

Do all sensible Galerkin methods converge for the  
standard 2nd kind boundary integral equations on  
Lipschitz domains?

Simon Chandler-Wilde

Department of Mathematics and  
Statistics  
University of Reading  
*s.n.chandler-wilde@reading.ac.uk*



Joint work with:  
Euan Spence (Bath)

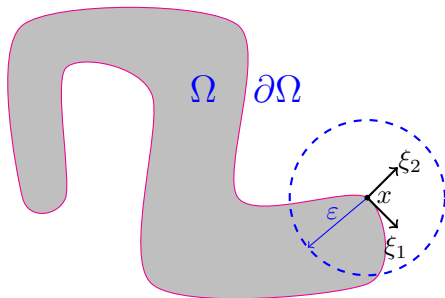
SIAM UKIE National Student Conference, Bath, June 2018

# Overview of the talk

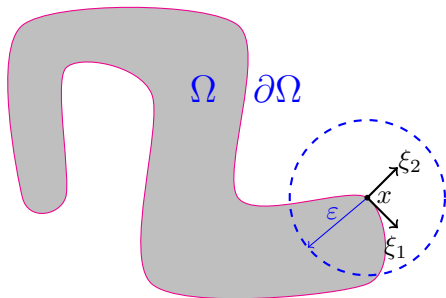
- 1 **Lipschitz domains** - the setting for modern PDE theory
  - What are Lipschitz domains?
  - What is the Lipschitz character of a Lipschitz domain?
- 2 **Potential theory and 2nd kind boundary integral equations (BIEs)**
  - A Dirichlet problem and 2nd kind BIE formulation
  - The Galerkin approximation to the BIE
  - **A long-standing open problem: do all “sensible” Galerkin methods converge?**
- 3 The **Hilbert space** theory of **Galerkin methods**
  - Definitions of bounded, compact, coercive
  - Galerkin methods and their convergence
- 4 **Do all sensible Galerkin methods converge for the standard 2nd kind BIEs?**
  - Previous results
  - **Solving the open problem:** Constructing  $\Omega$  for which  $A = I - D$  is not coercive + compact so not all sensible Galerkin methods converge

# Overview of the talk

- 1 **Lipschitz domains** - the setting for modern PDE theory
  - What are Lipschitz domains?
  - What is the Lipschitz character of a Lipschitz domain?
- 2 **Potential theory and 2nd kind boundary integral equations (BIEs)**
  - A Dirichlet problem and 2nd kind BIE formulation
  - The Galerkin approximation to the BIE
  - **A long-standing open problem: do all “sensible” Galerkin methods converge?**
- 3 The **Hilbert space** theory of **Galerkin methods**
  - Definitions of bounded, compact, coercive
  - Galerkin methods and their convergence
- 4 **Do all sensible Galerkin methods converge for the standard 2nd kind BIEs?**
  - Previous results
  - **Solving the open problem:** Constructing  $\Omega$  for which  $A = I - D$  is not coercive + compact so not all sensible Galerkin methods converge



A bounded domain  $\Omega \subset \mathbb{R}^2$  is **Lipschitz** if, in a neighbourhood of each point  $x \in \partial\Omega$ ,  $\partial\Omega$  is the graph of a **Lipschitz continuous function**  $f$ , with respect to some rotated coordinate system  $0\xi_1\xi_2$ , with  $\Omega$  on precisely one side of  $\partial\Omega$ .



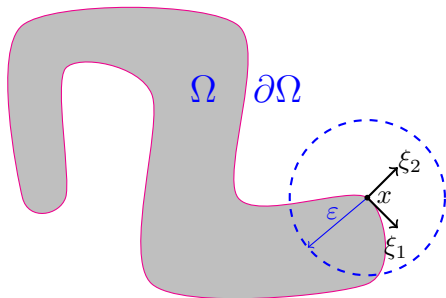
A bounded domain  $\Omega \subset \mathbb{R}^2$  is **Lipschitz** if, in a neighbourhood of each point  $x \in \partial\Omega$ ,  $\partial\Omega$  is the graph of a **Lipschitz continuous function**  $f$ , with respect to some rotated coordinate system  $0\xi_1\xi_2$ , with  $\Omega$  on precisely one side of  $\partial\Omega$ .

In equations,

$$\partial\Omega \cap B_\epsilon(x) = \{(\xi_1, f(\xi_1)) : \xi_1 \in \mathbb{R}\} \cap B_\epsilon(x),$$

for some  $f$  that satisfies, for some  $L > 0$  (the **Lipschitz constant**)

$$|f(s) - f(t)| \leq L|s - t|, \quad \text{for } s, t \in \mathbb{R}. \quad (*)$$



A bounded domain  $\Omega \subset \mathbb{R}^2$  is **Lipschitz** if, in a neighbourhood of each point  $x \in \partial\Omega$ ,  $\partial\Omega$  is the graph of a **Lipschitz continuous function**  $f$ , with respect to some rotated coordinate system  $0\xi_1\xi_2$ , with  $\Omega$  on precisely one side of  $\partial\Omega$ .

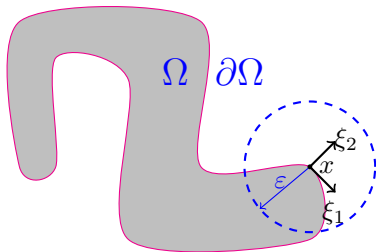
In equations,

$$\partial\Omega \cap B_\epsilon(x) = \{(\xi_1, f(\xi_1)) : \xi_1 \in \mathbb{R}\} \cap B_\epsilon(x),$$

for some  $f$  that satisfies, for some  $L > 0$  (the **Lipschitz constant**)

$$|f(s) - f(t)| \leq L|s - t|, \quad \text{for } s, t \in \mathbb{R}. \quad (*)$$

A Lipschitz continuous function is differentiable almost everywhere. Indeed,  $(*)$  holds iff  $|f'(s)| \leq L$ , for almost all  $s \in \mathbb{R}$ .



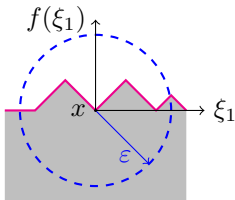
In equations,

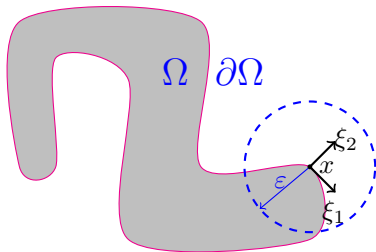
$$\partial\Omega \cap B_\epsilon(x) = \{(\xi_1, f(\xi_1)) : \xi_1 \in \mathbb{R}\} \cap B_\epsilon(x),$$

for some  $f$  that satisfies, for some  $L > 0$  (the **Lipschitz constant**)

$$|f(s) - f(t)| \leq L|s - t|, \quad \text{for } s, t \in \mathbb{R}.$$

This **allows corners**, e.g. this  $f$  has  $L = 1$  ...





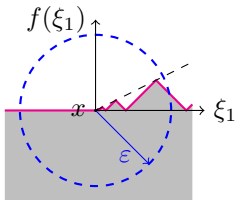
In equations,

$$\partial\Omega \cap B_\epsilon(x) = \{(\xi_1, f(\xi_1)) : \xi_1 \in \mathbb{R}\} \cap B_\epsilon(x),$$

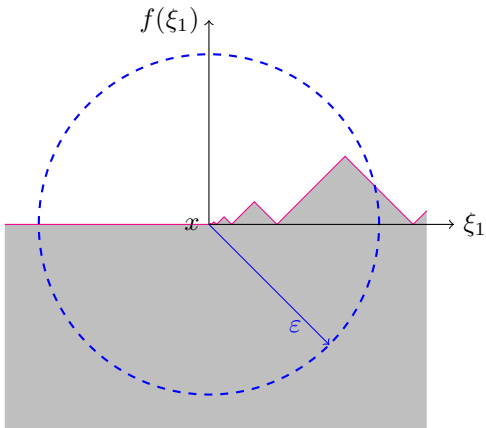
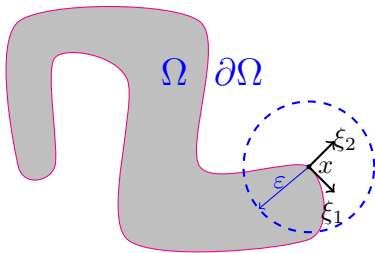
for some  $f$  that satisfies, for some  $L > 0$  (the **Lipschitz constant**)

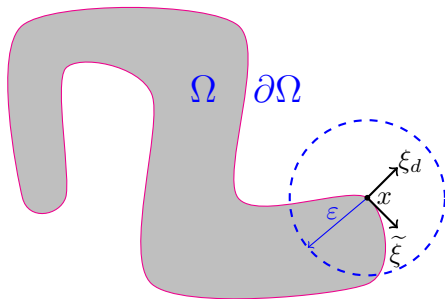
$$|f(s) - f(t)| \leq L|s - t|, \quad \text{for } s, t \in \mathbb{R}.$$

Indeed it allows **infinitely many corners**, e.g. this  $f$  also has  $L = 1$  ...

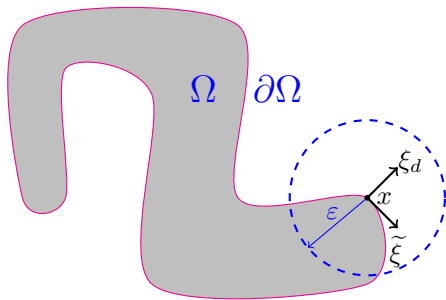








A bounded domain  $\Omega \subset \mathbb{R}^d$  is **Lipschitz** if, in a neighbourhood of each point  $x \in \partial\Omega$ ,  $\partial\Omega$  is the graph of a **Lipschitz continuous function**  $f$ , with respect to some rotated coordinate system  $0\xi_1 \dots \xi_d$ , with  $\Omega$  on precisely one side of  $\partial\Omega$ .



