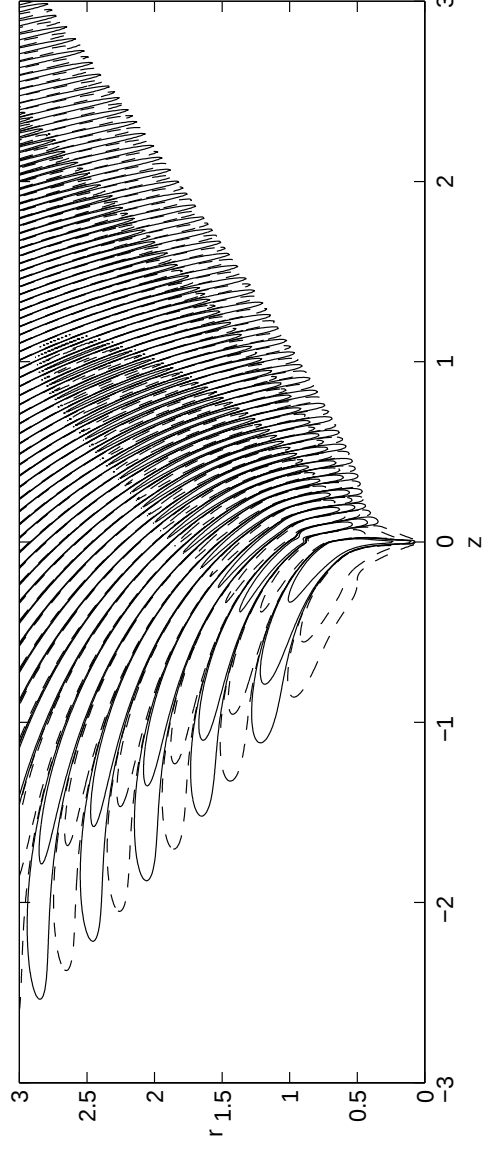
$$\text{where } \gamma = \operatorname{sech}^{-1} \left[\frac{M_t \sin \phi}{1 - M_\infty \cos \phi} \right],$$

$$\text{and } \phi = \tan^{-1} \frac{r}{z}.$$

On the outer sideline, $r = 3$:

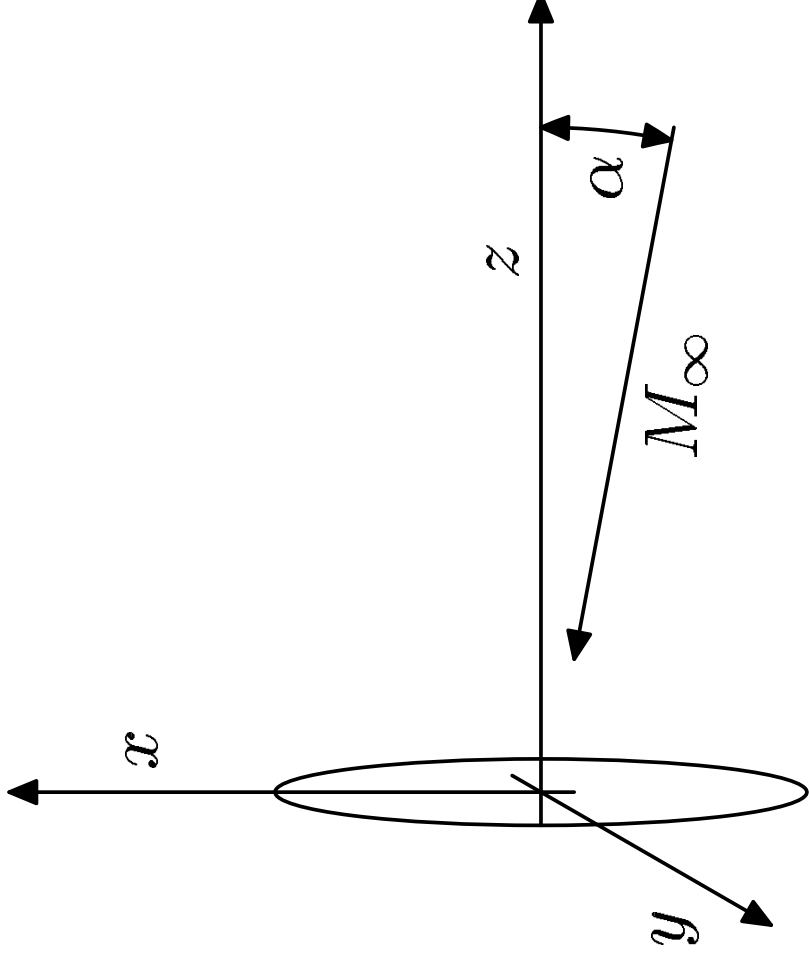


Thickness noise: $\nu = 1, 2, M_t = 1.05, M_\infty = 0.8$.



$$p = \pm 10^{-3}, -2, -1.$$

Incidence effects



Aerodynamics Unsteady loading and thickness terms.

