

Unit Code MA30087/MA50087	Unit Title OPTIMIZATION METHODS OF OPR. RESEARCH		
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Part		Mark
(a)	Suppose $y \in F(C)$ then $A'y = \underline{b}$ hence $(A : I_m) \begin{pmatrix} y^0 \\ y_B \end{pmatrix} = \underline{b}$ or $Ay^0 + y_B = \underline{b}$ (*) Since $y \in F(C)$ it also follows that $y^0 \geq \underline{0}_n$ (**) and $y_B \geq \underline{0}_m$. Hence from (*) $Ay^0 \leq \underline{b}$ (***) (**) and (***) $\Rightarrow y^0 \in F(S)$ We now have that $\left\{ y^0 : \begin{pmatrix} y^0 \\ y_B \end{pmatrix} \in F(C) \right\} \subseteq F(S)$ Thus $\sup_{y \in F(C)} y \cdot \underline{c}' = \sup_{y^0 \in F(C)} y^0 \cdot \underline{c}$ $\leq \sup_{x \in F(S)} x \cdot \underline{c}$	6
Total		

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(b)	Now suppose $x \in F(S)$ and note that $\underline{u} = \underline{b} - (A\underline{x}) \geq \underline{0}_m \quad \text{as } \underline{x} \in F(S) \quad (*)$ Let $\underline{y}^* = \begin{pmatrix} \underline{x} \\ \underline{u} \end{pmatrix}$ and note that $\begin{aligned} A' \underline{y}^* &= (A : I_m) \begin{pmatrix} \underline{x} \\ \underline{u} \end{pmatrix} = A\underline{x} + \underline{u} \\ &= A\underline{x} + (\underline{b} - A\underline{x}) = \underline{b}. \end{aligned}$ Moreover $\underline{y}^* \geq \underline{0}_{n+m}$ since $\underline{x} \geq \underline{0}_n$ (as $\underline{x} \in F(S)$) and $\underline{u} \geq \underline{0}_m$ (see (*) above). Hence $\underline{y}^* \in F(C)$. Now note that $\left\{ \begin{pmatrix} \underline{x} \\ \underline{u} \end{pmatrix} : \underline{x} \in F(S), \underline{u} = \underline{b} - A\underline{x} \right\} \subseteq F(C). \quad (†)$ Hence $\sup_{\underline{x} \in F(S)} \underline{c} \cdot \underline{x} = \sup_{\underline{x} \in F(S)} \begin{pmatrix} \underline{x} \\ \underline{u} \end{pmatrix} \cdot \underline{c}'$ (†) $\leq \sup_{\underline{y} \in F(C)} \underline{y} \cdot \underline{c}'$		
			6
			Total

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(c)	Now suppose (S) has an optimal solⁿ, say $\underline{x}^* \in F(S)$. Then by (b) $\begin{pmatrix} \underline{x}^* \\ \underline{u}^* \end{pmatrix} \in F(c)$ and hence $F(c) \neq \emptyset$. with $\underline{u}^* \in \underline{b} - A\underline{x}^*$ Moreover $\sup_{\underline{x} \in F(S)} \underline{c} \cdot \underline{x} \leq \sup_{\underline{y} \in F(c)} \underline{y} \cdot \underline{c}'$ But then, since $F(c) \neq \emptyset$ we have by (a). $\sup_{\underline{x} \in F(S)} \underline{c} \cdot \underline{x} \geq \sup_{\underline{y} \in F(c)} \underline{y} \cdot \underline{c}'$ Thus $\sup_{F(S)} \underline{c} \cdot \underline{x} = \sup_{F(c)} \underline{y} \cdot \underline{c}'$ Note that also that since $\underline{x}^* \cdot \underline{c} = \sup_{F(S)} \underline{c} \cdot \underline{x}$ then and $\underline{x}^* \cdot \underline{c} = \begin{pmatrix} \underline{x}^* \\ \underline{u}^* \end{pmatrix} \cdot \underline{c}'$ it follows that $\begin{pmatrix} \underline{x}^* \\ \underline{u}^* \end{pmatrix}$ is an optimal solⁿ for (c).		
Total			8