A bounded domain  $\Omega \subset \mathbb{R}^d$  is **Lipschitz** if, in a neighbourhood of each point  $x \in \partial\Omega$ ,  $\partial\Omega$  is the graph of a **Lipschitz continuous function**  $f$ , with respect to some rotated coordinate system  $0\xi_1 \dots \xi_d$ , with  $\Omega$  on precisely one side of  $\partial\Omega$ .

In equations, where  $\tilde{\xi} = (\xi_1, \dots, \xi_{d-1})$  (e.g.  $\tilde{\xi} = \xi_1$  in 2D),

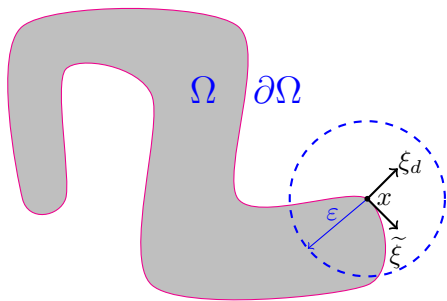
$$\partial\Omega \cap B_\epsilon(x) = \{(\tilde{\xi}, f(\tilde{\xi})) : \tilde{\xi} \in \mathbb{R}^{d-1}\} \cap B_\epsilon(x),$$

for some  $f$  that satisfies, for some  $L > 0$  (the **Lipschitz constant**)

$$|f(s) - f(t)| \leq L|s - t|, \quad \text{for } s, t \in \mathbb{R}^{d-1}.$$

# Where are we in this talk?

- 1 **Lipschitz domains** - the setting for modern PDE theory
  - What are Lipschitz domains?
  - What is the Lipschitz character of a Lipschitz domain?
- 2 **Potential theory and 2nd kind boundary integral equations (BIEs)**
  - A Dirichlet problem and 2nd kind BIE formulation
  - The Galerkin approximation to the BIE
  - **A long-standing open problem: do all “sensible” Galerkin methods converge?**
- 3 The **Hilbert space** theory of **Galerkin methods**
  - Definitions of bounded, compact, coercive
  - Galerkin methods and their convergence
- 4 **Do all sensible Galerkin methods converge for the standard 2nd kind BIEs?**
  - Previous results
  - **Solving the open problem:** Constructing  $\Omega$  for which  $A = I - D$  is not coercive + compact so not all sensible Galerkin methods converge



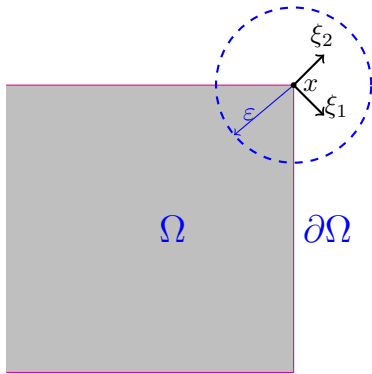
In equations, where  $\tilde{\xi} = (\xi_1, \dots, \xi_{d-1})$  (e.g.  $\tilde{\xi} = \xi_1$  in 2D),

$$\partial\Omega \cap B_\epsilon(x) = \{(\tilde{\xi}, f(\tilde{\xi})) : \tilde{\xi} \in \mathbb{R}^{d-1}\} \cap B_\epsilon(x), \quad (X)$$

for some  $f$  that satisfies, for some  $L > 0$  (the **Lipschitz constant**)

$$|f(s) - f(t)| \leq L|s - t|, \quad \text{for } s, t \in \mathbb{R}^{d-1}. \quad (*)$$

The **Lipschitz character** of  $\Omega$ ,  $\text{char}(\Omega)$ , is the infimum of the  $L$  such that for every  $x \in \partial\Omega$  there exists  $\epsilon > 0$  and coordinates  $0\xi_1\xi_2$  such that (X) and (\*) hold.



In equations, where  $\tilde{\xi} = (\xi_1, \dots, \xi_{d-1})$  (e.g.  $\tilde{\xi} = \xi_1$  in 2D),

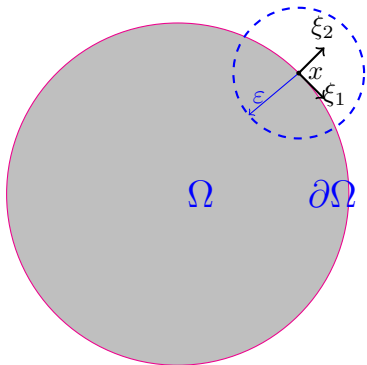
$$\partial\Omega \cap B_\epsilon(x) = \{(\tilde{\xi}, f(\tilde{\xi})) : \tilde{\xi} \in \mathbb{R}^{d-1}\} \cap B_\epsilon(x),$$

for some  $f$  that satisfies, for some  $L > 0$  (the **Lipschitz constant**)

$$|f(s) - f(t)| \leq L|s - t|, \quad \text{for } s, t \in \mathbb{R}^{d-1}. \quad (*)$$

The **Lipschitz character** of  $\Omega$ ,  $\text{char}(\Omega)$ , is the infimum of the  $L$  such that for every  $x \in \partial\Omega$  there exists  $\epsilon > 0$  and coordinates  $0 \leq \xi_1 \leq \xi_2$  such that  $(X)$  and  $(*)$  hold.

A **square** has **Lipschitz character**  $\text{char}(\Omega) = 1$  (and a **cube** has  $\text{char}(\Omega) = \sqrt{2}$ ).



In equations, where  $\tilde{\xi} = (\xi_1, \dots, \xi_{d-1})$  (e.g.  $\tilde{\xi} = \xi_1$  in 2D),

$$\partial\Omega \cap B_\epsilon(x) = \{(\tilde{\xi}, f(\tilde{\xi})) : \tilde{\xi} \in \mathbb{R}^{d-1}\} \cap B_\epsilon(x), \quad (X)$$

for some  $f$  that satisfies, for some  $L > 0$  (the **Lipschitz constant**)

$$|f(s) - f(t)| \leq L|s - t|, \quad \text{for } s, t \in \mathbb{R}^{d-1}. \quad (*)$$

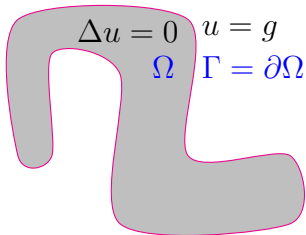
The **Lipschitz character** of  $\Omega$ ,  $\text{char}(\Omega)$ , is the infimum of the  $L$  such that for every  $x \in \partial\Omega$  there exists  $\epsilon > 0$  and coordinates  $0\xi_1\xi_2$  such that (X) and (\*) hold.

A smooth ( $C^1$ ) boundary has **Lipschitz character**  $\text{char}(\Omega) = 0$ .

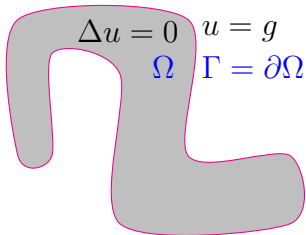
# Where are we in this talk?

- 1 **Lipschitz domains** - the setting for modern PDE theory
  - What are Lipschitz domains?
  - What is the Lipschitz character of a Lipschitz domain?
- 2 **Potential theory and 2nd kind boundary integral equations (BIEs)**
  - A Dirichlet problem and 2nd kind BIE formulation
  - The Galerkin approximation to the BIE
  - **A long-standing open problem: do all “sensible” Galerkin methods converge?**
- 3 The **Hilbert space** theory of **Galerkin methods**
  - Definitions of bounded, compact, coercive
  - Galerkin methods and their convergence
- 4 **Do all sensible Galerkin methods converge for the standard 2nd kind BIEs?**
  - Previous results
  - **Solving the open problem:** Constructing  $\Omega$  for which  $A = I - D$  is not coercive + compact so not all sensible Galerkin methods converge



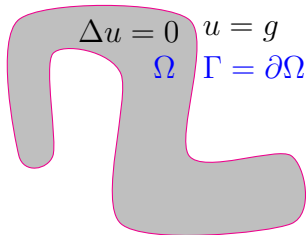


Assume that  $\Omega \subset \mathbb{R}^d$  ( $d = 2$  or  $3$ ) is **bounded** and **Lipschitz**, and  $g \in L^2(\Gamma)$ .



Assume that  $\Omega \subset \mathbb{R}^d$  ( $d = 2$  or  $3$ ) is **bounded** and **Lipschitz**, and  $g \in L^2(\Gamma)$ .

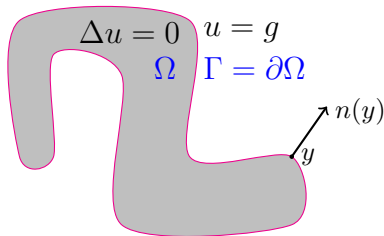
**BVP:** Find  $u \in C^2(\Omega)$  such that  $\Delta u = 0$  in  $\Omega$  and  $u = g$  on  $\Gamma$ .