Acoustics Asymmetric convection of sound.

At incidence

$$\begin{aligned}P &= \frac{e^{jk\sigma}}{4\pi S}, \\S &= [\beta^2 R^2 + (M_x r_2 \boxed{\cos(\theta + \theta_2)} + M_z z)^2]^{1/2}, \\ \sigma &= S + M_x r_2 \boxed{\cos(\theta + \theta_2)} + M_z z, \\ R^2 &= r_2^2 + z^2.\end{aligned}$$

Propagation is not axially symmetric.

Green's function expansion

$$\frac{e^{jkS}}{4\pi S} = \frac{e^{jkS_0}}{4\pi S_0} \sum_{p=-\infty}^{\infty} g_p e^{jp\theta_2},$$

$$\frac{e^{jk\sigma}}{4\pi S} \simeq \frac{e^{jk(S_0+M_z z)}}{4\pi S_0} \sum_{p=-P}^P \sum_{m=-M}^M j^m g_p J_m(kM_x r_2) e^{j(p+m)\theta} e^{j(p+m)\theta_2}$$

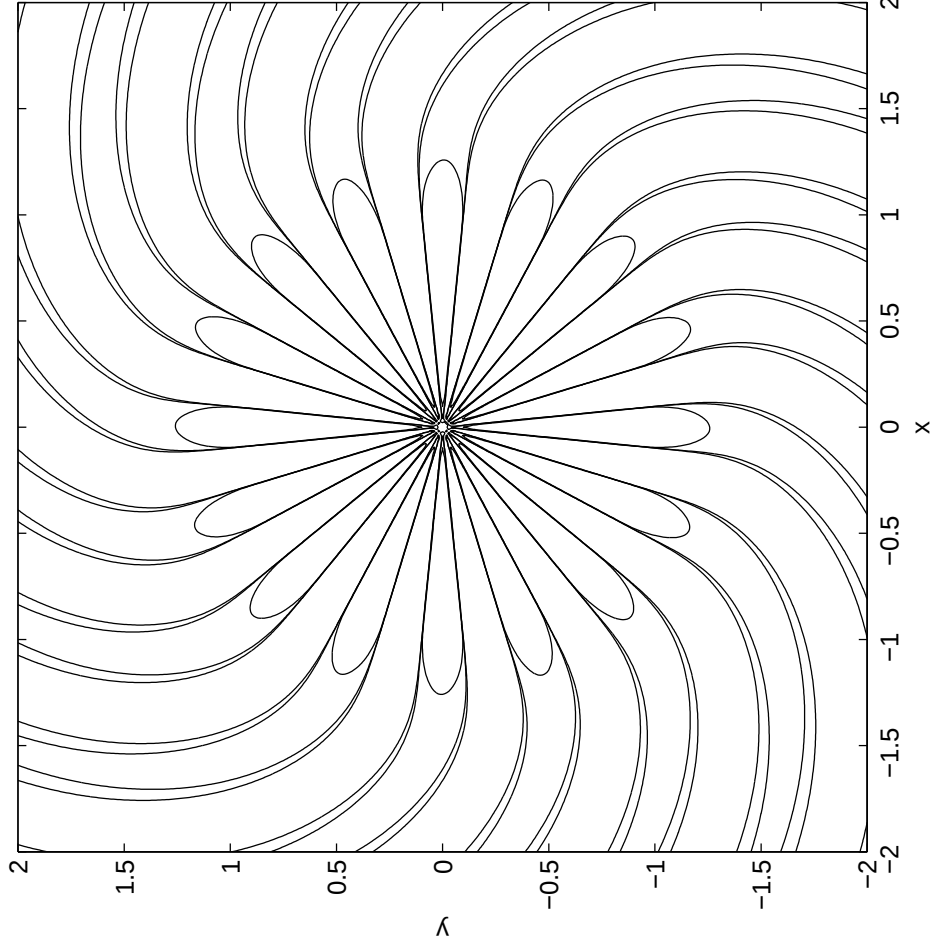
g_p can be evaluated from power series expansion of $\exp(jkS)/S$.

