

Macro: slider_crank_dsp.mac

Macro	slider_crank_dsp.mac
Description	Demonstrates a slider-crank mechanism (four bar mechanism) and uses surface (dsp) models for the links, etc.
CM version	Any; some commands (commented out here) require the DAG version of the modeller
Requires	dsp files used in <code>setup</code> function, namely: <code>sc_coupler.dsp</code> , <code>sc_crank.dsp</code> , <code>sc_pin.dsp</code> , <code>sc_pivot.dsp</code> , <code>sc_rail.dsp</code> , <code>sc_slider.dsp</code>
See also	macro: slider_crank.mac

What the macro does

This macro creates a model of a slider-crank mechanism (a type of four bar mechanism) using surface (dsp) models to show the links. These were originally created using Solid Edge and then saved as STL files and then converted into DSP format. The model is shown in figure 1.

This macro is an extension of macro slider_crank.mac.

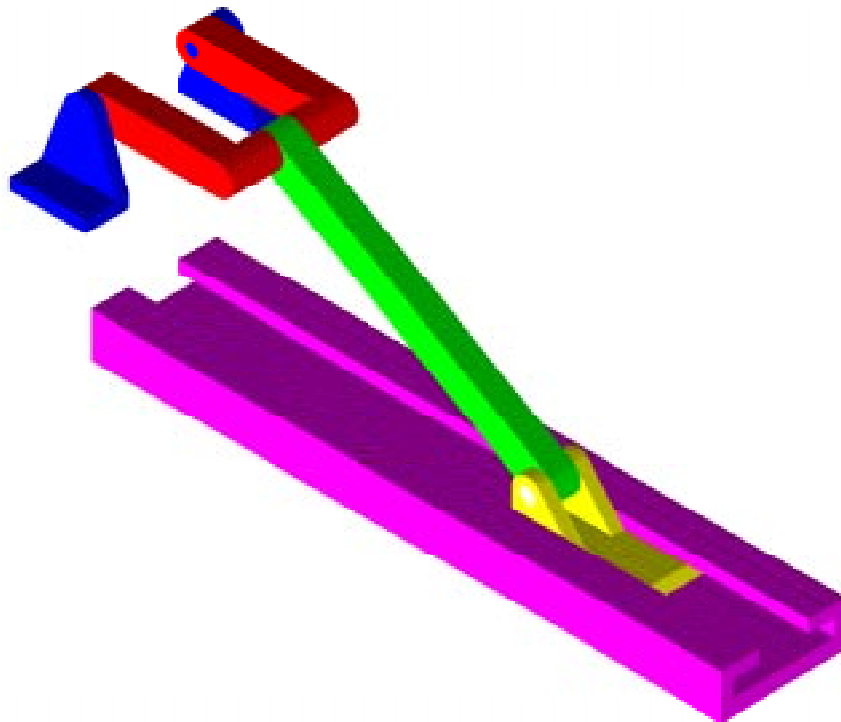


Figure 1: Slider-crank (four bar) mechanism

How the main part of the macro works

The macro is an extension of macro slider_crank.mac.

The extension is to use DSP files to define surface models of the links. Each DSP object is associated with an entity of type `geom`. Each entity is embedded into a three dimensional model space. For the moving links, this model space is itself embedded into the corresponding two dimensional space used to hold the stick geometry.

GM

May 2013

Listing of macro

```

0001  $ =====
0002  $   slider_crank_dsp.mac
0003  $ =====
0004  $   Slider crank mechanism
0005  $   based on slider_crank.mac
0006  $   revised: May 2013
0007  $ =====
0008
0009  dec int    npoint;                $ number of points
0010  npoint = 36;                    $ make it 36
0011  dec int    delay_factor;          $ delay factor
0012  delay_factor = 0;                $ set to zero
0013
0014  dec string file_name;             $ name of output file
0015  dec geom    p0;                   $ fixed pivot point
0016  dec geom    lcrank, lcoupler, lslider; $ lines for links/rail
0017  dec geom    pcoupler;             $ end of coupler point
0018  dec mod2    mcrank, mcoupler, mslider; $ model spaces
0019  dec real    len_crank, len_coupler, len_slider; $ link lengths
0020  dec real    yoffset;              $ offset value
0021  dec mod3    m1crank, m1coupler, m1slider; $ 3d spaces to ...
0022  dec mod3    m1rail, m1pin;        $ ... hold the dsp ...
0023  dec mod3    m1pivot1, m1pivot2;    $ ... objects
0024  dec geom    dcrank, dcoupler, dslider; $ dsp objects
0025  dec geom    draill, dpin;          $ ditto
0026  dec geom    dpivot1, dpivot2;      $ ditto
0027  dec geom    qq[npoint];           $ array of points
0028  dec real    xx[npoint];           $ array of pos
0029  dec real    vv[npoint];           $ array of vel
0030  dec real    aa[npoint];           $ array of acc
0031  dec real    tstep;                $ time step
0032  dec int     echo_qq_flag;          $ integer flag
0033  dec real    v_theta, v_phi, v_psi, v_inc; $ viewing angles
0034
0035  file_name = "slider_crank.out";     $ set the file name
0036  len_crank = 40;                    $ length of crank
0037  len_coupler = 100;                 $ length of coupler
0038  len_slider = 160;                 $ length of slide rail
0039  yoffset = -50;                    $ offset of rail
0040  tstep = 0.1;                      $ time step
0041  echo_qq_flag = 1;                 $ flag set to unity
0042  v_inc = 1.0;                      $ viewing increment
0043
0044
0045  function setup                    $ start of function
0046  {
0047      p0 = pnt(0,0,0);              $ define point p0
0048      cfont(7,p0);                  $ change its font
0049      ccol(blue(),p0);              $ and colour
0050      mcrank = mod2(0,0,0);          $ crank model space