**BVP:** Find  $u \in C^2(\Omega)$  such that  $\Delta u = 0$  in  $\Omega$  and  $u = g$  on  $\Gamma$ .

Define the **fundamental solution**

$$G(x, y) := \begin{cases} -\frac{1}{\pi} \log|x - y|, & d = 2, \\ (2\pi|x - y|)^{-1}, & d = 3, \end{cases}$$



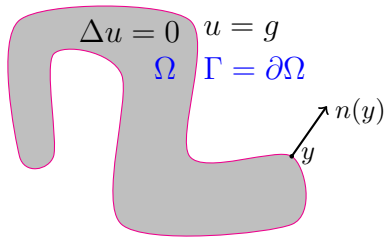
**BVP:** Find  $u \in C^2(\Omega)$  such that  $\Delta u = 0$  in  $\Omega$  and  $u = g$  on  $\Gamma$ .

Define the **fundamental solution**

$$G(x, y) := \begin{cases} -\frac{1}{\pi} \log |x - y|, & d = 2, \\ (2\pi |x - y|)^{-1}, & d = 3, \end{cases}$$

Look for a solution as the **double-layer potential** with density  $\phi \in L^2(\Gamma)$  (which satisfies  $\Delta u = 0$  in  $\Omega$ ):

$$u(x) = \int_{\Gamma} \frac{\partial G(x, y)}{\partial n(y)} \phi(y) \, ds(y), \quad x \in \Omega.$$



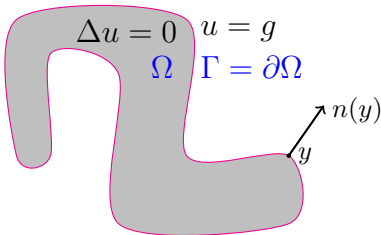
**BVP:** Find  $u \in C^2(\Omega)$  such that  $\Delta u = 0$  in  $\Omega$  and  $u = g$  on  $\Gamma$ .

Look for a solution as the **double-layer potential** with density  $\phi \in L^2(\Gamma)$  (which satisfies  $\Delta u = 0$  in  $\Omega$ ):

$$u(x) = \int_{\Gamma} \frac{\partial G(x, y)}{\partial n(y)} \phi(y) ds(y), \quad x \in \Omega.$$

This satisfies the BVP iff  $\phi$  satisfies the **boundary integral equation (BIE)**

$$\phi(x) - \int_{\Gamma} \frac{\partial G(x, y)}{\partial n(y)} \phi(y) ds(y) = -2g(x), \quad x \in \Gamma.$$



Look for a solution as the **double-layer potential** with density  $\phi \in L^2(\Gamma)$ :

$$u(x) = \int_{\Gamma} \frac{\partial G(x, y)}{\partial n(y)} \phi(y) ds(y), \quad x \in \Omega.$$

This satisfies the BVP iff  $\phi$  satisfies the **boundary integral equation (BIE)**

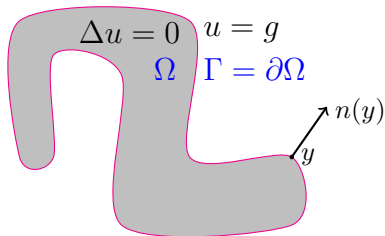
$$\phi(x) - \int_{\Gamma} \frac{\partial G(x, y)}{\partial n(y)} \phi(y) ds(y) = -2g(x), \quad x \in \Gamma,$$

in operator form

$$\phi - D\phi = -2g \quad \text{or} \quad A\phi = -2g,$$

where  $A = I - D$ ,  $I$  is the identity operator, and  $D$  is the **double-layer potential operator** given by

$$D\phi(x) = \int_{\Gamma} \frac{\partial G(x, y)}{\partial n(y)} \phi(y) ds(y), \quad x \in \Gamma, \quad \phi \in L^2(\Gamma).$$



The double-layer potential satisfies the BVP iff  $\phi$  satisfies the **BIE**

$$\phi(x) - \int_{\Gamma} \frac{\partial G(x, y)}{\partial n(y)} \phi(y) ds(y) = -2g(x), \quad x \in \Gamma,$$

in operator form

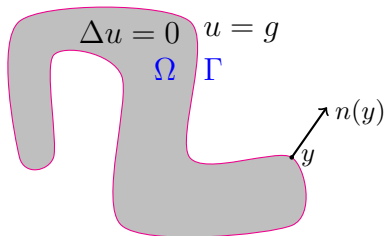
$$\phi - D\phi = -2g \quad \text{or} \quad A\phi = -2g,$$

where  $A = I - D$ . The **Galerkin method** for solving the BIE numerically is: choose a basis  $v_1, \dots, v_N$  for a linear subspace  $V_N$  of  $L^2(\Gamma)$  and approximate

$$\phi \approx \phi_N := \sum_{n=1}^N \alpha_n v_n,$$

choosing the coefficients  $\alpha_1, \dots, \alpha_N \in \mathbb{C}$  so that

$$\int_{\Gamma} A\phi_N \overline{v_m} ds = -2 \int_{\Gamma} g \overline{v_m} ds, \quad m = 1, \dots, N.$$



The double-layer potential satisfies the BVP iff  $\phi$  satisfies the **BIE** in operator form

$$\phi - D\phi = -2g \quad \text{or} \quad A\phi = -2g,$$

where  $A = I - D$ . The **Galerkin method** for solving the BIE numerically is: choose a basis  $v_1, \dots, v_N$  for a linear subspace  $V_N$  of  $L^2(\Gamma)$  and approximate

$$\phi \approx \phi_N := \sum_{n=1}^N \alpha_n v_n,$$

choosing the coefficients  $\alpha_1, \dots, \alpha_N \in \mathbb{C}$  so that

$$\int_{\Gamma} A\phi_N \overline{v_m} \, ds = -2 \int_{\Gamma} g \overline{v_m} \, ds, \quad m = 1, \dots, N.$$

**Long-standing open problem.** Do all sensible Galerkin methods converge?



# Where are we in this talk?

- 1 **Lipschitz domains** - the setting for modern PDE theory
  - What are Lipschitz domains?
  - What is the Lipschitz character of a Lipschitz domain?
- 2 **Potential theory and 2nd kind boundary integral equations (BIEs)**
  - A Dirichlet problem and 2nd kind BIE formulation
  - The Galerkin approximation to the BIE
  - **A long-standing open problem: do all “sensible” Galerkin methods converge?**
- 3 The **Hilbert space** theory of **Galerkin methods**
  - Definitions of bounded, compact, coercive
  - Galerkin methods and their convergence
- 4 **Do all sensible Galerkin methods converge for the standard 2nd kind BIEs?**
  - Previous results
  - **Solving the open problem:** Constructing  $\Omega$  for which  $A = I - D$  is not coercive + compact so not all sensible Galerkin methods converge

$H$  is a **complex Hilbert space** with inner product  $(u, v)$  and norm  $\|u\| = \sqrt{(u, u)}$ , e.g.

$$H = L^2(\Gamma), \quad (u, v) = \int_{\Gamma} u \bar{v} \, ds, \quad \|u\|^2 = \int_{\Gamma} |u|^2 \, ds.$$

$H$  is a **complex Hilbert space** with inner product  $(u, v)$  and norm  $\|u\| = \sqrt{(u, u)}$ , e.g.

$$H = L^2(\Gamma), \quad (u, v) = \int_{\Gamma} u \bar{v} \, ds, \quad \|u\|^2 = \int_{\Gamma} |u|^2 \, ds.$$

Suppose that  $A$  is a **bounded linear operator** on  $H$ , i.e.

$$A(\lambda u) = \lambda Au, \quad A(u + v) = Au + Av, \quad \forall \lambda \in \mathbb{C}, \quad u, v \in H,$$

and, for some  $C \geq 0$ ,

$$\|Au\| \leq C\|u\|, \quad \forall u \in H.$$

The **norm** of  $A$  is

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$H$  is a **complex Hilbert space** with inner product  $(u, v)$  and norm  $\|u\| = \sqrt{(u, u)}$ , e.g.

$$H = L^2(\Gamma), \quad (u, v) = \int_{\Gamma} u\bar{v} \, ds, \quad \|u\|^2 = \int_{\Gamma} |u|^2 \, ds.$$

Suppose that  $A$  is a **bounded linear operator** on  $H$ , i.e.

$$A(\lambda u) = \lambda Au, \quad A(u + v) = Au + Av, \quad \forall \lambda \in \mathbb{C}, \quad u, v \in H,$$

and, for some  $C \geq 0$ ,

$$\|Au\| \leq C\|u\|, \quad \forall u \in H.$$

The **norm** of  $A$  is

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$A$  is **finite rank** if the **range of**  $A$ ,  $A(H) := \{Au : u \in H\}$ , has finite dimension.

$H$  is a **complex Hilbert space** with inner product  $(u, v)$  and norm  $\|u\| = \sqrt{(u, u)}$ , e.g.

$$H = L^2(\Gamma), \quad (u, v) = \int_{\Gamma} u \bar{v} \, ds, \quad \|u\|^2 = \int_{\Gamma} |u|^2 \, ds.$$

Suppose that  $A$  is a **bounded linear operator** on  $H$ , i.e.

$$A(\lambda u) = \lambda Au, \quad A(u + v) = Au + Av, \quad \forall \lambda \in \mathbb{C}, \quad u, v \in H,$$

and, for some  $C \geq 0$ ,

$$\|Au\| \leq C\|u\|, \quad \forall u \in H.$$

The **norm** of  $A$  is

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$A$  is **finite rank** if the **range of**  $A$ ,  $A(H) := \{Au : u \in H\}$ , has finite dimension.

$A$  is **compact** if, for some sequence of finite rank operators  $A_1, A_2, \dots$ , it holds that  $\|A - A_n\| \rightarrow 0$  as  $n \rightarrow \infty$ .