Power series expansion of Green's function

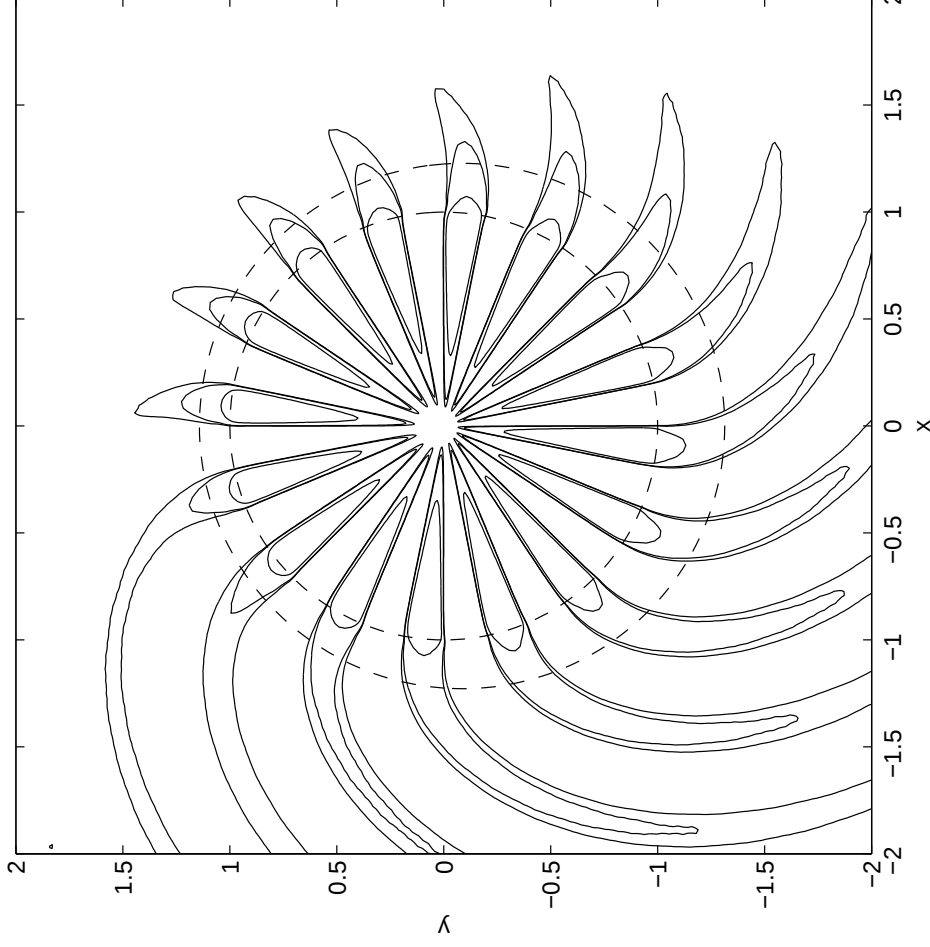
$$\frac{d^u}{dC^u} \left(e^{jk(S-S_0)} \frac{S_0}{S} \right) = \sum_{q=0}^u \binom{u}{q} \frac{d^u}{dC^u} \left(e^{jk(S-S_0)} \right) \frac{d^{u-v}}{dC^{u-v}} \left(\frac{S_0}{S} \right),$$
$$C = \cos(\theta + \theta_2).$$

All the required derivatives can be evaluated exactly using recursion relations or in closed form.