Similar argument for converse

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(a)	(i) Dual: Minimize $z' = \underline{b} \cdot \underline{y}$ Subject to: $A^T \underline{y} \geq \underline{c}$ $\underline{y} \in \mathbb{R}^M$ $\underline{y} \geq \underline{0}_M$		(2)
	(ii) <u>Duality Theorem</u>: The primal problem (P) has a finite optimal solution if and only if the dual (D) does too in which case the objectives values are optimally equal.		(2)
	(iii) say $\underline{x}_0$ is optimal for (P) and $\underline{y}_0$ is optimal for (D). Since $A\underline{x}_0 \leq \underline{b}$ and $\underline{y}_0 \geq \underline{0}_M$ we have $\underline{y}_0^T A \underline{x}_0 \leq \underline{y}_0^T \underline{b} = \underline{y}_0^T \underline{b}$.		
	Similarly, since $\underline{y}_0^T A \geq \underline{c}^T$ and $\underline{x}_0 \geq \underline{0}_N$, it follows that $\underline{y}_0^T A \underline{x}_0 \geq \underline{c}^T \underline{x}_0 = \underline{c} \cdot \underline{x}_0$.		
	But since $\underline{x}_0, \underline{y}_0$ are optimal, it follows that		
			Total

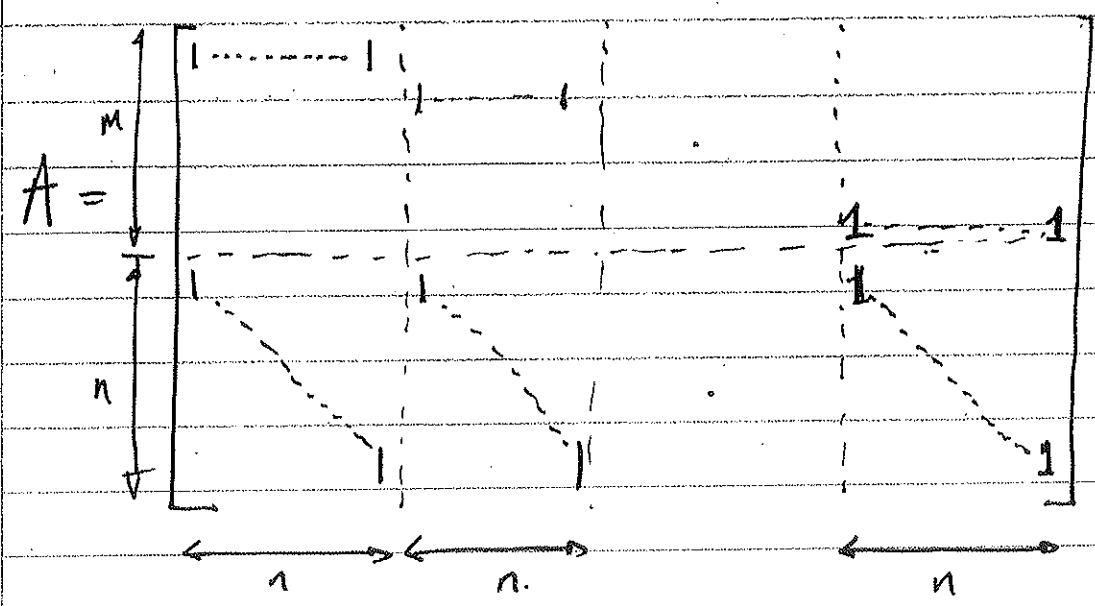
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	$c \cdot x_0 = b \cdot y_0$ from the Weak Duality Theorem. Here $b \cdot y_0 \geq y_0^T A x_0 \geq c \cdot x_0 = b \cdot y_0.$ So all inequalities are equalities and in particular $y_0^T A x_0 = y_0^T b.$ or $y_0^T (A x_0 - b) = 0.$ $\text{or } \sum_{i=1}^m (y_0)_i [(A x_0)_i - b_i] = 0.$ since $(A x_0)_i - b_i \leq 0$ and $(y_0)_i > 0 \forall i$ it follows that all summands are non-positive and hence, since sum = 0 $\Rightarrow$ all terms are zero $\Rightarrow (y_0)_i [(A x_0)_i - b_i] = 0 \forall i$ $\Rightarrow (A x_0)_i - b_i = 0 \forall i \text{ as } (y_0)_i > 0 \forall i$ i.e. $A x_0 = b.$		
			6
Total			