$H$  is a **complex Hilbert space** with inner product  $(u, v)$  and norm  $\|u\| = \sqrt{(u, u)}$ , e.g.

$$H = L^2(\Gamma), \quad (u, v) = \int_{\Gamma} u \bar{v} \, ds, \quad \|u\|^2 = \int_{\Gamma} |u|^2 \, ds.$$

Suppose that  $A$  is a **bounded linear operator** on  $H$ , with **norm**

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$A$  is **coercive** if, for some  $\gamma > 0$ ,

$$|(Au, u)| \geq \gamma \|u\|^2, \quad \forall u \in H.$$

$H$  is a **complex Hilbert space** with inner product  $(u, v)$  and norm  $\|u\| = \sqrt{(u, u)}$ , e.g.

$$H = L^2(\Gamma), \quad (u, v) = \int_{\Gamma} u \bar{v} \, ds, \quad \|u\|^2 = \int_{\Gamma} |u|^2 \, ds.$$

Suppose that  $A$  is a **bounded linear operator** on  $H$ , with **norm**

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$A$  is **coercive** if, for some  $\gamma > 0$ ,

$$|(Au, u)| \geq \gamma \|u\|^2, \quad \forall u \in H.$$

E.g. if  $A = I - B$ , where  $I$  is the identity operator and  $B$  is bounded,

$$\begin{aligned} (Au, u) = (u - Bu, u) &= (u, u) - (Bu, u) \\ &= \|u\|^2 - (Bu, u) \\ &\geq \|u\|^2 - |(Bu, u)| \end{aligned}$$

$H$  is a **complex Hilbert space** with inner product  $(u, v)$  and norm  $\|u\| = \sqrt{(u, u)}$ , e.g.

$$H = L^2(\Gamma), \quad (u, v) = \int_{\Gamma} u \bar{v} \, ds, \quad \|u\|^2 = \int_{\Gamma} |u|^2 \, ds.$$

Suppose that  $A$  is a **bounded linear operator** on  $H$ , with **norm**

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$A$  is **coercive** if, for some  $\gamma > 0$ ,

$$|(Au, u)| \geq \gamma \|u\|^2, \quad \forall u \in H.$$

E.g. if  $A = I - B$ , where  $I$  is the identity operator and  $B$  is bounded,

$$\begin{aligned} (Au, u) = (u - Bu, u) &= (u, u) - (Bu, u) \\ &= \|u\|^2 - (Bu, u) \\ &\geq \|u\|^2 - |(Bu, u)| \\ &\geq \|u\|^2 - \|Bu\| \|u\| \quad (\text{Cauchy-Schwarz}) \end{aligned}$$



$H$  is a **complex Hilbert space** with inner product  $(u, v)$  and norm  $\|u\| = \sqrt{(u, u)}$ , e.g.

$$H = L^2(\Gamma), \quad (u, v) = \int_{\Gamma} u \bar{v} \, ds, \quad \|u\|^2 = \int_{\Gamma} |u|^2 \, ds.$$

Suppose that  $A$  is a **bounded linear operator** on  $H$ , with **norm**

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$A$  is **coercive** if, for some  $\gamma > 0$ ,

$$|(Au, u)| \geq \gamma \|u\|^2, \quad \forall u \in H.$$

E.g. if  $A = I - B$ , where  $I$  is the identity operator and  $B$  is bounded,

$$\begin{aligned} (Au, u) = (u - Bu, u) &= (u, u) - (Bu, u) \\ &= \|u\|^2 - (Bu, u) \\ &\geq \|u\|^2 - |(Bu, u)| \\ &\geq \|u\|^2 - \|Bu\| \|u\| \quad (\text{Cauchy-Schwarz}) \\ &\geq \|u\|^2 - \|B\| \|u\|^2 \quad (\text{Definition of } \|B\|) \\ &= (1 - \|B\|) \|u\|^2. \end{aligned}$$

$H$  is a **complex Hilbert space** with inner product  $(u, v)$  and norm  $\|u\| = \sqrt{(u, u)}$ , e.g.

$$H = L^2(\Gamma), \quad (u, v) = \int_{\Gamma} u \bar{v} \, ds, \quad \|u\|^2 = \int_{\Gamma} |u|^2 \, ds.$$

Suppose that  $A$  is a **bounded linear operator** on  $H$ , with **norm**

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$A$  is **coercive** if, for some  $\gamma > 0$ ,

$$|(Au, u)| \geq \gamma \|u\|^2, \quad \forall u \in H.$$

E.g. if  $A = I - B$ , where  $I$  is the identity operator and  $B$  is bounded,

$$\begin{aligned} (Au, u) = (u - Bu, u) &= (u, u) - (Bu, u) \\ &= \|u\|^2 - (Bu, u) \\ &\geq \|u\|^2 - |(Bu, u)| \\ &\geq \|u\|^2 - \|Bu\| \|u\| \quad (\text{Cauchy-Schwarz}) \\ &\geq \|u\|^2 - \|B\| \|u\|^2 \quad (\text{Definition of } \|B\|) \\ &= (1 - \|B\|) \|u\|^2. \end{aligned}$$

So  $A = I - B$  is coercive if  $\|B\| < 1$ , with  $\gamma = 1 - \|B\|$ .

Suppose that  $A$  is a **bounded linear operator** on  $H$ , with **norm**

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$A$  is **invertible** if

$$Au = g$$

has exactly one solution  $u \in H$  for every  $g \in H$ , i.e. if  $A : H \rightarrow H$  is **bijective**, in which case (the **Banach theorem**)  $A$  has a **bounded inverse**  $A^{-1}$ .

Suppose that  $A$  is a **bounded linear operator** on  $H$ , with **norm**

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$A$  is **invertible** if

$$Au = g$$

has exactly one solution  $u \in H$  for every  $g \in H$ , i.e. if  $A : H \rightarrow H$  is **bijective**, in which case (the **Banach theorem**)  $A$  has a **bounded inverse**  $A^{-1}$ .

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

Suppose that  $A$  is a **bounded linear operator** on  $H$ , with **norm**

$$\|A\| := \sup_{u \in H \setminus \{0\}} \frac{\|Au\|}{\|u\|}.$$

$A$  is **invertible** if

$$Au = g$$

has exactly one solution  $u \in H$  for every  $g \in H$ , i.e. if  $A : H \rightarrow H$  is **bijective**, in which case (the **Banach theorem**)  $A$  has a **bounded inverse**  $A^{-1}$ .

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

If  $\{v_1, \dots, v_N\}$  is a basis for  $V_N$ , in which case  $u_N = \sum_{n=1}^N \alpha_n v_n$ , for some  $\alpha_n \in \mathbb{C}$ , then (G) is equivalent to

$$\sum_{n=1}^N (Av_n, v_m) \alpha_n = (g, v_m), \quad m = 1, \dots, N.$$

$A$  is **invertible** if

$$Au = g$$

has exactly one solution  $u \in H$  for every  $v \in H$ , i.e. if  $A : H \rightarrow H$  is **bijective**, in which case (the **Banach theorem**)  $A$  has a **bounded inverse**  $A^{-1}$ .

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

$A$  is **invertible** if

$$Au = g$$

has exactly one solution  $u \in H$  for every  $v \in H$ , i.e. if  $A : H \rightarrow H$  is **bijective**, in which case (the **Banach theorem**)  $A$  has a **bounded inverse**  $A^{-1}$ .

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

We will say that the **Galerkin method is convergent for the sequence  $V$**  if, for every  $g \in H$ ,  $(G)$  has a unique solution for all sufficiently large  $N$  and  $u_N \rightarrow u = A^{-1}g$  as  $N \rightarrow \infty$ .

$A$  is **invertible** if

$$Au = g$$

has exactly one solution  $u \in H$  for every  $v \in H$ , i.e. if  $A : H \rightarrow H$  is **bijective**, in which case (the **Banach theorem**)  $A$  has a **bounded inverse**  $A^{-1}$ .

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

We will say that the **Galerkin method is convergent for the sequence  $V$**  if, for every  $g \in H$ ,  $(G)$  has a unique solution for all sufficiently large  $N$  and  $u_N \rightarrow u = A^{-1}g$  as  $N \rightarrow \infty$ .

We will say that  $V$  **converges to  $H$**  if, for every  $u \in H$ ,

$$\inf_{v \in V_N} \|u - v\| \rightarrow 0 \quad \text{as } N \rightarrow \infty.$$

It is easy to see that a **necessary condition** for the convergence of the Galerkin method is that  $V$  converges to  $H$ .



**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

**The Main Abstract Theorem on the Galerkin Method.**

**Part a).** If  $A$  is invertible then there exists a sequence  $V = (V_1, V_2, \dots)$  for which the Galerkin method converges.

*This is interesting theoretically, but not helpful for computation.*

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

**The Main Abstract Theorem on the Galerkin Method.**

**Part a).** If  $A$  is invertible then there exists a sequence  $V = (V_1, V_2, \dots)$  for which the Galerkin method converges.

*This is interesting theoretically, but not helpful for computation.*

**Part b) (Céa's Lemma).** If  $A$  is coercive then, for every sequence  $V$ ,  $(G)$  has a unique solution  $u_N$  for every  $N$  and

$$\|u - u_N\| \leq \frac{\|A\|}{\gamma} \inf_{v \in V_N} \|u - v\|,$$

so  $u_N \rightarrow u = A^{-1}g$  as  $N \rightarrow \infty$  if  $V$  converges to  $H$ .