Low speed takeoff



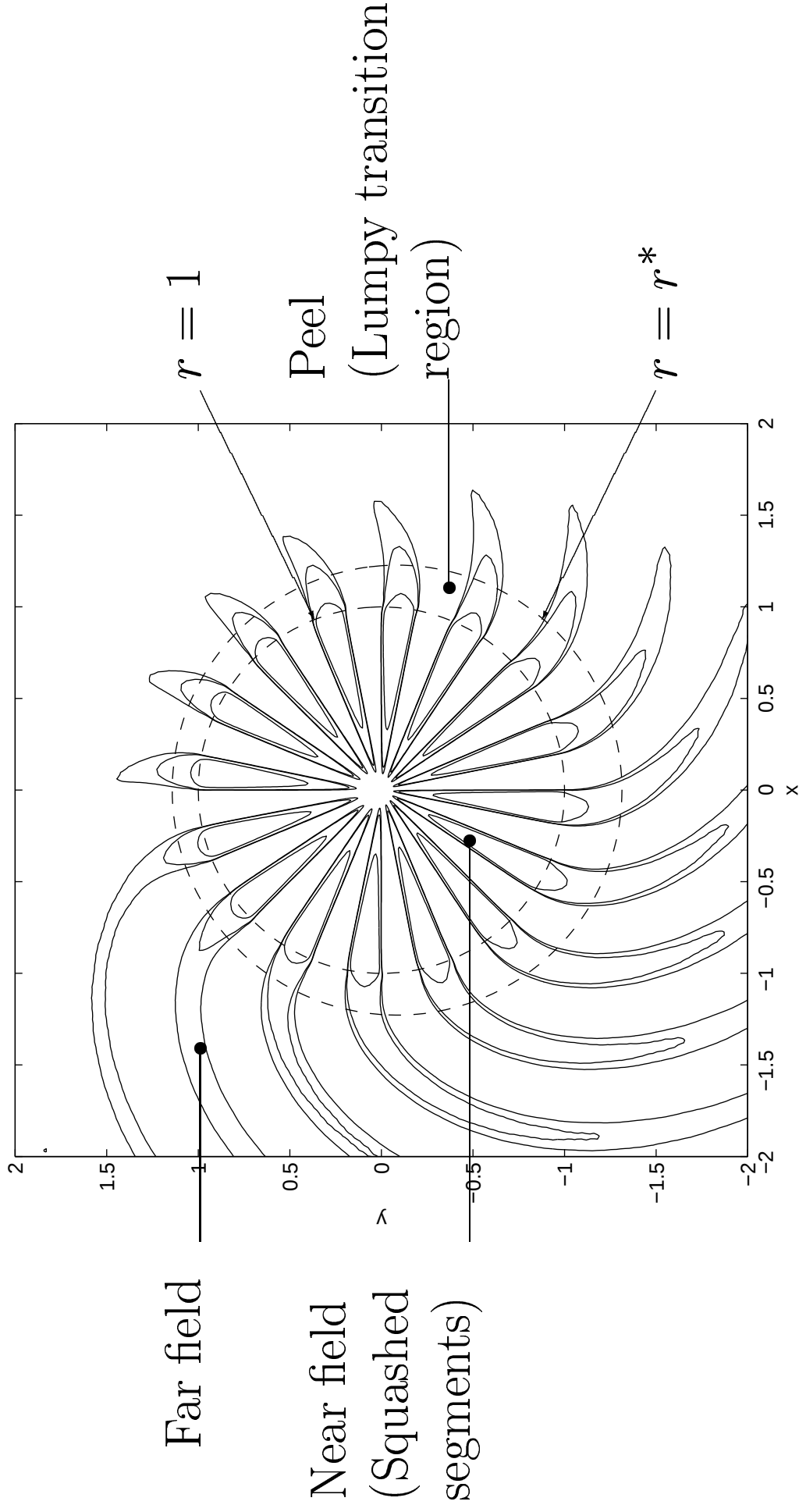
$$\alpha = 0^\circ, p = 10^{-5}, -4, -3$$



