

## Previously in MA30087/50087:

- balanced transportation problem

$$\begin{array}{ll}\text{minimise} & z = \sum_{i=1}^m \sum_{j=1}^n c_{ij} x_{ij} \\ \text{subject to} & \sum_{j=1}^n x_{ij} = s_i \quad i = 1, \dots, m \\ & \sum_{i=1}^m x_{ij} = d_j \quad j = 1, \dots, n \\ & x_{ij} \geq 0 \quad i = 1, \dots, m, j = 1, \dots, n\end{array}$$

- dual of the balanced transportation problem

$$\begin{array}{ll}\text{maximise} & z' = \sum_{i=1}^m u_i s_i + \sum_{j=1}^n v_j d_j \\ \text{subject to} & u_i + v_j \leq c_{ij} \quad i = 1, \dots, m, j = 1, \dots, n\end{array}$$

- transportation algorithm utilises asymmetric complementary slackness

$$x_{ij}[u_i + v_j - c_{ij}] = 0 \quad \forall i = 1, \dots, m, j = 1, \dots, n$$

## Today in MA30087/50087:

- find an initial BFS to balanced transportation problem
  - typically use north-west corner method or the matrix method
- solve complementary slackness to find possible dual solution

$$x_{ij} > 0 \Rightarrow u_i + v_j = c_{ij}$$

- if dual solution feasible, we have optimal solution
- if dual solution not feasible, move to another BFS
- example of the transportation algorithm
- perturbation loop for moving to another BFS