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

**The Main Abstract Theorem on the Galerkin Method.**

**Part a).** If  $A$  is invertible then there exists a sequence  $V = (V_1, V_2, \dots)$  for which the Galerkin method converges.

*This is interesting theoretically, but not helpful for computation.*

**Part b) (Céa's Lemma).** If  $A$  is coercive then, for every sequence  $V$ ,  $(G)$  has a unique solution  $u_N$  for every  $N$  and

$$\|u - u_N\| \leq \frac{\|A\|}{\gamma} \inf_{v \in V_N} \|u - v\|,$$

so  $u_N \rightarrow u = A^{-1}g$  as  $N \rightarrow \infty$  if  $V$  converges to  $H$ .

*This is a fantastically explicit result – provided  $A$  is coercive.*

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

**The Main Abstract Theorem on the Galerkin Method.**

**Part a).** If  $A$  is invertible then there exists a sequence  $V = (V_1, V_2, \dots)$  for which the Galerkin method converges.

*This is interesting theoretically, but not helpful for computation.*

**Part b) (Céa's Lemma).** If  $A$  is coercive then, for every sequence  $V$ , (G) has a unique solution  $u_N$  for every  $N$  and

$$\|u - u_N\| \leq \frac{\|A\|}{\gamma} \inf_{v \in V_N} \|u - v\|,$$

so  $u_N \rightarrow u = A^{-1}g$  as  $N \rightarrow \infty$  if  $V$  converges to  $H$ .

*This is a fantastically explicit result – provided  $A$  is coercive.*

**Part c).** If  $A$  is invertible then the following statements are equivalent:

- The Galerkin method converges for every  $V$  that converges to  $H$ .
- $A = A_0 + K$  where  $A_0$  is **coercive** and  $K$  is **compact**.

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

**The Main Abstract Theorem on the Galerkin Method.**

**Part a).** If  $A$  is invertible then there exists a sequence  $V = (V_1, V_2, \dots)$  for which the Galerkin method converges.

*This is interesting theoretically, but not helpful for computation.*

**Part b) (Céa's Lemma).** If  $A$  is coercive then, for every sequence  $V$ ,  $(G)$  has a unique solution  $u_N$  for every  $N$  and

$$\|u - u_N\| \leq \frac{\|A\|}{\gamma} \inf_{v \in V_N} \|u - v\|,$$

so  $u_N \rightarrow u = A^{-1}g$  as  $N \rightarrow \infty$  if  $V$  converges to  $H$ .

*This is a fantastically explicit result – provided  $A$  is coercive.*

**Part c).** If  $A$  is invertible then the following statements are equivalent:

- The Galerkin method converges for every  $V$  that converges to  $H$ .
- $A = A_0 + K$  where  $A_0$  is **coercive** and  $K$  is **compact**.

*This is almost as strong a result as Part b), with weaker requirements on  $A$ .*

# Where are we in this talk?

- 1 **Lipschitz domains** - the setting for modern PDE theory
  - What are Lipschitz domains?
  - What is the Lipschitz character of a Lipschitz domain?
- 2 **Potential theory and 2nd kind boundary integral equations (BIEs)**
  - A Dirichlet problem and 2nd kind BIE formulation
  - The Galerkin approximation to the BIE
  - **A long-standing open problem: do all “sensible” Galerkin methods converge?**
- 3 The **Hilbert space** theory of **Galerkin methods**
  - Definitions of bounded, compact, coercive
  - Galerkin methods and their convergence
- 4 **Do all sensible Galerkin methods converge for the standard 2nd kind BIEs?**
  - Previous results
  - **Solving the open problem:** Constructing  $\Omega$  for which  $A = I - D$  is not coercive + compact so not all sensible Galerkin methods converge

**What is known about the double-layer potential operator  $D$  and  $A = I - D$  when  $\Omega$  is Lipschitz?** Remember the BIE in operator form is  $A\phi = -2g$ .

**What is known about the double-layer potential operator  $D$  and  $A = I - D$  when  $\Omega$  is Lipschitz?** Remember the BIE in operator form is  $A\phi = -2g$ .

- $A$  is a bounded linear operator on  $L^2(\Gamma)$  if  $\Omega$  is a bounded Lipschitz domain
  - Calderón *Proc. Nat. Acad. Sci.* 1977, for  $\text{char}(\Omega)$  sufficiently small
  - Coifman, McIntosh, Meyer *Ann. Math.* 1982, for the general case
  - Verchota *J. Funct. Anal.* 1984, in fact  $A$  is bounded on  $H^s(\Gamma)$ ,  $0 \leq s \leq 1$ .



**What is known about the double-layer potential operator  $D$  and  $A = I - D$  when  $\Omega$  is Lipschitz?** Remember the BIE in operator form is  $A\phi = -2g$ .

- $A$  is a bounded linear operator on  $L^2(\Gamma)$  if  $\Omega$  is a bounded Lipschitz domain
  - Calderón *Proc. Nat. Acad. Sci.* 1977, for  $\text{char}(\Omega)$  sufficiently small
  - Coifman, McIntosh, Meyer *Ann. Math.* 1982, for the general case
  - Verchota *J. Funct. Anal.* 1984, in fact  $A$  is bounded on  $H^s(\Gamma)$ ,  $0 \leq s \leq 1$ .
- $A$  is invertible on  $L^2(\Gamma)$  (Verchota *J. Funct. Anal.* 1984)

**What is known about the double-layer potential operator  $D$  and  $A = I - D$  when  $\Omega$  is Lipschitz?** Remember the BIE in operator form is  $A\phi = -2g$ .

- $A$  is a bounded linear operator on  $L^2(\Gamma)$  if  $\Omega$  is a bounded Lipschitz domain
  - Calderón *Proc. Nat. Acad. Sci.* 1977, for  $\text{char}(\Omega)$  sufficiently small
  - Coifman, McIntosh, Meyer *Ann. Math.* 1982, for the general case
  - Verchota *J. Funct. Anal.* 1984, in fact  $A$  is bounded on  $H^s(\Gamma)$ ,  $0 \leq s \leq 1$ .
- $A$  is invertible on  $L^2(\Gamma)$  (Verchota *J. Funct. Anal.* 1984)
- $D$  is compact (so  $A = I - D$  is coercive + compact) if  $\Omega$  is  $C^1$  (Fabes, Jodeit, Rivière *Acta. Math.* 1978)

**What is known about the double-layer potential operator  $D$  and  $A = I - D$  when  $\Omega$  is Lipschitz?** Remember the BIE in operator form is  $A\phi = -2g$ .

- $A$  is a bounded linear operator on  $L^2(\Gamma)$  if  $\Omega$  is a bounded Lipschitz domain
    - Calderón *Proc. Nat. Acad. Sci.* 1977, for  $\text{char}(\Omega)$  sufficiently small
    - Coifman, McIntosh, Meyer *Ann. Math.* 1982, for the general case
    - Verchota *J. Funct. Anal.* 1984, in fact  $A$  is bounded on  $H^s(\Gamma)$ ,  $0 \leq s \leq 1$ .
  - $A$  is invertible on  $L^2(\Gamma)$  (Verchota *J. Funct. Anal.* 1984)
  - $D$  is compact (so  $A = I - D$  is coercive + compact) if  $\Omega$  is  $C^1$  (Fabes, Jodeit, Rivière *Acta. Math.* 1978)
  - $D = D_0 + C$ , with  $\|D_0\| < 1$  and  $C$  compact, if  $\Omega$  is a (curvilinear) polygon (Shelepov *Soviet Math. Dokl.* 1969, Chandler *J. Austral. Math. Soc. Ser. B* 1984)
- so

$$A = I - D = \underbrace{I - D_0}_{\text{coercive}} + \underbrace{C}_{\text{compact}}$$

**What is known about the double-layer potential operator  $D$  and  $A = I - D$  when  $\Omega$  is Lipschitz?** Remember the BIE in operator form is  $A\phi = -2g$ .

- $A$  is a bounded linear operator on  $L^2(\Gamma)$  if  $\Omega$  is a bounded Lipschitz domain
    - Calderón *Proc. Nat. Acad. Sci.* 1977, for  $\text{char}(\Omega)$  sufficiently small
    - Coifman, McIntosh, Meyer *Ann. Math.* 1982, for the general case
    - Verchota *J. Funct. Anal.* 1984, in fact  $A$  is bounded on  $H^s(\Gamma)$ ,  $0 \leq s \leq 1$ .
  - $A$  is invertible on  $L^2(\Gamma)$  (Verchota *J. Funct. Anal.* 1984)
  - $D$  is compact (so  $A = I - D$  is coercive + compact) if  $\Omega$  is  $C^1$  (Fabes, Jodeit, Rivière *Acta. Math.* 1978)
  - $D = D_0 + C$ , with  $\|D_0\| < 1$  and  $C$  compact, if  $\Omega$  is a (curvilinear) polygon (Shelepov *Soviet Math. Dokl.* 1969, Chandler *J. Austral. Math. Soc. Ser. B* 1984)
- so

$$A = I - D = \underbrace{I - D_0}_{\text{coercive}} + \underbrace{C}_{\text{compact}}$$

- $A$  is **coercive** on  $H^{1/2}(\Gamma)$  (Steinbach, Wendland *J. Math. Anal. Appl.* 2001)
  - but this not so useful as the inner product in  $H^{1/2}(\Gamma)$  hard to compute

**What is known about the double-layer potential operator  $D$  and  $A = I - D$  when  $\Omega$  is Lipschitz?** Remember the BIE in operator form is  $A\phi = -2g$ .

