Unsteady thermal boundary layer flows of a Bingham fluid in a porous medium following a sudden change in surface heat flux

D. Andrew S. Reesa,⇑, Andrew P. Bassomb,1

aDepartment of Mechanical Engineering, University of Bath, Bath BA2 7AY, UK
bSchool of Mathematics and Statistics, The University of Western Australia, Crawley, WA 6009, Australia

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A B S T R A C T

We consider the effect of suddenly applying a uniform heat flux to a vertical wall bounding a porous medium which is saturated by a Bingham fluid. We consider both an infinite porous domain and a vertical channel of finite width. Initially, the evolving temperature field provides too little buoyancy force to overcome the yield threshold of the fluid. For the infinite domain convection will always eventually arise, but this does not necessarily happen in the vertical channel. We show (i) how the presence of yield surfaces alters the classical results for Newtonian flows and (ii) the manner in which the locations of the yield surfaces change as time progresses.

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1. Introduction

Bingham fluids are an example of a yield stress fluid. Unlike Herschel–Bulkeley and Casson fluids, they exhibit a linear stress–strain relationship once the yield stress is exceeded. They arise in a wide variety of situations both in the environment and industry, and examples of the very many natural and man-made fluids which exhibit a yield stress have been collated and presented in the chapter [1].

The aim of the present short paper is to investigate the manner in which convection arises when a Bingham fluid saturates a porous medium. There already exist some papers on this type of topic, but they are concerned with the equivalent fluid problem, i.e. there is no porous matrix present. We refer to the analyses by Yang and Yeh [2] and Bayazitoglu et al. [3] who studied free convection in a sidewall–heated channel. They find that steady convection will only arise whenever the Rayleigh number is sufficiently large that the buoyancy force is then able to overcome the yield stress. When flow occurs the velocity profile consists of five regions, with three regions of flow alternating with two of plug flow (i.e. constant velocity with no shear). The plug flow regions are themselves moving and are placed at equal distances either side of the centreline of the channel. Other papers which consider variations on this theme are those by Patel and Ingham [4] who consider a mixed convection with the combination of buoyancy and a driving pressure gradient, Barletta and Magyari [5] who consider a free convection variant on vertical Couette flow, and Karimfazli and Frigaard [6] whose study of free convection when the boundary temperatures vary linearly with distance up the walls. The unsteady analysis of Kleppe and Marner [7] is also important because it considers the evolution of the temperature and velocity profiles in a vertical channel after an sudden change in temperature of one of the vertical walls.

The present paper considers the unsteady unidirection convection which is set up by suddenly changing the boundary heat flux of a vertical surface. This is a natural extension to the work of Rees and Bassom [8] who studied an impulsive change in the boundary temperature. We will see that the final outcome here has many qualitative differences from those found in [8]. Again, we will consider both a semi-infinite domain (i.e. bounded by a single vertical wall), and a vertical channel of constant thickness. As in [8] buoyancy forces spread into the porous medium due to the diffusion of heat from the heated surface. We find that convection does not happen at first, but that there is an onset time after which convection persists. We present detailed exact solutions for the locations of the yield surfaces and overall velocity flux, and an asymptotic analysis yields highly accurate data for large times.

⇑Corresponding author.
E-mail addresses: D.A.S.Rees@bath.ac.uk (D. Andrew S. Rees), andrew.bassom@uwa.edu.au (A.P. Bassom).
1Permanent address: School of Mathematics and Physics, University of Tasmania, Private Bag 37, Hobart, TAS 7001, Australia.