```

Figure 2: Listing of macro slider_crank_dsp.mac (part 1)

```

0051    lcrank = lin( 0,0,0, len_crank,0,0, mcrank );    $ crank line
0052    mcoupler = mod2(0,0,-45,mcrank);    $ coupler model space
0053    lcoupler = lin(0,0,0,len_coupler,0,0,mcoupler);    $ coupler line
0054    pcoupler = pnt( len_coupler, 0, 0, mcoupler );    $ end of coupler point
0055    mslider = mod2(0,0,0);    $ slider model space
0056    lslider = lin(0,yoffset,0,len_slider,yoffset,0);    $ line for slide rail
0057    ccol( red(), lcrank );    $ make crank red
0058    ccol( green(), lcoupler, pcoupler );    $ and coupler green
0059    ccol( magenta(), lslider );    $ and rail magenta
0060    cfont( 4, pcoupler );    $ make font a circle
0061    pivot( mcrank, lcrank:e1, p0 );    $ join crank to p0
0062    pivot( mcoupler, lcoupler:e1, lcrank:e2 );    $ and crank to coupler
0063
0064    m1crank = mod3( 0,0,0, 0,0,0, mcrank );    $ model space and ...
0065    dcrank = readdsp( "sc_crank.dsp" );    $ ... dsp for crank
0066    dcrank:m = &m1crank;
0067    ccol( red(), dcrank );
0068
0069    m1coupler = mod3( 0,0,0, 0,0,0, mcoupler );    $ model space and ...
0070    dcoupler = readdsp( "sc_coupler.dsp" );    $ ... dsp for coupler
0071    dcoupler:m = &m1coupler;
0072    ccol( green(), dcoupler );
0073
0074    m1slider = mod3( 0,0,0, 0,0,0, mslider );    $ model space and ...
0075    dslider = readdsp( "sc_slider.dsp" );    $ ... dsp for slider
0076    dslider:m = &m1slider;
0077    ccol( yellow(), dslider );
0078
0079    m1rail = mod3( 0,yoffset-20,0, 0,0,0 );    $ model space and ...
0080    drail = readdsp( "sc_rail.dsp" );    $ ... dsp for rail
0081    drail:m = &m1rail;
0082    ccol( magenta(), drail );
0083
0084    m1pin = mod3( 0,0,0, 0,0,0, m1slider );    $ model space and ...
0085    dpin = readdsp( "sc_pin.dsp" );    $ ... dsp for pin
0086    dpin:m = &m1pin;
0087    ccol( blue(), dpin );
0088
0089    m1pivot1 = mod3( 0,0,-20, 0,0,0 );    $ model space and ...
0090    dpivot1 = readdsp( "sc_pivot.dsp" );    $ ... dsp for povot 1
0091    dpivot1:m = &m1pivot1;
0092    ccol( blue(), dpivot1 );
0093
0094    m1pivot2 = mod3( 0,0,20, 0,180,0 );    $ model space and ...
0095    dpivot2 = readdsp( "sc_pivot.dsp" );    $ ... dsp for povot 2
0096    dpivot2:m = &m1pivot2;
0097    ccol( blue(), dpivot2 );
0098 }    $ end of function
0099
0100