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(b)	Suppose $x = (1, 4, 0, 0, 0)$ is optimal. The dual problem is: minimize $z' = y_1 + 4y_2$ subject to $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 1 & 0 \\ 3 & 4 & -1 \\ -1 & 2 & 3 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} \geq \begin{pmatrix} -1 \\ 0 \\ 1 \\ -5 \\ 1 \end{pmatrix} \quad y_i \in \mathbb{R} \quad i=1,2,3$ (Note we have converted primal problem to a maximisation problem before writing down the dual) $x_1 > 0 \Rightarrow y_1 = -1$ $x_2 > 0 \Rightarrow y_2 = 0$ also remaining constraints require $-3y_3 - 3y_2 \geq -5$ $1 + 3y_3 \geq 1 \Rightarrow y_3 \in [0, 2]$ now note that $y \cdot b = -1 = c \cdot x$ Hence by weak duality theorem, since $(-1, 0, y_3)$ is feasible (for any $y_3 \in [0, 2]$) and the objective agrees with the objective of the primal for given x then x is optimal. (5)	
Total		

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(C)	$x = (1, 1, 0)$. Assume x is optimal. Dual problem minimise $2y_1 + y_2$. $\begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \geq \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \text{s.t. } y_1, y_2 \geq 0.$ $\left. \begin{array}{l} x_1 > 0 \Rightarrow y_1 + y_2 = 0. \\ x_2 > 0 \Rightarrow y_1 = 1. \end{array} \right\} \Rightarrow y_2 = -1$ Which is a contradiction as need positivity for a feasible sol ⁿ to dual. Here x is not optimal.		
Total			5

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(a)	
 $\underline{b}^T = (s_1, \dots, s_m, d_1, \dots, d_n).$	
(b)	
Dual: Maximize $z' = \sum_{i=1}^m s_i u_i + \sum_{j=1}^n d_j v_j$ subject to $u_i + v_j \leq c_{ij} \quad \forall i, j$ $u_i, v_j \in \mathbb{R} \quad \forall i, j.$	
(c)	
(i) (x_{ij}) is not optimal because if it were then the system (u_i, v_j) would constitute a solution to the dual. However (u_i, v_j) cannot be feasible for the dual since	
Total	