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2. Governing equations

We follow the early paper by Pascal [9] which employs a threshold gradient model to describe the one-dimensional flow of a Bingham fluid in a porous medium:

\[ \pi = \begin{cases} - \frac{\pi}{\eta} \left[ 1 - \frac{C_0}{\eta} |\phi_l - \rho g \beta (T - T_0)| \right] & \text{when } |\phi_l - \rho g \beta (T - T_0)| > \eta, \\ 0 & \text{otherwise,} \end{cases} \]

(1)

where \( \pi \) denotes the threshold gradient (or, more generally, the threshold body force) above which the fluid yields. When buoyancy is included as an extra body force, the threshold model becomes,

\[ \pi = \begin{cases} - \frac{\pi}{\eta} \left[ 1 - \frac{C_0}{\eta} \phi_l \right] & \text{when } |\phi_l - \rho g \beta (T - T_0)| > \eta, \\ 0 & \text{otherwise,} \end{cases} \]

(2)

and where \( \pi \) is now the vertical coordinate and \( \eta \) is the corresponding Darcy velocity. We have assumed that the Boussinesq approximation applies when writing down the buoyancy term, and \( T_0 \) is the initial temperature of the porous medium. If a heated vertical surface is of infinite extent in both the positive and negative \( x \) directions, then there will be a zero horizontal fluid velocity. We may allow both \( \pi \) and \( T \) to be functions only of the horizontal coordinate, \( y \), and time, \( t \), and so the equation of continuity is satisfied and the heat transport equation is,

\[ \sigma T_t = \pi \pi_T, \]

(3)

where \( \sigma \) is heat capacity ratio between the porous medium and the saturating fluid, and \( \pi \) is the effective thermal diffusivity of the saturated porous medium. At \( T = 0 \) a uniform and steady heat flux, \( q \), is applied suddenly to the vertical bounding surface:

\[ k \frac{\partial T}{\partial y} = -q, \]

(4)

where \( k \) is the thermal conductivity of the medium.

Equations (2) and (3) may be nondimensionalised using the scalings,

\[ (x, y) = L(x, y), \quad \pi = \frac{x}{L} \mu, \quad \eta = \frac{\pi}{L}, \quad T = T_o \frac{q L}{K} \theta, \]

(5)

and we obtain,

\[ u = \begin{cases} Ra \theta - p_x - R_b, & \text{if } Ra \theta - p_x < -R_b, \\ 0, & \text{if } -R_b < Ra \theta - p_x < R_b, \\ Ra \theta - p_x + R_b, & \text{if } Ra \theta - p_x > R_b, \end{cases} \]

(6)

and

\[ \theta_t = \theta_T. \]

(7)

In the above the Darcy–Rayleigh number is given by

\[ Ra = \frac{\rho g \beta K L^2}{k \mu \alpha}, \]

(8)

and the parameter, \( R_b \), is given by

\[ R_b = \frac{KL}{\mu \alpha}. \]

(9)

This latter parameter is a scaled version of the yield pressure gradient, \( G \), and might be referred to as a porous convective Bingham number; hereinafter it is termed the Rees–Bingham number \( R_b \).

The lengthscale, \( L \), which was introduced in Eq. (5), will be taken to be the dimensional width of the vertical channel when that configuration is being studied. But when the porous medium occupies a semi-infinite domain there is no natural external lengthscale that may be used. Therefore we set the Darcy–Rayleigh number to a unit value, which will then automatically define a natural lengthscale, \( L \), in terms of the properties of the medium; thus we have,

\[ L = \sqrt{\frac{k \alpha}{\rho g p q K}}. \]

(10)
The initial condition in nondimensional form is simply that \( \theta = 0 \) at \( t = 0 \). For both the infinite domain and the vertical channel we have \( \partial \theta / \partial y = -1 \) at \( y = 0 \), whereas we have \( \theta \to 0 \) as \( y \to \infty \) for the infinite domain, and either \( \theta = 0 \) at \( y = 1 \) (Case 1) or \( \partial \theta / \partial y = 0 \) at \( y = 1 \) (Case 2) for the vertical channel.

3. The semi-infinite domain

We consider first the heat transfer and flow which is caused by suddenly imposing a unit heat flux to the vertical bounding surface at \( y = 0 \), i.e. the boundary condition,
\[
\frac{\partial \theta}{\partial y} = -1, \tag{11}
\]
applies there, and we expect that \( \theta \to 0 \) as \( y \to \infty \). As has already been discussed we are setting \( Ra = 1 \) in this semi-infinite case.