```

Figure 3: Listing of macro slider_crank_dsp.mac (part 2)

```

0101 function    echo_wire_frame                $ start of function
0102 {
0103     dec int    code;
0104     inp        code;                        $ one input argument
0105
0106     echo( code, p0, pcoupler );              $ echo on/off
0107     echo( code, lcrank, lcoupler, lslider );
0108
0109     rpnt( 1 );
0110 }                                              $ end of function
0111
0112
0113 function    echo_dsp                        $ start of function
0114 {
0115     dec int    code;
0116     inp        code;                        $ one input argument
0117
0118     echo( code, dcrank, dcoupler, dslider ); $ echo on/off
0119     echo( code, drail, dpin );
0120     echo( code, dpivot1, dpivot2 );
0121
0122     rpnt( 1 );
0123 }                                              $ end of function
0124
0125
0126 function    echo_qq                        $ start of function
0127 {
0128     dec int    code, i;
0129     inp        code;                        $ one input argument
0130
0131     loop( i, 0, npoint )                    $ start loop
0132     { echo( code, qq[i] );                  $ echo on/off
0133     }                                        $ end loop
0134
0135     rpnt( 1 );                              $ clear and repaint
0136     echo_qq_flag = code;                    $ update flag value
0137 }                                              $ end of function
0138
0139
0140
0141 function    do_delay                        $ start of function
0142 {
0143     dec int    i, j;                        $ local variables
0144     dec real   a, b;
0145
0146     loop( i, 0, delay_factor )              $ start loop
0147     { a = i;
0148       loop( j, 0, 1000 )                    $ start another loop
0149       { b = j;                              $ do pointless calc ...
0150         a = a + sin( a + b );                $ ... to waste time

```

Figure 4: Listing of macro slider_crank_dsp.mac (part 3)

```

0151     }                                $ end inner loop
0152   }                                $ end outer loop
0153 }                                $ end of function
0154
0155 function assemble_inner                $ start of function
0156 {
0157     var mcoupler;                    $ coupler angle varies
0158
0159     rule( pcoupler on lslider );      $ put coupler on rail
0160 }                                    $ end of function
0161
0162
0163 function assemble                      $ start of function
0164 {
0165     assemble_inner();                $ do basic assembly
0166     mslider:p = transf( pcoupler ):x; $ adjust slider pos ...
0167     mslider:q = transf( pcoupler ):y; $ ... in x and y
0168 }                                    $ end of function
0169
0170
0171
0172 function cycle                         $ start of function
0173 {
0174     dec int i, code;                 $ local variables
0175     inp code;                        $ one argument
0176
0177     loop( i, 0, npoint )             $ loop for cycle
0178     { mcrank:a = i*360/npoin;        $ increment crank angle
0179       assemble();                    $ call assemble
0180       rpnt(code);                    $ repaint graphics
0181       qq[i] = transf( pcoupler );    $ get end of coupler
0182       ccol( cyan(), qq[i] );         $ change colour
0183       cfont( 6, qq[i] );             $ and its font
0184       echo( echo_qq_flag, qq[i] );   $ echo on/off
0185       xx[i] = qq[i]:x;               $ get x coordinate
0186       if( i < npoint )
0187       { do_delay();
0188       }
0189     }
0190 }
0191 }                                    $ end of function
0192
0193
0194 function find_vel_acc                 $ start of function
0195 {
0196     vv = deriv( 1, xx, timestep );   $ first derivative
0197     aa = deriv( 2, xx, timestep );   $ second derivative
0198 }                                    $ end of function
0199
0200

```

Figure 5: Listing of macro slider_crank_dsp.mac (part 4)

```

0201 function do_output                                $ start of function
0202 {
0203     dec int i;                                     $ declare local int
0204
0205     fwriteln( 0, "Opening file:", file_name );      $ message to screen
0206     fopen( 2, 2, file_name );                      $ open file to write
0207     fwriteln( 2, asc(36), "File:", file_name );     $ output file name
0208     fwriteln( 2, asc(36), "Date:", date() );        $ output date/time
0209     fwriteln( 2 );                                  $ blank line
0210
0211     loop( i, 0, npoint )
0212     { fwrite( 2, "%3d", i );                         $ output counter
0213       fwrite( 2, "%12.5lf", xx[i] );                 $ output pos
0214       fwrite( 2, "%12.5lf", vv[i] );                 $ output vel
0215       fwrite( 2, "%12.5lf", aa[i] );                 $ output acc
0216       fwriteln( 2 );                                $ end output line
0217     }
0218
0219     fwriteln( 2 );                                  $ blank line
0220     fwriteln( 2, asc(36), "End of file" );           $ output end of file
0221     fwriteln( 2 );                                  $ blank line
0222     fclose( 2 );                                    $ close file
0223     fwriteln( 0, "File closed:", file_name );        $ write to screen
0224 }                                                    $ end of function
0225
0226 graphics();                                         $ graphics window
0227 deflight();                                         $ default lighting
0228 lposition( 0, 1,0,4 );                             $ adjust light position
0229 vangles( 45.0, 35.5, -120.0 );                   $ set view
0230 setup();                                           $ call setup
0231 assemble();                                        $ call assemble
0232 echo_wire_frame( 0 );                             $ wires off
0233 echo_dsp( 1 );                                     $ surfaces on
0234 echo_qq( 0 );                                     $ track points off
0235 rpnt();                                           $ repaint screen
0236 zoom();                                           $ and zoom all
0237 zoom(0.8);                                        $ zoom down a little
0238
0239 menu slider                                       $ create menu
0240 {
0241     button Setup
0242     { setup();                                     $ call setup function
0243     }
0244     submenu Background>
0245     { button Black
0246       { background( 0, 0, 0 );
0247       rpnt();
0248       }
0249       button Grey (0.33)
0250       { background( 0.33, 0.33, 0.33 );