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(a)	Transportation problem data: <table style="margin: 10px auto; border-collapse: collapse;"> <tr> <td></td> <td style="border-right: 1px solid black; padding: 5px;">4</td> <td style="padding: 5px;">9</td> <td style="padding: 5px;">9</td> <td style="padding: 5px;">13</td> </tr> <tr> <td style="padding: 5px;">8</td> <td style="border-right: 1px solid black; padding: 5px;">4</td> <td style="padding: 5px;">3</td> <td style="padding: 5px;">3</td> <td style="padding: 5px;">1</td> </tr> <tr> <td style="padding: 5px;">11</td> <td style="border-right: 1px solid black; padding: 5px;">3</td> <td style="padding: 5px;">2</td> <td style="padding: 5px;">4</td> <td style="padding: 5px;">8</td> </tr> <tr> <td style="padding: 5px;">16</td> <td style="border-right: 1px solid black; padding: 5px;">5</td> <td style="padding: 5px;">4</td> <td style="padding: 5px;">6</td> <td style="padding: 5px;">3</td> </tr> </table> Matrix method now gives not BFS. <table style="margin: 10px auto; border-collapse: collapse;"> <tr> <td></td> <td style="border-right: 1px solid black; padding: 5px;">4</td> <td style="padding: 5px;">9</td> <td style="padding: 5px;">9</td> <td style="padding: 5px;">13</td> <td style="border-right: 1px solid black;"></td> </tr> <tr> <td style="padding: 5px;">8</td> <td style="border-right: 1px solid black; padding: 5px;">0₄</td> <td style="padding: 5px;">0₃</td> <td style="padding: 5px;">0₃⁽¹⁾</td> <td style="padding: 5px;">8₁</td> <td style="border-right: 1px solid black; padding: 5px;">0 ← choose $u_1 = 0$.</td> </tr> <tr> <td style="padding: 5px;">11</td> <td style="border-right: 1px solid black; padding: 5px;">2₃</td> <td style="padding: 5px;">9₂</td> <td style="padding: 5px;">0₄</td> <td style="padding: 5px;">0₈</td> <td style="border-right: 1px solid black; padding: 5px;">0</td> </tr> <tr> <td style="padding: 5px;">16</td> <td style="border-right: 1px solid black; padding: 5px;">2₅</td> <td style="padding: 5px;">0₄</td> <td style="padding: 5px;">9₆⁽¹⁾</td> <td style="padding: 5px;">5₃⁽¹⁾</td> <td style="border-right: 1px solid black; padding: 5px;">2</td> </tr> <tr> <td></td> <td style="border-right: 1px solid black; padding: 5px;">3</td> <td style="padding: 5px;">2</td> <td style="padding: 5px;">4</td> <td style="padding: 5px;">1</td> <td style="border-right: 1px solid black;"></td> </tr> </table> Note $x_{13} = 0$ but $u_1 + v_3 = 0 + 4 > 3$. hence above not optimal. $\rightarrow$ the only such (i,j) Introduce x_{13} and remove x_{14} via the loop shown.		4	9	9	13	8	4	3	3	1	11	3	2	4	8	16	5	4	6	3		4	9	9	13		8	0 ₄	0 ₃	0 ₃ ⁽¹⁾	8 ₁	0 ← choose $u_1 = 0$.	11	2 ₃	9 ₂	0 ₄	0 ₈	0	16	2 ₅	0 ₄	9 ₆ ⁽¹⁾	5 ₃ ⁽¹⁾	2		3	2	4	1	
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		4	9	9	13	
	8	0 ₄	0 ₃	8 ₃	0 ₁	0 ← choose $u_1 = 0$.
	11	2 ₃	9 ₂	0 ₄	0 ₈	1
	16	2 ₅	0 ₄	1 ₆	13 ₃	3
		2	1	3	0	
note for all (i,j) such that $x_{ij} = 0$ we have $u_i + v_j \leq c_{ij}$ specifically: $0 + 2 \leq 4$ (1,1) $0 + \cancel{1} \leq 3$ (1,2). $0 + 0 \leq 1$ (1,4). $\cancel{1} + 3 \leq 4$ (2,3) $1 + 0 \leq 8$ (2,4). $3 + 1 \leq 4$ (3,2). Hence opt optimal $Z = \underbrace{24}_{30} + \underbrace{6 + 18}_{28} + \underbrace{10 + 6}_{19} + \cancel{139} = \cancel{103}.$						
					103	Total

(9)