Eq. (7) for \( \theta \) is well-known to possess a self-similar solution of the form,
\[
\theta = t^{1/2} f(\eta) \quad \text{where} \quad \eta = \frac{y}{2\sqrt{t}}, \tag{12}
\]
and where
\[
\int_0^\eta f'' + 2\eta f' = 2f, \quad f'(0) = -1, \quad f \to 0 \quad \text{as} \quad \eta \to \infty. \tag{13}
\]
The solution is
\[
f = 2 \text{erfc} \eta - 2 \int_\eta^\infty \text{erfc} \zeta \zeta d\zeta - \frac{2}{\sqrt{\pi}} e^{-\eta^2} - 2 \eta \text{erfc} \eta. \tag{14}
\]
When the domain is infinite this developing thermal field will generate only upward flows, and therefore the hydrostatic gradient, \( \rho \sigma \), which is seen in Eq. (6), must take zero values when one considers conditions in the ambient medium. Therefore Eq. (6) simplifies to,
\[
u = \begin{cases} \theta - Rb \quad \text{when} \quad Rb < \theta \\ 0 \quad \text{when} \quad \theta < Rb. \end{cases} \tag{15}
\]
From this we see that flow arises only when \( \theta \) takes values which are above \( Rb \). Therefore there will always be an interval of time during which no flow is induced. Given that, at any instant of time, the highest temperature in the domain is at \( \eta = 0 \), Eq. (14) shows that the time at which convection begins is when \( t^{1/2} f(0) = Rb \), or
\[
t = \frac{\pi Rb^2}{4}. \tag{16}
\]
From this we deduce the obvious qualitative result that the stronger the yield threshold, the longer one has to wait for convection to ensure. However, the precise form of this onset time is not obvious.

At later times convection takes place in a near-surface sublayer of the thermal boundary layer and there is no motion outside of the yield surface where \( \theta = Rb \). If we denote the location of this yield surface by \( \eta_y \), then \( \theta = Rb \) becomes
\[
\frac{2}{\sqrt{\pi}} e^{-\eta_y^2} - 2 \eta_y \text{erfc} \eta_y = \frac{Rb}{\sqrt{t}}. \tag{17}
\]

Fig. 1 shows the variation of \( \eta_y \) and its Cartesian counterpart, \( y_y \), with \( \tau \), where \( \tau \) is a scaled time given by
\[
t = Rb^2 \tau. \tag{18}
\]
This curve is also compared with a large-time asymptotic analysis which may be found in the Appendix A. These four terms in the asymptotic series are seen clearly to provide an excellent match with the exact data when \( \tau > 10^4 \).

We may now determine the total velocity flux as a function of both \( Rb \) and time. The total velocity flux is now given by
\[
Q = \int_0^\infty u dy = 2\sqrt{\tau} Rb \int_0^{y_y} Rb \sqrt{f(\zeta)} - 1 \, d\zeta = Rb^2 \tau \text{erf} \eta_y = \text{erf} \eta_y. \tag{19}
\]
Given that \( Q/t \) is a function solely of \( \eta_y \) which is, in turn, a function of \( \tau \), we display the variation of \( Q/t \) with \( \log_{10} \tau / \pi \) in Fig. 2. Convection begins when \( \tau = \pi/4 \), and the curve given in Fig. 2 may also be interpreted as the total velocity flux compared with that of a Newtonian fluid. Once more, the asymptotic series is shown to have excellent agreement with the exact solution when \( \tau > 10^4 \).

4. The vertical channel

We now consider convection within a tall cavity with unit nondimensional width, and therefore the Darcy–Rayleigh number now appears as a parameter, as discussed earlier. This means that the lengthscale, \( L \), has now been taken to be the width of the channel. As in [8] we assume that the flow, when it arises, will
be parallel and dependent solely on $y$ and $t$; there will exist turning regions at the upper and lower extremities of the channel within which there will be further $x$-dependence. One major consequence of this is that there is now no mean flow up the cavity at any time.

Beginning with $\theta = 0$ everywhere, heat transport is induced by suddenly imposing $\theta_y = -1$ on $y = 0$. We will consider two cases corresponding to the following boundary conditions on the second wall:

Case 1: $\theta = 0$ \quad \text{on} \quad y = 1.

Case 2: $\theta_y = 0$\quad \text{on} \quad y = 1.