$$\alpha = 20^\circ, p = 0.01, 0.02, 0.1.$$

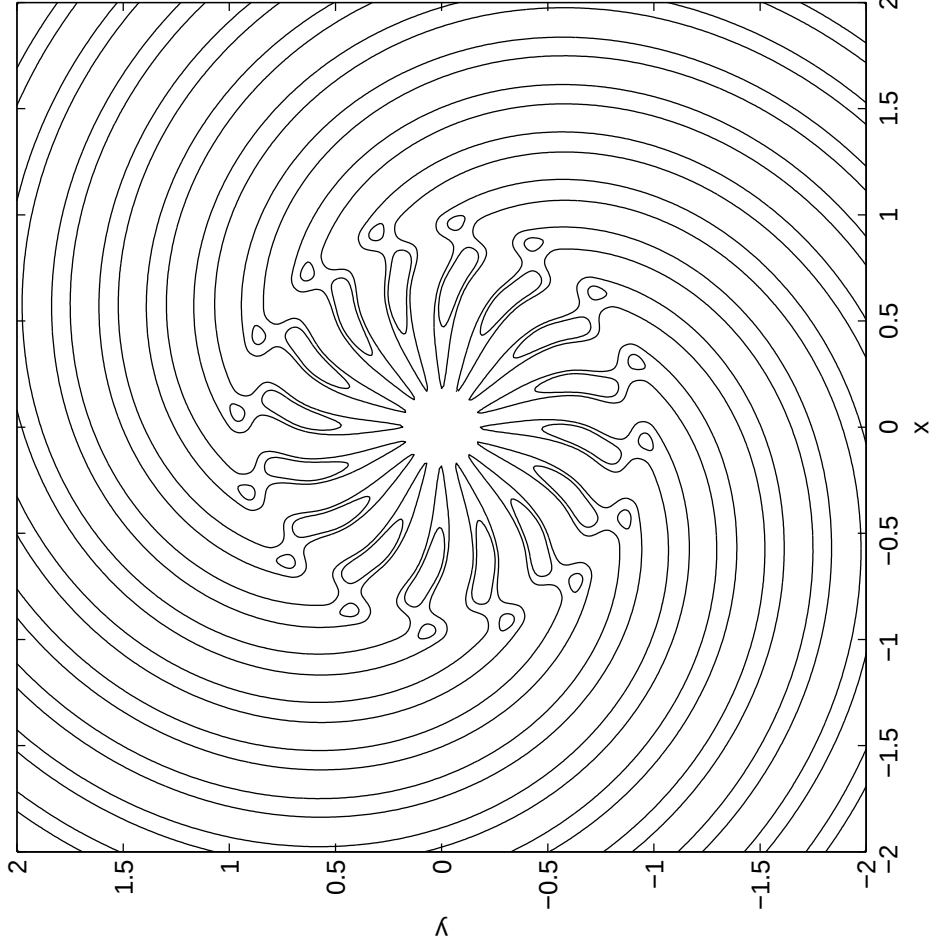
$$M_t = 0.7, M_\infty = 0.2$$

Lumpy orange



$$r^* = -(M_x/M_t) \sin \theta + (M_x^2 \sin^2 \theta + \beta^2)^{1/2}/M_t$$