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(a)	Maximise $z = 2x_1 - 3x_2 + x_3$ subject to: $3x_1 + 6x_2 + x_3 \leq 6$ $4x_1 + 2x_2 + x_3 \leq 4$ $x_1 - x_2 + x_3 \leq 3$ $x_1, x_2, x_3 \geq 0$ Introduce slack variables $x_4, \dots, x_6$ $\theta = b_i/a_{ij}$ <table style="margin: 10px auto; border-collapse: collapse;"> <tr> <th></th> <th>x_1</th> <th>x_2</th> <th>x_3</th> <th>x_4</th> <th>x_5</th> <th>x_6</th> <th></th> </tr> <tr> <td style="border-right: 1px solid black; padding: 5px;">x_4</td> <td style="padding: 5px;">$\theta=2$ 3</td> <td style="padding: 5px;">6</td> <td style="padding: 5px;">1^6</td> <td style="padding: 5px;">1</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">6</td> </tr> <tr> <td style="border-right: 1px solid black; padding: 5px;">x_5</td> <td style="padding: 5px;">4^1 4</td> <td style="padding: 5px;">2</td> <td style="padding: 5px;">1^4</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">1</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">4</td> </tr> <tr> <td style="border-right: 1px solid black; padding: 5px;">x_6</td> <td style="padding: 5px;">1^3 1</td> <td style="padding: 5px;">-1</td> <td style="padding: 5px; border: 1px solid black;">1^3</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">1</td> <td style="padding: 5px;">3</td> </tr> <tr> <td style="border-right: 1px solid black; padding: 5px;"></td> <td style="padding: 5px;">-2</td> <td style="padding: 5px;">3</td> <td style="padding: 5px;">-1</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;"></td> </tr> </table> $\downarrow$ z increase by 2 $\downarrow$ z increase by 3. pivoting at circled entry: <table style="margin: 10px auto; border-collapse: collapse;"> <tr> <th></th> <th>x_1</th> <th>x_2</th> <th>x_3</th> <th>x_4</th> <th>x_5</th> <th>x_6</th> <th></th> </tr> <tr> <td style="border-right: 1px solid black; padding: 5px;">x_4</td> <td style="padding: 5px;">$2^{3/2}$ 7</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">1</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">-1</td> <td style="padding: 5px;">3</td> </tr> <tr> <td style="border-right: 1px solid black; padding: 5px;">x_5</td> <td style="padding: 5px;">$(3)^{1/3}$ 3</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">1</td> <td style="padding: 5px;">-1</td> <td style="padding: 5px;">1</td> </tr> <tr> <td style="border-right: 1px solid black; padding: 5px;">x_3</td> <td style="padding: 5px;">1^3 -1</td> <td style="padding: 5px;">1</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">1</td> <td style="padding: 5px;">3</td> </tr> <tr> <td style="border-right: 1px solid black; padding: 5px;"></td> <td style="padding: 5px;">-1</td> <td style="padding: 5px;">2</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">0</td> <td style="padding: 5px;">1</td> </tr> </table>		x_1	x_2	x_3	x_4	x_5	x_6		x_4	$\theta=2$ 3	6	1^6	1	0	0	6	x_5	4^1 4	2	1^4	0	1	0	4	x_6	1^3 1	-1	1^3	0	0	1	3		-2	3	-1	0	0	0			x_1	x_2	x_3	x_4	x_5	x_6		x_4	$2^{3/2}$ 7	0	1	0	-1	3	x_5	$(3)^{1/3}$ 3	0	0	1	-1	1	x_3	1^3 -1	1	0	0	1	3		-1	2	0	0	0	1	Total
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	<table style="margin-left: auto; margin-right: auto;"> <tr> <th></th> <th>x_1</th> <th>x_2</th> <th>x_3</th> <th>x_4</th> <th>x_5</th> <th>x_6</th> <th></th> </tr> <tr> <td>x_4</td> <td>0</td> <td>5</td> <td>0</td> <td>1</td> <td>$-\frac{2}{3}$</td> <td>$-\frac{1}{3}$</td> <td>$\frac{7}{3}$</td> </tr> <tr> <td>x_1</td> <td>1</td> <td>1</td> <td>0</td> <td>0</td> <td>$\frac{1}{3}$</td> <td>$-\frac{1}{3}$</td> <td>$\frac{1}{3}$</td> </tr> <tr> <td>x_3</td> <td>0</td> <td>-2</td> <td>1</td> <td>0</td> <td>$-\frac{1}{3}$</td> <td>$\frac{4}{3}$</td> <td>$\frac{8}{3}$</td> </tr> <tr> <td></td> <td>0</td> <td>3</td> <td>0</td> <td>0</td> <td>$\frac{1}{3}$</td> <td>$\frac{2}{3}$</td> <td>$\frac{10}{3}$</td> </tr> </table>		x_1	x_2	x_3	x_4	x_5	x_6		x_4	0	5	0	1	$-\frac{2}{3}$	$-\frac{1}{3}$	$\frac{7}{3}$	x_1	1	1	0	0	$\frac{1}{3}$	$-\frac{1}{3}$	$\frac{1}{3}$	x_3	0	-2	1	0	$-\frac{1}{3}$	$\frac{4}{3}$	$\frac{8}{3}$		0	3	0	0	$\frac{1}{3}$	$\frac{2}{3}$	$\frac{10}{3}$	
	x_1	x_2	x_3	x_4	x_5	x_6																																				
x_4	0	5	0	1	$-\frac{2}{3}$	$-\frac{1}{3}$	$\frac{7}{3}$																																			
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x_3	0	-2	1	0	$-\frac{1}{3}$	$\frac{4}{3}$	$\frac{8}{3}$																																			
	0	3	0	0	$\frac{1}{3}$	$\frac{2}{3}$	$\frac{10}{3}$																																			
	This is optimal as all coefficients in final row are positive.	8																																								
	<table style="margin-right: 20px;"> <tr><td>0</td><td>8</td><td>8</td><td>0</td><td>4</td><td>0</td></tr> <tr><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>0</td></tr> <tr><td>0</td><td>0</td><td>0</td><td>7</td><td>0</td><td>3</td></tr> <tr><td>0</td><td>1</td><td>3</td><td>0</td><td>0</td><td>3+k</td></tr> <tr><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>4</td></tr> <tr><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td></tr> </table> can be represented as	0	8	8	0	4	0	0	0	0	1	0	0	0	0	0	7	0	3	0	1	3	0	0	3+k	0	0	0	0	0	4	0	0	0	0	0	0	1				
0	8	8	0	4	0																																					
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Part	Mark
(c) Suppose $k=0$. Then introduce the following flows	
$1 \rightarrow 2 \rightarrow 4 \rightarrow 6$: flow 1 $1 \rightarrow 5 \rightarrow 6$: flow 4 $1 \rightarrow 3 \rightarrow 4 \rightarrow 6$: flow 2 $1 \rightarrow 3 \rightarrow 6$: flow 3	
residual capacities:	
Now labelling:	
	Total