- $A$  is a bounded linear operator on  $L^2(\Gamma)$  if  $\Omega$  is a bounded Lipschitz domain
    - Calderón *Proc. Nat. Acad. Sci.* 1977, for  $\text{char}(\Omega)$  sufficiently small
    - Coifman, McIntosh, Meyer *Ann. Math.* 1982, for the general case
    - Verchota *J. Funct. Anal.* 1984, in fact  $A$  is bounded on  $H^s(\Gamma)$ ,  $0 \leq s \leq 1$ .
  - $A$  is invertible on  $L^2(\Gamma)$  (Verchota *J. Funct. Anal.* 1984)
  - $D$  is compact (so  $A = I - D$  is coercive + compact) if  $\Omega$  is  $C^1$  (Fabes, Jodeit, Rivière *Acta. Math.* 1978)
  - $D = D_0 + C$ , with  $\|D_0\| < 1$  and  $C$  compact, if  $\Omega$  is a (curvilinear) polygon (Shelepov *Soviet Math. Dokl.* 1969, Chandler *J. Austral. Math. Soc. Ser. B* 1984)
- so

$$A = I - D = \underbrace{I - D_0}_{\text{coercive}} + \underbrace{C}_{\text{compact}}$$

- $A$  is **coercive** on  $H^{1/2}(\Gamma)$  (Steinbach, Wendland *J. Math. Anal. Appl.* 2001)
  - but this not so useful as the inner product in  $H^{1/2}(\Gamma)$  hard to compute

**Key open question:** is  $A = \text{coercive} + \text{compact}$  on  $L^2(\Gamma)$

- for every bounded Lipschitz domain  $\Omega$ ?
- for every bounded Lipschitz domain in 2D?
- for every Lipschitz polyhedron in 3D?

**What is known about the double-layer potential operator  $D$  and  $A = I - D$  when  $\Omega$  is Lipschitz?** Remember the BIE in operator form is  $A\phi = -2g$ .

- $A$  is a bounded linear operator on  $L^2(\Gamma)$  if  $\Omega$  is a bounded Lipschitz domain
    - Calderón *Proc. Nat. Acad. Sci.* 1977, for  $\text{char}(\Omega)$  sufficiently small
    - Coifman, McIntosh, Meyer *Ann. Math.* 1982, for the general case
    - Verchota *J. Funct. Anal.* 1984, in fact  $A$  is bounded on  $H^s(\Gamma)$ ,  $0 \leq s \leq 1$ .
  - $A$  is invertible on  $L^2(\Gamma)$  (Verchota *J. Funct. Anal.* 1984)
  - $D$  is compact (so  $A = I - D$  is coercive + compact) if  $\Omega$  is  $C^1$  (Fabes, Jodeit, Rivière *Acta. Math.* 1978)
  - $D = D_0 + C$ , with  $\|D_0\| < 1$  and  $C$  compact, if  $\Omega$  is a (curvilinear) polygon (Shelepov *Soviet Math. Dokl.* 1969, Chandler *J. Austral. Math. Soc. Ser. B* 1984)
- so

$$A = I - D = \underbrace{I - D_0}_{\text{coercive}} + \underbrace{C}_{\text{compact}}$$

- $A$  is **coercive** on  $H^{1/2}(\Gamma)$  (Steinbach, Wendland *J. Math. Anal. Appl.* 2001)
  - but this not so useful as the inner product in  $H^{1/2}(\Gamma)$  hard to compute

**Key open question:** is  $A = \text{coercive} + \text{compact}$  on  $L^2(\Gamma)$

- for every bounded Lipschitz domain  $\Omega$ ?
- for every bounded Lipschitz domain in 2D?
- for every Lipschitz polyhedron in 3D?

The answer is **NO** in each case (C-W & Euan 2018), so no guarantee of convergence of Galerkin methods.

# Where are we in this talk?

- 1 **Lipschitz domains** - the setting for modern PDE theory
  - What are Lipschitz domains?
  - What is the Lipschitz character of a Lipschitz domain?
- 2 **Potential theory and 2nd kind boundary integral equations (BIEs)**
  - A Dirichlet problem and 2nd kind BIE formulation
  - The Galerkin approximation to the BIE
  - **A long-standing open problem: do all “sensible” Galerkin methods converge?**
- 3 The **Hilbert space** theory of **Galerkin methods**
  - Definitions of bounded, compact, coercive
  - Galerkin methods and their convergence
- 4 **Do all sensible Galerkin methods converge for the standard 2nd kind BIEs?**
  - Previous results
  - **Solving the open problem:** Constructing  $\Omega$  for which  $A = I - D$  is not coercive + compact so not all sensible Galerkin methods converge

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

**The Main Abstract Theorem on the Galerkin Method.**

**Part c) extended.** If  $A$  is invertible then the following statements are equivalent:

- The Galerkin method converges for every  $V$  that converges to  $H$ .
- $A = A_0 + K$  where  $A_0$  is **coercive** and  $K$  is **compact**.
- $0 \neq W_{\text{ess}}(A)$



**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

**The Main Abstract Theorem on the Galerkin Method.**

**Part c) extended.** If  $A$  is invertible then the following statements are equivalent:

- The Galerkin method converges for every  $V$  that converges to  $H$ .
- $A = A_0 + K$  where  $A_0$  is **coercive** and  $K$  is **compact**.
- $0 \neq W_{\text{ess}}(A)$

Here  $W_{\text{ess}}(A)$  denotes the **essential numerical range** of  $A$ , defined by

$$W_{\text{ess}}(A) := \bigcap_{K \text{ compact}} \overline{W(A + K)},$$

where, for a bounded linear operator  $B$ ,  $W(B)$  denotes the **numerical range** or **field of values** of  $B$ , given by

$$W(B) := \{(Bu, u) : \|u\| = 1\} = \left\{ \frac{(Bu, u)}{\|u\|^2} : u \in H \setminus \{0\} \right\}.$$

**The Galerkin method.** Pick a sequence  $V = (V_1, V_2, \dots)$  of finite-dimensional subspaces of  $H$  with  $\dim(V_N) = N$ , and seek  $u_N \in V_N$  such that

$$(Au_N, v) = (g, v), \quad \forall v \in V_N \quad (G).$$

**The Main Abstract Theorem on the Galerkin Method.**

**Part c) extended.** If  $A$  is invertible then the following statements are equivalent:

- The Galerkin method converges for every  $V$  that converges to  $H$ .
- $A = A_0 + K$  where  $A_0$  is **coercive** and  $K$  is **compact**.
- $0 \notin W_{\text{ess}}(A)$

Here  $W_{\text{ess}}(A)$  denotes the **essential numerical range** of  $A$ , defined by

$$W_{\text{ess}}(A) := \bigcap_{K \text{ compact}} \overline{W(A + K)},$$

where, for a bounded linear operator  $B$ ,  $W(B)$  denotes the **numerical range** or **field of values** of  $B$ , given by

$$W(B) := \{(Bu, u) : \|u\| = 1\} = \left\{ \frac{(Bu, u)}{\|u\|^2} : u \in H \setminus \{0\} \right\}.$$

If  $A = I - D$  and  $D$  is the double-layer potential operator, is  $0 \in W_{\text{ess}}(A)$ ?  
Equivalently, is  $1 \in W_{\text{ess}}(D)$ ?

# Numerical range

For a bounded linear operator  $B$  on  $H$

$$W(B) = \{(Bu, u) : \|u\| = 1\} = \left\{ \frac{(Bu, u)}{\|u\|^2} : u \in H \setminus \{0\} \right\}.$$

# Numerical range

For a bounded linear operator  $B$  on  $H$

$$W(B) = \{(Bu, u) : \|u\| = 1\} = \left\{ \frac{(Bu, u)}{\|u\|^2} : u \in H \setminus \{0\} \right\}.$$

**Theorem.**  $W(B)$  is **convex** and  $\text{spec}(B) \subset \overline{W(B)}$ , so the **convex hull**

$$\text{conv}(\text{spec}(B)) \subset \overline{W(B)},$$

with equality if  $B$  is **normal**, i.e. if  $BB^* = B^*B$ .

# Numerical range

For a bounded linear operator  $B$  on  $H$

$$W(B) = \{(Bu, u) : \|u\| = 1\} = \left\{ \frac{(Bu, u)}{\|u\|^2} : u \in H \setminus \{0\} \right\}.$$

**Theorem.**  $W(B)$  is **convex** and  $\text{spec}(B) \subset \overline{W(B)}$ , so the **convex hull**

$$\text{conv}(\text{spec}(B)) \subset \overline{W(B)},$$

with equality if  $B$  is **normal**, i.e. if  $BB^* = B^*B$ .

**Special case.** If  $H = \mathbb{C}^N$  with norm  $\|u\| = \sqrt{\sum_{m=1}^N |u_m|^2}$  and  $B$  is an  $N \times N$  matrix, then  $W(B) = \overline{W(B)}$  and  $\text{spec}(B) = \{\text{eigenvalues of } B\} \subset W(B)$ .

# Numerical range

For a bounded linear operator  $B$  on  $H$

$$W(B) = \{(Bu, u) : \|u\| = 1\} = \left\{ \frac{(Bu, u)}{\|u\|^2} : u \in H \setminus \{0\} \right\}.$$

**Theorem.**  $W(B)$  is **convex** and  $\text{spec}(B) \subset \overline{W(B)}$ , so the **convex hull**

$$\text{conv}(\text{spec}(B)) \subset \overline{W(B)},$$

with equality if  $B$  is **normal**, i.e. if  $BB^* = B^*B$ .