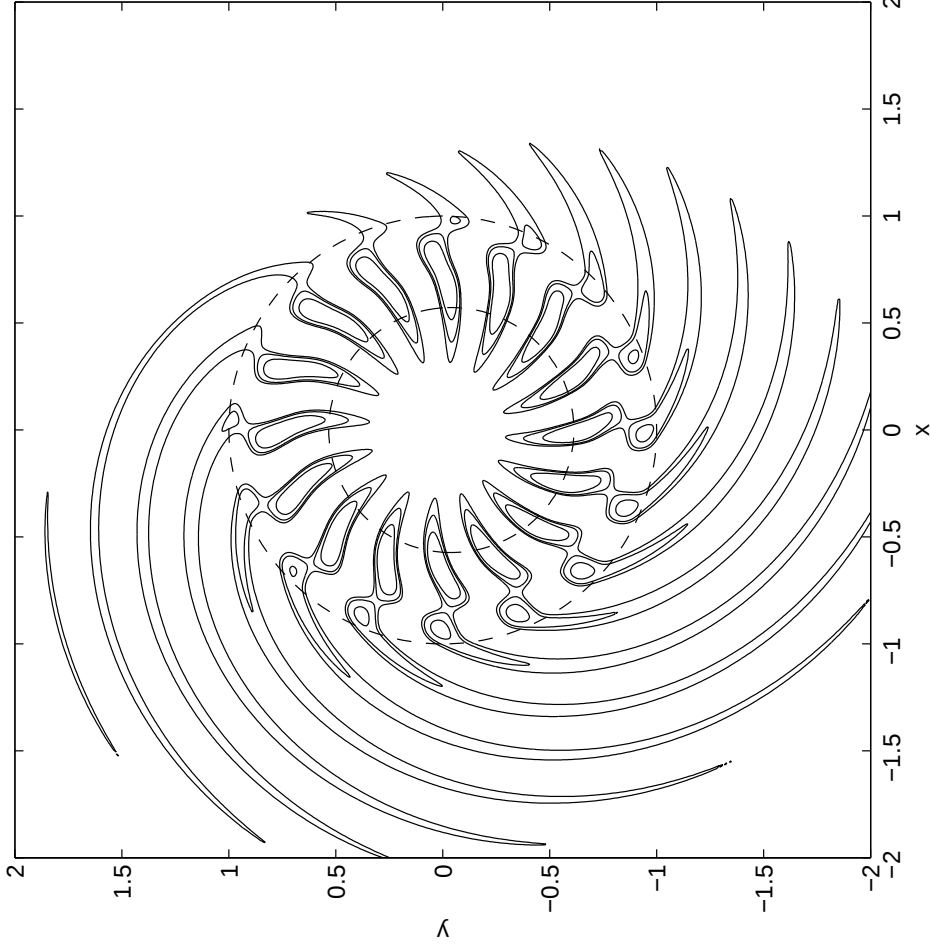
High speed cruise



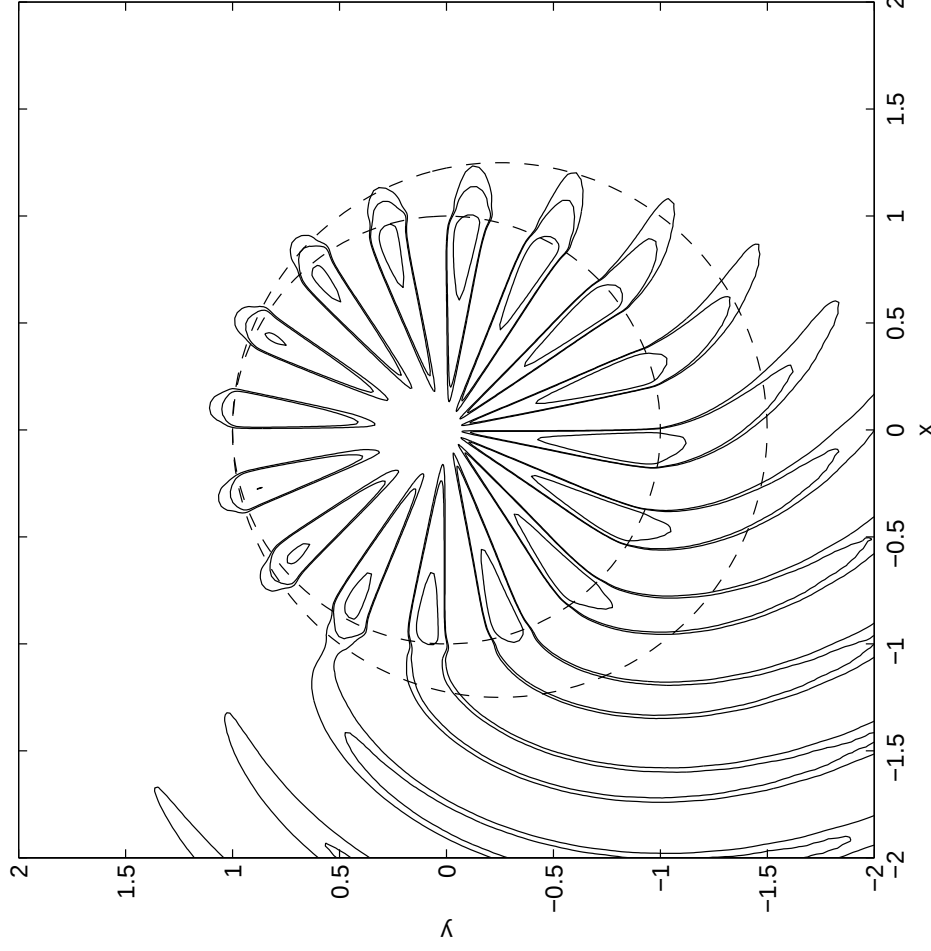
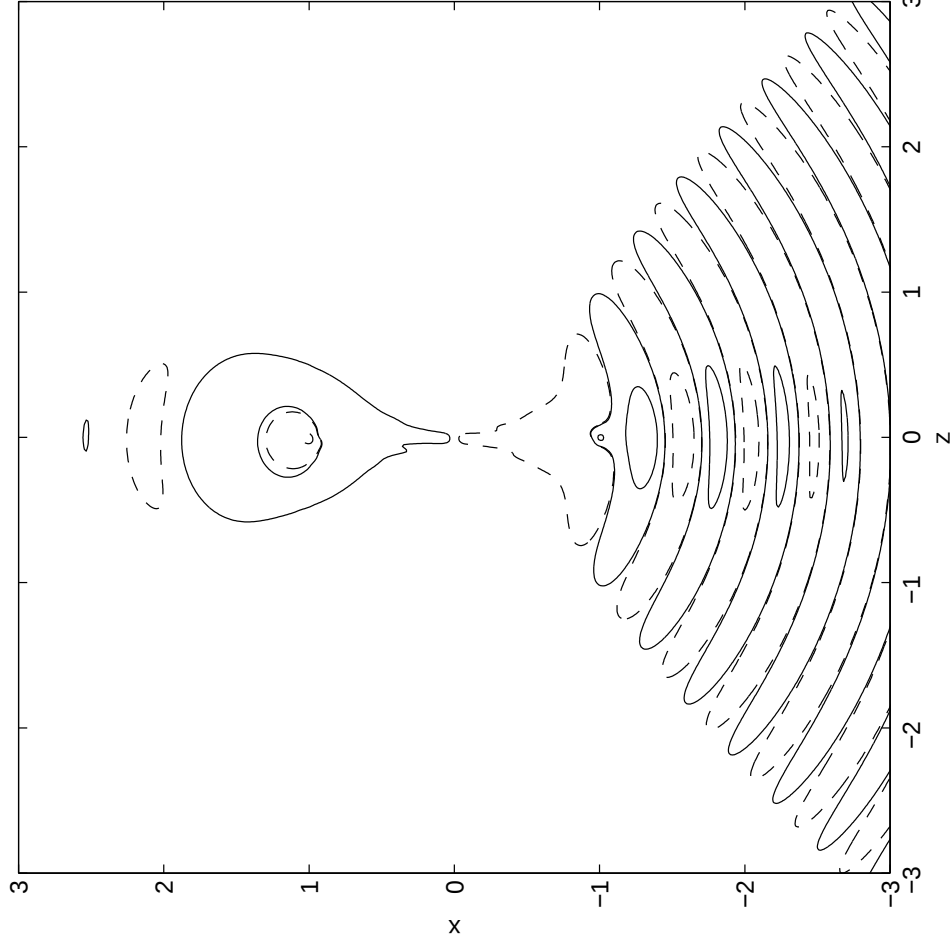
$$\alpha = 0^\circ, p = 10^{-2, -1}$$