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	Sink is not labelled hence saturation.		
	$\text{max flow} = 1 + 4 + 2 + 3 = 10.$		(6)
(d)	Max-flow min-cut Theorem states that if f is a maximum flow, then there exists a cut (A, B) such that $\text{flow of } f = \text{capacity across}(A, B).$ and the capacity of the cut (A, B) is minimal across all cuts.		
	Cuts : $\{1\} \{2, \dots, 6\}$ capacity = $8 + 4 + 8 = 20$. $\{1, 2\} \{3, \dots, 6\}$ $\rightarrow$ = $8 + 4 + 1 = 13$ $\{1, 2, 3\} \{4, 5, 6\}$ $\rightarrow$ = $1 + 7 + 4 + 3 = 15$ $* \{1, 2, 3, 4\} \{5, 6\}$ $\rightarrow$ = $3 + 3 + 4 = 10$ $\{1, \dots, 5\} \{6\}$ $\rightarrow$ = $3 + 3 + 4 = 10$		
	minimal cut not unique — one of last two cuts.		
	* Note in proof of Max-flow-min cut theorem, the existence of a min-cut is shown by looking at the labelled and non-labelled nodes as providing the cut.		(2)
	Total		

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(e)	If K is increased from zero then from $(*)$ we can increase the flow by K along $1 \rightarrow 3 \rightarrow 4 \rightarrow 6$ for $K \in (0, 3]$. for $K > 3$, can increase the flow along $1 \rightarrow 3 \rightarrow 4 \rightarrow 6$ by 3.. Maximal flow is thus $10 + (K \wedge 3)$.		(3)
			Total