Case 1 corresponds to maintaining the right hand wall at the original ambient temperature and therefore one would expect the temperature eventually to tend towards a steady state. On the other hand, Case 2 admits no heat loss, and therefore the mean temperature of the channel will rise linearly in time.

The two respective solutions of (7) are found using a Laplace transform in time; we find that,

\begin{align}
\text{Case 1:} & \quad \theta = \sum_{n=0}^{\infty} 2t^{1/2} \left[ \text{erfc} \left( \eta + \frac{n}{\sqrt{t}} \right) - \text{erfc} \left( \frac{n + 1}{\sqrt{t}} - \eta \right) \right], \\
\text{Case 2:} & \quad \theta = \sum_{n=0}^{\infty} 2t^{1/2} \left[ \text{erfc} \left( \eta + \frac{n}{\sqrt{t}} \right) + \text{erfc} \left( \frac{n + 1}{\sqrt{t}} - \eta \right) \right].
\end{align}

When $t \ll 1$ it is clear that these two solutions reproduce (14) corresponding to the infinite domain because the thermal boundary layer is very thin at such early times.

Some temperature profiles at selected times are shown in Figs. 3 and 4. For both cases the early-time solutions display the ierfc profile which grows in amplitude with time. For Case 1 (Fig. 3) the evolution towards the ultimate state where

$$\theta = 1 - y$$ \quad (23)

is essentially complete by $t = 2$. For Case 2 (Fig. 4) the final state is

$$\theta = t + \frac{1}{2} y^2 - y + \frac{1}{3}.$$ \quad (24)

and the exact profile at $t = 0.5$ is seen to differ from the final state by only a very small amount; the dotted lines in Fig. 4 depict the asymptotic state.

It is necessary now to determine when convection will begin. At sufficiently early times the fluid remains stagnant because insufficient heat has passed into the channel and buoyancy forces are too weak. Bearing in mind the form of (6), incipient convection must correspond to both

$$\text{Ra} \theta_{\max} - p_x = \text{Rb}$$ \quad (25)

and

$$\text{Ra} \theta_{\min} - p_x = -\text{Rb}.$$ \quad (26)

Therefore convection arises when
\[ \theta_{\text{max}} - \theta_{\text{min}} = 2 \frac{Rb}{Ra}, \]  
(27)

and the corresponding hydrostatic pressure gradient is

\[ p_x = \frac{Ra(\theta_{\text{max}} + \theta_{\text{min}})}{2}. \]  
(28)

As noted in [8] a zero net upward fluid flux cannot be sustained by allowing \( p_x \) to be zero for all time, as is the case for the infinite domain, and therefore the value of \( p_x \) must vary in time in order to maintain the zero-vertical-flux condition. Such a variation in the hydrostatic pressure gradient is a direct physical consequence of the rising mean temperature of the porous medium coupled with the requirement of zero mean flow. It may be viewed as a readjustment of the hydrostatic pressure due to the changing environment.

Given the above expressions, (23) and (24), the long-term values of \( Rb \) above which there is no convection are given by,

\[
\text{Case 1}: \quad Rb = \frac{1}{2} Ra, \quad \text{Case 2}: \quad Rb = \frac{1}{4} Ra. \quad (29)
\]

At earlier times we may calculate the values of \( \theta_{\text{max}} \) and \( \theta_{\text{min}} \) from Eqs. (21) and (22) to find the times at which convection starts, and the result of these computations are shown in Fig. 5. For a chosen value of \( Rb/Ra \) the fluid is stagnant until the appropriate curve is crossed after which convection ensues. The Figure confirms the bounds given in Eq. (29) which give the maximum values of \( Rb \) above which the fluid remains stagnant.