$$M_t = 1.05, M_\infty = 0.8$$

$$\alpha = 3^\circ, p = 2, 1, 0.5$$



Helicopter rotor

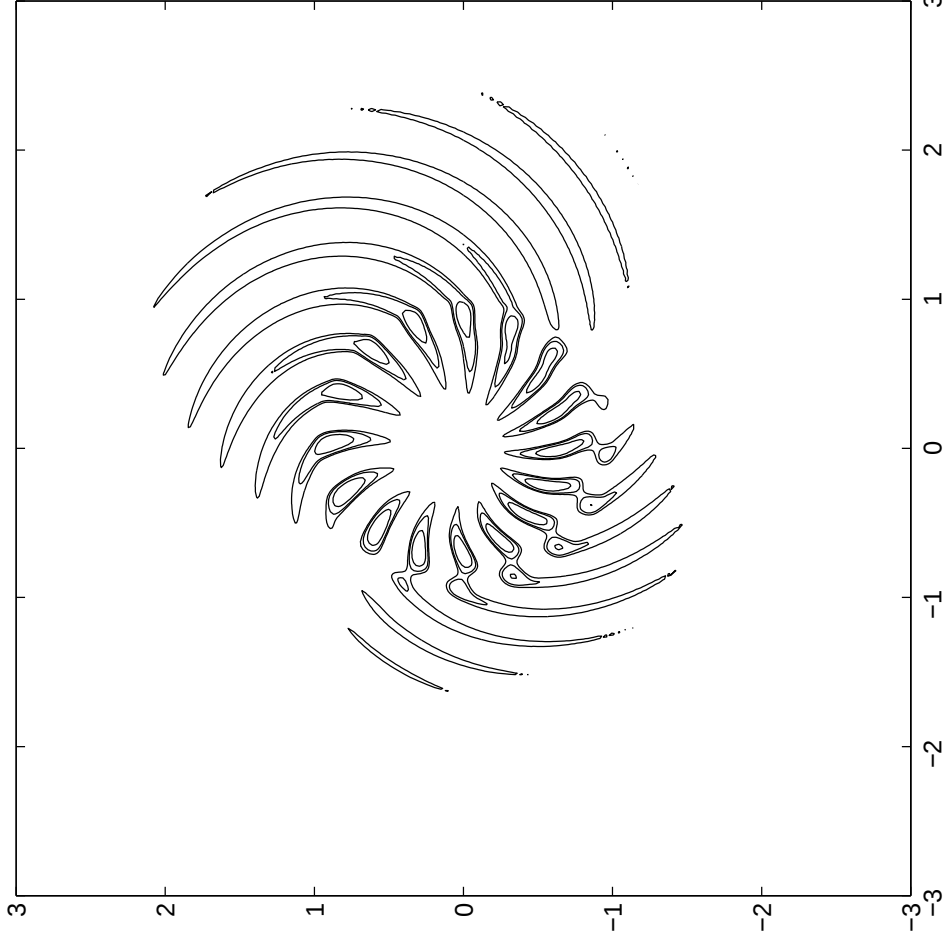
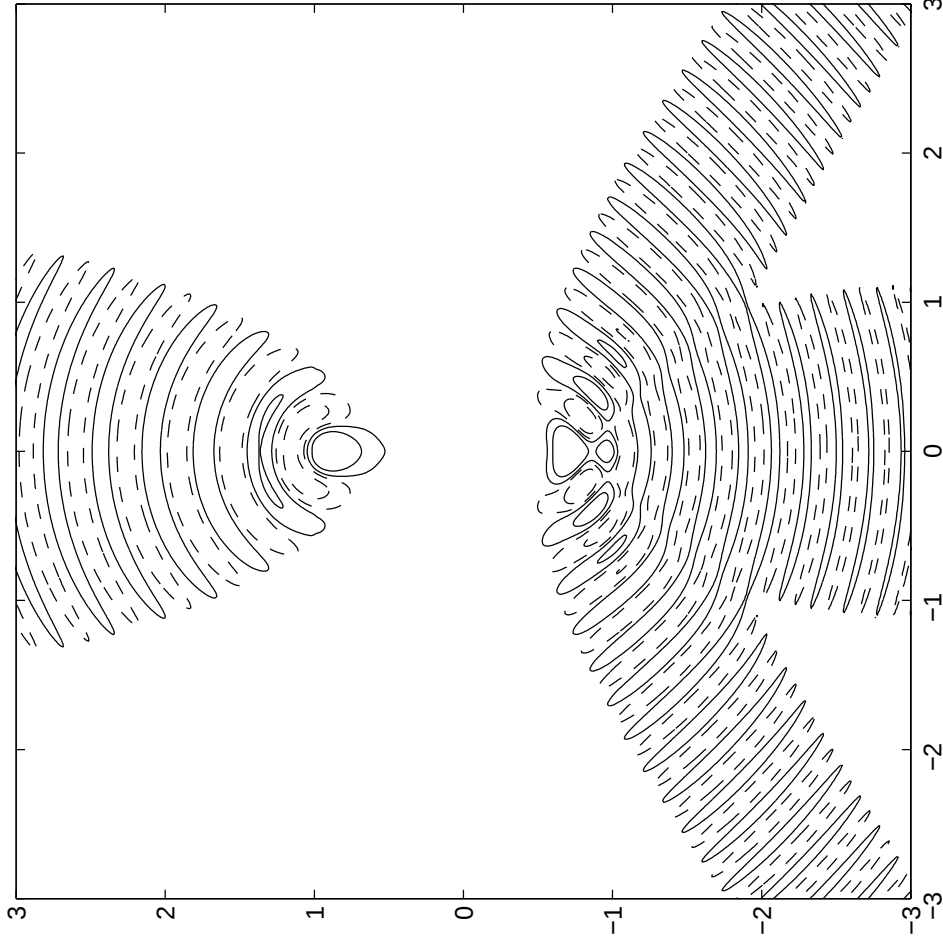