```

Figure 6: Listing of macro slider_crank_dsp.mac (part 5)

```

0251         rpnt();
0252     }
0253     button Grey (0.67)
0254     { background( 0.67, 0.67, 0.67 );
0255         rpnt();
0256     }
0257     button White
0258     { background( 1, 1, 1 );
0259         rpnt();
0260     }
0261 }
0262 submenu Views>
0263 { button View 1
0264     { vangles( 45.0, 35.5, -120.0 );
0265         rpnt(1);
0266     }
0267     button View 2
0268     { vangles( 34.7, 17.7, -101.8 );
0269         rpnt(1);
0270     }
0271     button Front
0272     { vvector( 0, 0, 1 );
0273         rpnt(1);
0274     }
0275
0276 $ =====
0277 $   function getvangles is only available in DAG version of modeller
0278 $ =====
0279 $   button Rotate+
0280 $   { v_theta, v_phi, v_psi = getvangles();
0281 $     vangles( v_theta, v_phi, v_psi+v_inc );
0282 $     rpnt(1);
0283 $   }
0284 $   button Rotate-
0285 $   { v_theta, v_phi, v_psi = getvangles();
0286 $     vangles( v_theta, v_phi, v_psi-v_inc );
0287 $     rpnt(1);
0288 $   }
0289 $   button Double v_inc
0290 $   { v_inc = 2.0*v_inc;
0291 $     fwriteln( 0, "v_inc =", v_inc );
0292 $   }
0293 $   button Halve v_inc
0294 $   { v_inc = 0.5*v_inc;
0295 $     fwriteln( 0, "v_inc =", v_inc );
0296 $   }
0297 $ =====
0298
0299 }
0300

```

Figure 7: Listing of macro slider_crank_dsp.mac (part 6)

```

0301     button Cycle
0302     { cycle(1);
0303     }
0304     submenu Delay>
0305     { button 0
0306     { delay_factor = 0;
0307     }
0308     button 1
0309     { delay_factor = 1;
0310     }
0311     button 2
0312     { delay_factor = 2;
0313     }
0314     button 5
0315     { delay_factor = 5;
0316     }
0317     button 10
0318     { delay_factor = 10;
0319     }
0320     button 20
0321     { delay_factor = 20;
0322     }
0323     button 50
0324     { delay_factor = 50;
0325     }
0326     button 100
0327     { delay_factor = 100;
0328     }
0329     }
0330     submenu Echo>
0331     { button Wireframe ON
0332     { echo_wire_frame( 1 );
0333     }
0334     button Wireframe OFF
0335     { echo_wire_frame( 0 );
0336     }
0337     button Surface (dsp) ON
0338     { echo_dsp( 1 );
0339     }
0340     button Surface (dsp) OFF
0341     { echo_dsp( 0 );
0342     }
0343     button Rail (dsp) OFF
0344     { echo( 0, drail );
0345     rpnt( 1 );
0346     }
0347     button Track points (qq) ON
0348     { echo_qq( 1 );
0349     }
0350     button Track points (qq) OFF

```

Figure 8: Listing of macro slider_crank_dsp.mac (part 7)

```

0351     { echo_qq( 0 );
0352     }
0353 }
0354 button Vel/acc
0355 { find_vel_acc();           $ find vel and acc
0356   fwriteIn( 0, "Completed" ); $ write to screen
0357 }
0358 button Output
0359 { do_output();             $ output values
0360 }
0361 }
0362
0363 remmenu();                 $ remove previous menu
0364 addmenu( slider );        $ put up new menu
0365
0366 $ End of file
0367

```

Figure 9: Listing of macro slider_crank_dsp.mac (part 8)