It is essential to determine where the yield surfaces are as a function of time. If we write those locations in terms of \( \eta \), then Eq. (6) gives the following two conditions:

\[ \theta(\eta_1, t) = \frac{p_x}{Ra} + \frac{Rb}{Ra}, \]  
(30)

and

\[ \theta(\eta_2, t) = \frac{p_x}{Ra} - \frac{Rb}{Ra}, \]  
(31)

where \( \eta_1 \) and \( \eta_2 \) are the two locations and where \( \eta_1 < \eta_2 \). The condition of zero fluid flux up the layer means that the following condition must be satisfied:

\[ \int_{0}^{\eta_1} \left[ \theta - \frac{p_x}{Ra} - \frac{Rb}{Ra} \right] d\eta + \int_{\eta_1}^{\eta_2} \left[ \theta - \frac{p_x}{Ra} + \frac{Rb}{Ra} \right] d\eta = 0. \]  
(32)

This becomes,

\[
2t^{1/2} \sum_{n=0}^{\infty} A_n \left[ i^2 \text{erfc} \left( \frac{n}{\sqrt{t}} \right) - n^2 \text{erfc} \left( \eta_1 + \frac{n}{\sqrt{t}} \right) + i^2 \text{erfc} \left( \eta_2 + \frac{n}{\sqrt{t}} \right) \right] \\
- i^2 \text{erfc} \left( \eta_3 + \frac{n}{\sqrt{t}} \right) - 2t^{1/2} \sum_{n=0}^{\infty} B_n \left[ i^2 \text{erfc} \left( \frac{n+1}{\sqrt{t}} \right) \right] \\
- i^2 \text{erfc} \left( \frac{n+1}{\sqrt{t}} - \eta_1 \right) + i^2 \text{erfc} \left( \frac{n+1}{\sqrt{t}} - \eta_2 \right) \\
- i^2 \text{erfc} \left( \frac{n+1}{\sqrt{t}} - \eta_3 \right) - (\eta_1 - \eta_2 + \eta_3) \frac{p_x}{Ra} \\
- (\eta_1 + \eta_2 - \eta_3) \frac{Rb}{Ra} = 0, \]  
(33)

where \( \eta_3 = 1/(2\sqrt{t}) \), which is equivalent to \( y = 1 \), and where the new coefficients, \( A_n \) and \( B_n \) are given by,

\[
\text{Case 1}: \quad A_n = (-1)^n, \quad B_n = (-1)^{n+1}, \quad \text{Case 2}: \quad A_n = B_n = 1. \quad (34)
\]

Eqs. (30), (31) and (33) may be solved for \( \eta_1, \eta_2 \) and \( p_x/Ra \) using a straightforward Newton–Raphson solver and the results obtained are essentially exact to near machine accuracy.

Figs. 6 and 7 show the evolution with time of the yield surface locations for a selection of values of \( Rb/Ra \) and for Cases 1 and 2, respectively. In both Figures the abscissa are \( \log_{10} t \) in order to view the evolution over three orders of magnitude. In addition each Figure has two curves corresponding to each value of \( Rb/Ra \); the channel is delineated into three regions the middle one of which is stagnant, while the one neighbouring the hot (cold) surface corresponds to upward (downward) flow. Thus, in Fig. 6 and for \( Rb/Ra \), the whole channel is stagnant until \( t \approx 0.0078540 \) (i.e. \( \log_{10} t \approx -2.10491 \)) after which the centreline of the stagnant plug moves rapidly from the cold surface towards the heated surface and then moves back towards the centre of the channel. For larger values of \( Rb/Ra \) the initial movement of the centre of the
plug becomes less rapid, but in all cases the yield surfaces are symmetrically placed about \( y = \frac{1}{2} \) when \( t \) is sufficiently large. More specifically they are located at

\[
y = \frac{1}{2} \cdot \frac{Rb}{Ra}
\]

(35)

This figure also shows clearly the increasing delay before convection sets in as \( Rb/Ra \) increases.

In Fig. 7 it is clear that there is almost no difference between Cases 1 and 2 at early times, and while the yield surfaces move more quickly to their ultimate positions within the channel for Case 2 when compared with Case 1, they are no longer located symmetrically about the centreline since the temperature profile is quadratic rather than linear.