**Special case.** If  $H = \mathbb{C}^N$  with norm  $\|u\| = \sqrt{\sum_{m=1}^N |u_m|^2}$  and  $B$  is an  $N \times N$

matrix, then  $W(B) = \overline{W(B)}$  and  $\text{spec}(B) = \{\text{eigenvalues of } B\} \subset W(B)$ .

E.g.

$$B = \begin{pmatrix} i & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \quad B^* = \begin{pmatrix} -i & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \quad \text{spec}(B) = \{i, 1, 2\}.$$

Clearly  $BB^* = B^*B$  so  $W(B) = \text{conv}(\{i, 1, 2\})$ .

**Theorem.**  $W(B)$  is **convex** and  $\text{spec}(B) \subset \overline{W(B)}$ , so the **convex hull**

$$\text{conv}(\text{spec}(B)) \subset \overline{W(B)},$$

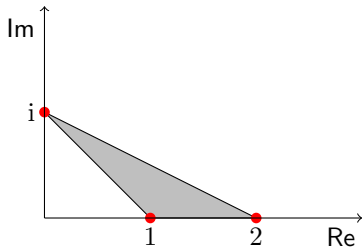
with equality if  $B$  is **normal**, i.e. if  $BB^* = B^*B$ .

**Special case.** If  $H = \mathbb{C}^N$  with norm  $\|u\| = \sqrt{\sum_{m=1}^N |u_m|^2}$  and  $B$  is an  $N \times N$  matrix, then  $W(B) = \overline{W(B)}$  and  $\text{spec}(B) = \{\text{eigenvalues of } B\} \subset W(B)$ .

E.g.

$$B = \begin{pmatrix} i & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \quad B^* = \begin{pmatrix} -i & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \quad \text{spec}(B) = \{i, 1, 2\}.$$

Clearly  $BB^* = B^*B$  so  $W(B) = \text{conv}(\{i, 1, 2\})$ .



**What is  $W_{\text{ess}}(D)$  for the double-layer potential operator?**

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\}, \quad W_{\text{ess}}(D) = \bigcap_{K \text{ compact}} \overline{W(D + K)}.$$



**What is  $W_{\text{ess}}(D)$  for the double-layer potential operator?**

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\}, \quad W_{\text{ess}}(D) = \bigcap_{K \text{ compact}} \overline{W(D + K)}.$$

A first new result for the case when the Lipschitz character  $\text{char}(\Omega)$  is small and  $\Gamma = \partial\Omega$ .

**What is  $W_{\text{ess}}(D)$  for the double-layer potential operator?**

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\}, \quad W_{\text{ess}}(D) = \bigcap_{K \text{ compact}} \overline{W(D + K)}.$$

A first new result for the case when the Lipschitz character  $\text{char}(\Omega)$  is small and  $\Gamma = \partial\Omega$ .

**Theorem.** For some constants  $C > 0$  and  $p > 0$  dependent only on  $d$  it holds for every bounded Lipschitz domain  $\Omega$  that

$$\sup_{z \in W_{\text{ess}}(D)} |z| \leq C \text{char}(\Omega) (1 + \text{char}(\Omega))^p.$$

## What is $W_{\text{ess}}(D)$ for the double-layer potential operator?

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\}, \quad W_{\text{ess}}(D) = \bigcap_{K \text{ compact}} \overline{W(D + K)}.$$

A first new result for the case when the Lipschitz character  $\text{char}(\Omega)$  is small and  $\Gamma = \partial\Omega$ .

**Theorem.** For some constants  $C > 0$  and  $p > 0$  dependent only on  $d$  it holds for every bounded Lipschitz domain  $\Omega$  that

$$\sup_{z \in W_{\text{ess}}(D)} |z| \leq C \text{char}(\Omega) (1 + \text{char}(\Omega))^p.$$

Thus  $1 \notin W_{\text{ess}}(D)$  and  $A = I - D = \text{coercive} + \text{compact}$  if  $\text{char}(\Omega)$  is small enough.

*Proof.* Uses localisation arguments plus standard bounds for the norm of  $D$  on Lipschitz graphs.

**What is  $W_{\text{ess}}(D)$  for the double-layer potential operator?**

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\}, \quad W_{\text{ess}}(D) = \bigcap_{K \text{ compact}} \overline{W(D + K)}.$$

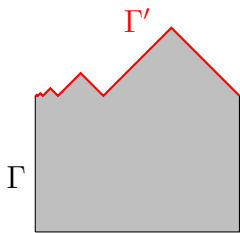
**What is  $W_{\text{ess}}(D)$  for the double-layer potential operator?**

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\}, \quad W_{\text{ess}}(D) = \bigcap_{K \text{ compact}} \overline{W(D + K)}.$$

A couple of simple lemmas.

**Lemma A.** If  $\Gamma' \subset \Gamma$  and  $D'$  is the DLP operator on  $\Gamma'$ , then, since  $L^2(\Gamma') \subset L^2(\Gamma)$ ,

$$W(D) \supset W(D').$$



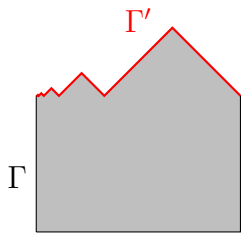
**What is  $W_{\text{ess}}(D)$  for the double-layer potential operator?**

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\}, \quad W_{\text{ess}}(D) = \bigcap_{K \text{ compact}} \overline{W(D + K)}.$$

A couple of simple lemmas.

**Lemma A.** If  $\Gamma' \subset \Gamma$  and  $D'$  is the DLP operator on  $\Gamma'$ , then, since  $L^2(\Gamma') \subset L^2(\Gamma)$ ,

$$W_{\text{ess}}(D) \supset W_{\text{ess}}(D').$$



**What is  $W_{\text{ess}}(D)$  for the double-layer potential operator?**

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\}, \quad W_{\text{ess}}(D) = \bigcap_{K \text{ compact}} \overline{W(D + K)}.$$

**What is  $W_{\text{ess}}(D)$  for the double-layer potential operator?**

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\}, \quad W_{\text{ess}}(D) = \bigcap_{K \text{ compact}} \overline{W(D + K)}.$$

**Lemma B.** If  $f$  is Lipschitz continuous and  $\Gamma = \{(s, f(s)) : 0 \leq s \leq 1\}$  and, for some  $0 < \alpha < 1$ ,

$$\alpha\Gamma := \{\alpha y : y \in \Gamma\} = \{(s, f(s)) : 0 \leq s \leq \alpha\},$$

then  $W_{\text{ess}}(D) = \overline{W(D)}$ .



## What is $W_{\text{ess}}(D)$ for the double-layer potential operator?

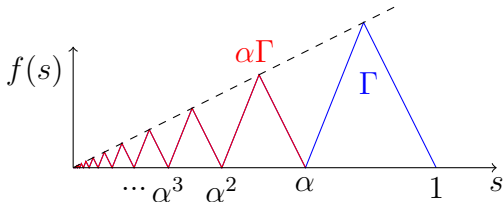
$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\}, \quad W_{\text{ess}}(D) = \bigcap_{K \text{ compact}} \overline{W(D + K)}.$$

**Lemma B.** If  $f$  is Lipschitz continuous and  $\Gamma = \{(s, f(s)) : 0 \leq s \leq 1\}$  and, for some  $0 < \alpha < 1$ ,

$$\alpha\Gamma := \{\alpha y : y \in \Gamma\} = \{(s, f(s)) : 0 \leq s \leq \alpha\},$$

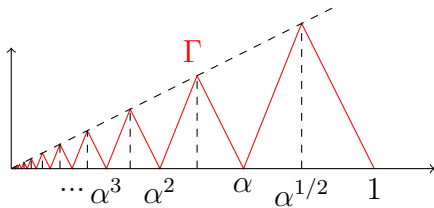
then  $W_{\text{ess}}(D) = \overline{W(D)}$ .

E.g.



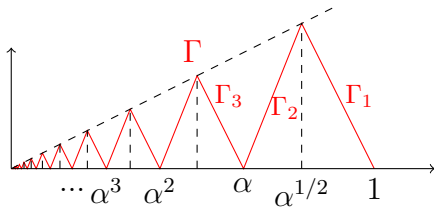
What is  $W_{\text{ess}}(D) = W(D)$  for the double-layer potential operator on this particular  $\Gamma$ ?

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\} = \left\{ \frac{(D\phi, \phi)}{\|\phi\|^2} : \phi \in L^2(\Gamma) \setminus \{0\} \right\}$$



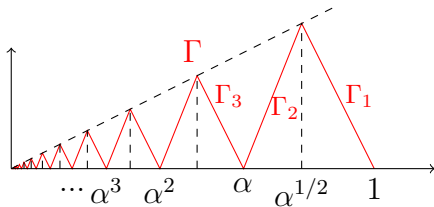
What is  $W_{\text{ess}}(D) = W(D)$  for the double-layer potential operator on this particular  $\Gamma$ ?

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\} = \left\{ \frac{(D\phi, \phi)}{\|\phi\|^2} : \phi \in L^2(\Gamma) \setminus \{0\} \right\}$$



What is  $W_{\text{ess}}(D) = W(D)$  for the double-layer potential operator on this particular  $\Gamma$ ?

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\} = \left\{ \frac{(D\phi, \phi)}{\|\phi\|^2} : \phi \in L^2(\Gamma) \setminus \{0\} \right\}$$



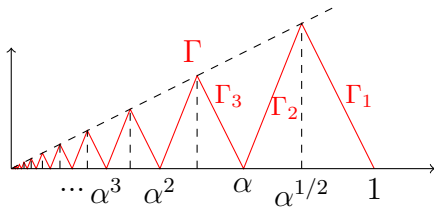
Choose  $N \in \mathbb{N}$  and define  $\phi \in L^2(\Gamma)$  by

$$\phi(x) := \phi_m \quad \text{on} \quad \Gamma_m, \quad \text{for } m = 1, \dots, N,$$

$\phi(x) := 0$ , otherwise.