$$y = 0, p = \pm 0.1, \pm 0.05, \pm 0.001$$

$$z = 0, p = 0.25, 0.05, 0.025$$

$$M_t = 0.8, M_\infty = 0.2, \alpha = 85^\circ.$$

Very high speed rotor



$$y = 0, p = \pm 10^{-3}, -2, -1$$

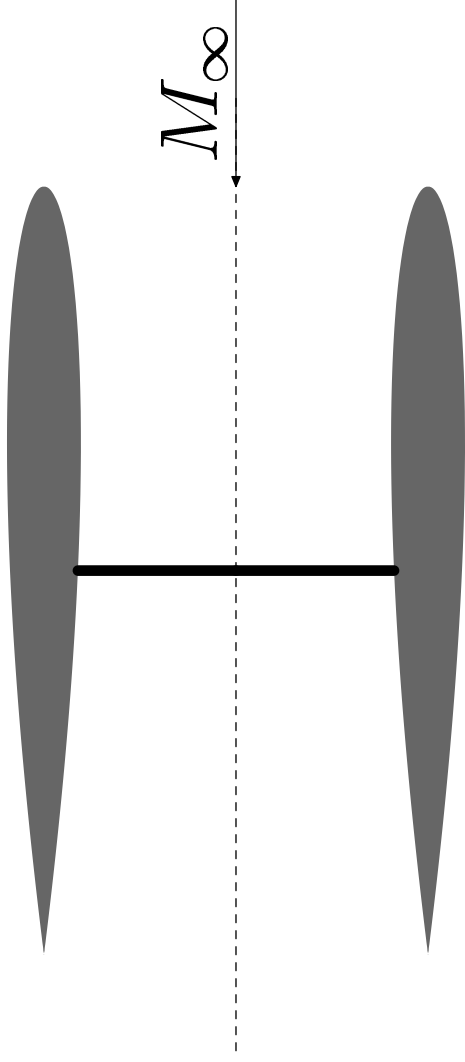
$$z = 0, p = 1, 0.5, 0.25$$

$$M_t = 1.5, M_\infty = 0.2, \alpha = 90^\circ.$$



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Current work: Ducted fan



- Boundary element method for acoustics in mean flow.
- Wake shear layer to be modelled.

Next ...

- Extend the approach to ducted rotors (current work).
- Other applications:
 - vortex dynamics in axisymmetric domains.
 - vibrating systems.
- Improve calculation of J :
 - asymptotic methods (hard).
 - power series (easy?).
- Inversion?
 - bit of a disaster ...
 - but has potential.