Figs. 8 and 9 display information on how the hydrostatic gradient varies with time. For Case 1, which is shown in Fig. 8, we show the variation of \( p_x \). For each value of \( Rb/Ra \) the value of \( p_x \) is precisely equal to \( Rb \), and this arises because Eq. (26) must be satisfied and \( \theta_{\text{min}} = 0 \). As the mean temperature in the channel rises so does the hydrostatic pressure gradient, and eventually it tends towards \( 1/(2Ra) \). On the other hand such a simple analysis for Case 2 cannot be made because \( \theta_{\text{min}} \) is no longer zero, but eventually \( p_x \) rises linearly with time. As the overall temperature profile continues to rise, so does the value of \( p_x \), and therefore we have plotted the evolution with time of \( (p_x - t)/Ra \) in Fig. 9.

Finally, we turn to the induced velocity within the layer, and Figs. 10 and 11 show how the maximum and minimum velocities (which correspond to the boundaries, \( y = 0 \) and \( y = 1 \),
respectively) vary with time. For both cases we see clearly that flow up the heated surface is greater in magnitude than the flow down the other surface soon after convection begins. And, for relatively small values of $R_b/Ra$, the initial velocity of the flow down the cooler wall is much weaker than its warmer counterpart. As time progresses $u_{\text{max}}$ and $u_{\text{min}}$ tend towards the same magnitude for Case 1, which again reflects the symmetry of the final velocity profile. There remains a distinct asymmetry at late times for the Case 2 profiles. In these Figures we have also included the corresponding curves for Newtonian fluids for comparison.

5. Conclusions

We have studied the effect of the presence of a yield threshold on convection which is induced by suddenly heating a vertical surface bounding a porous medium with a uniform heat flux. Three cases were considered, namely an infinitely wide domain, and two different channels which are distinguished by having either a fixed cold temperature or an insulated boundary condition.

The temperature profile evolves in time in a manner which is independent of any fluid flow and these have been presented. By virtue of the fact that heat is being supplied continuously to the porous medium the fluid remains stagnant at early times because the resulting buoyancy forces are too weak to overcome the yield threshold. For the infinite domain convection will always happen eventually since the boundary temperature is proportional to $t^{1/2}$ and therefore buoyancy forces also rise without limit. On the other hand convection will arise only if $R_b < \frac{1}{2}Ra$ for Case 1 and if $R_b < \frac{1}{2}Ra$ for Case 2. These results are somewhat different from those obtained in Rees and Bassom [8] where the analogous cases were considered where the heated surface was held at a fixed temperature (though not the equivalent of the present Case 2). There it was found that there is a restriction on the value of $R_b/Ra$ even for the infinite domain. It was also found that convection, if it does arise, will begin immediately.

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Appendix A

The aim here is to solve (17) for $\eta_y$ for large values of $t$. Using the substitution (18), Eq. (17) becomes,

$$
\frac{2}{\sqrt{\pi}} e^{-\eta^2} - 2\eta_y \text{erfc}\eta_y = \frac{1}{\sqrt{\pi}}.
$$

(36)

We omit the details of our analysis, which follows closely that of [8], and we eventually obtain the following series:

$$
\eta_y = \delta^{-1/2} \left[ 1 + \frac{D}{2} \right] \delta - \frac{1}{8} D^2 + 4D + 6 \delta^2 + \frac{1}{16} (D^3 + 8D^2 + 26D + 33) \delta^3 + \cdots.
$$

(37)

Evaluation of the scaled mass flux given in Eq. (19) requires the evaluation of $\text{erf}\eta_y$. We find that,

$$
\frac{Q}{t} = 1 - \frac{1}{2(\tau\delta)^{1/2}} \left[ 2 + (D + 2) \delta - \left( \frac{1}{4} D^2 + 2D + \frac{9}{2} \right) \delta^2 + \cdots \right].
$$

(38)

In these two expressions we have defined $\delta$ and $D$ according to

$$
e^{-1/\delta} = \sqrt{\frac{\pi}{\delta}} \quad \text{(or $\delta = 2 / \ln(\tau/\pi)$)} \quad \text{and} \quad D = \ln \delta.
$$

(39)

Finally, the location of the yield surface in terms of $y$, may be found easily from Eq. (37) and the definition of $\eta$ to be given by

$$
y_y/Ra = 2\eta_y \sqrt{\tau}.
$$

(40)

References