What is  $W_{\text{ess}}(D) = W(D)$  for the double-layer potential operator on this particular  $\Gamma$ ?

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\} = \left\{ \frac{(D\phi, \phi)}{\|\phi\|^2} : \phi \in L^2(\Gamma) \setminus \{0\} \right\}$$



Choose  $N \in \mathbb{N}$  and define  $\phi \in L^2(\Gamma)$  by

$$\phi(x) := \phi_m \quad \text{on} \quad \Gamma_m, \quad \text{for } m = 1, \dots, N,$$

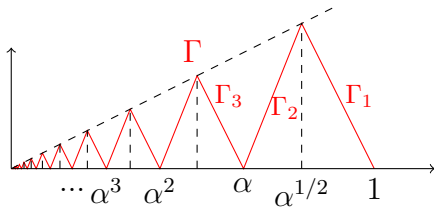
$\phi(x) := 0$ , otherwise. Then, where  $\underline{\phi} = (\phi_1, \dots, \phi_N)^T$ , and

$$A_N := [\text{sign}(n - m)(-1)^{n+1}]_{m,n=1}^N, \quad \text{it holds that} \quad \frac{(D\phi, \phi)}{\|\phi\|^2} \rightarrow \frac{(A_N \underline{\phi}, \underline{\phi})}{\|\underline{\phi}\|^2}$$

as  $\alpha \rightarrow 1^-$ .

What is  $W_{\text{ess}}(D) = W(D)$  for the double-layer potential operator on this particular  $\Gamma$ ?

$$W(D) = \{(D\phi, \phi) : \phi \in L^2(\Gamma), \|\phi\| = 1\} = \left\{ \frac{(D\phi, \phi)}{\|\phi\|^2} : \phi \in L^2(\Gamma) \setminus \{0\} \right\}$$



Choose  $N \in \mathbb{N}$  and define  $\phi \in L^2(\Gamma)$  by

$$\phi(x) := \phi_m \quad \text{on} \quad \Gamma_m, \quad \text{for } m = 1, \dots, N,$$

$\phi(x) := 0$ , otherwise. Then, where  $\underline{\phi} = (\phi_1, \dots, \phi_N)^T$ , and

$$A_N := [\text{sign}(n-m)(-1)^{n+1}]_{m,n=1}^N, \quad \text{it holds that} \quad \frac{(D\phi, \phi)}{\|\phi\|^2} \rightarrow \frac{(A_N \underline{\phi}, \underline{\phi})}{\|\underline{\phi}\|^2}$$

as  $\alpha \rightarrow 1^-$ . **So every neighbourhood of  $W(D)$  contains  $W(A_N)$  if  $\alpha$  is close enough to 1.**

$$A_N := [\text{sign}(n - m)(-1)^{n+1}]_{m,n=1}^N, \quad \text{e.g.} \quad A_4 = \begin{pmatrix} 0 & -1 & 1 & -1 \\ -1 & 0 & 1 & -1 \\ -1 & 1 & 0 & -1 \\ -1 & 1 & -1 & 0 \end{pmatrix}.$$

$$A_N := [\text{sign}(n - m)(-1)^{n+1}]_{m,n=1}^N, \quad \text{e.g.} \quad A_4 = \begin{pmatrix} 0 & -1 & 1 & -1 \\ -1 & 0 & 1 & -1 \\ -1 & 1 & 0 & -1 \\ -1 & 1 & -1 & 0 \end{pmatrix}.$$

**Lemma.** For every  $R > 0$ , if  $N$  is large enough,

$$\{z \in \mathbb{C} : |z| < R\} \subset W(A_N).$$



$$A_N := [\text{sign}(n - m)(-1)^{n+1}]_{m,n=1}^N, \quad \text{e.g. } A_4 = \begin{pmatrix} 0 & -1 & 1 & -1 \\ -1 & 0 & 1 & -1 \\ -1 & 1 & 0 & -1 \\ -1 & 1 & -1 & 0 \end{pmatrix}.$$

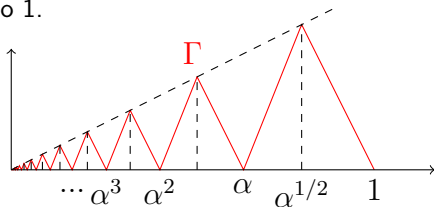
**Lemma.** For every  $R > 0$ , if  $N$  is large enough,

$$\{z \in \mathbb{C} : |z| < R\} \subset W(A_N).$$

**Corollary.** For this particular  $\Gamma$  and for every  $R > 0$ ,

$$W_{\text{ess}}(D) = \overline{W(D)} \supset \{z \in \mathbb{C} : |z| < R\}$$

if  $\alpha$  is close enough to 1.



$$A_N := [\text{sign}(n - m)(-1)^{n+1}]_{m,n=1}^N, \quad \text{e.g. } A_4 = \begin{pmatrix} 0 & -1 & 1 & -1 \\ -1 & 0 & 1 & -1 \\ -1 & 1 & 0 & -1 \\ -1 & 1 & -1 & 0 \end{pmatrix}.$$

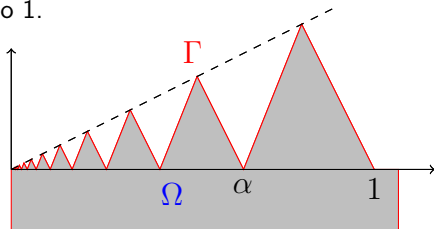
**Lemma.** For every  $R > 0$ , if  $N$  is large enough,

$$\{z \in \mathbb{C} : |z| < R\} \subset W(A_N).$$

**Corollary.** For this particular  $\Gamma$  and for every  $R > 0$ ,

$$W_{\text{ess}}(D) \supset \{z \in \mathbb{C} : |z| < R\}$$

if  $\alpha$  is close enough to 1.



$$A_N := [\text{sign}(n - m)(-1)^{n+1}]_{m,n=1}^N, \quad \text{e.g. } A_4 = \begin{pmatrix} 0 & -1 & 1 & -1 \\ -1 & 0 & 1 & -1 \\ -1 & 1 & 0 & -1 \\ -1 & 1 & -1 & 0 \end{pmatrix}.$$

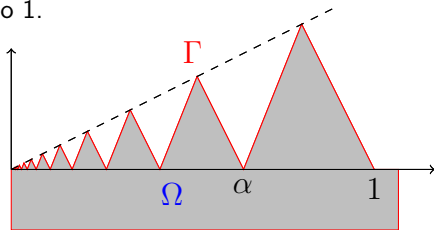
**Lemma.** For every  $R > 0$ , if  $N$  is large enough,

$$\{z \in \mathbb{C} : |z| < R\} \subset W(A_N).$$

**Corollary.** For this particular  $\Gamma$  and for every  $R > 0$ ,

$$W_{\text{ess}}(D) \supset \{z \in \mathbb{C} : |z| < R\}$$

if  $\alpha$  is close enough to 1.



**Corollary.** For this domain  $\Omega$ ,  $A = I - D$  is not coercive + compact if  $\alpha$  is close enough to 1.

$$A_N := [\text{sign}(n - m)(-1)^{n+1}]_{m,n=1}^N, \quad \text{e.g.} \quad A_4 = \begin{pmatrix} 0 & -1 & 1 & -1 \\ -1 & 0 & 1 & -1 \\ -1 & 1 & 0 & -1 \\ -1 & 1 & -1 & 0 \end{pmatrix}.$$

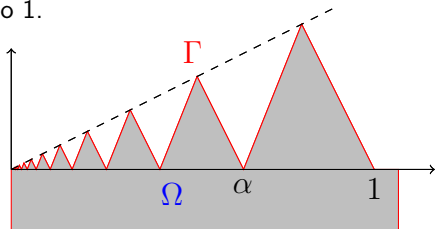
**Lemma.** For every  $R > 0$ , if  $N$  is large enough,

$$\{z \in \mathbb{C} : |z| < R\} \subset W(A_N).$$

**Corollary.** For this particular  $\Gamma$  and for every  $R > 0$ ,

$$W_{\text{ess}}(D) \supset \{z \in \mathbb{C} : |z| < R\}$$

if  $\alpha$  is close enough to 1.



**Corollary.** For this domain  $\Omega$ ,  $A = I - D$  is not coercive + compact if  $\alpha$  is close enough to 1. **This counter-example solves the long-standing open problem!**

# Summary of the talk

- 1 **Lipschitz domains** - the setting for modern PDE theory
  - What are Lipschitz domains?
  - What is the Lipschitz character of a Lipschitz domain?
- 2 **Potential theory and 2nd kind boundary integral equations (BIEs)**
  - A Dirichlet problem and 2nd kind BIE formulation
  - The Galerkin approximation to the BIE
  - **A long-standing open problem: do all “sensible” Galerkin methods converge?**
- 3 The **Hilbert space** theory of **Galerkin methods**
  - Definitions of bounded, compact, coercive
  - Galerkin methods and their convergence
- 4 **Do all sensible Galerkin methods converge for the standard 2nd kind BIEs?**
  - Previous results
  - **Solving the open problem:** Constructing  $\Omega$  for which  $A = I - D$  is not coercive + compact so not all sensible Galerkin methods converge