Previously in MA30087/50087:

• aymmetric complementary slackness theorem

maximise
$$z = \mathbf{c}^T \mathbf{x}$$

 (P) subject to $\mathbf{A}\mathbf{x} = \mathbf{b}$
 $\mathbf{x} \ge \mathbf{0}_n$.

• $\mathbf{x} \in \mathbb{R}^n$ is an optimal feasible solution for (P) and $\mathbf{y} \in \mathbb{R}^m$ is an optimal feasible solution for the corresponding dual (D) if and only if they are feasible solutions and

$$x_i[(\mathbf{A}^T\mathbf{y})_i - c_i] = 0 \ \forall j = 1, \dots, n$$

which is equivalent to

$$x_j > 0 \implies (\mathbf{A}^T \mathbf{y})_j = c_j \text{ or } (\mathbf{A}^T \mathbf{y})_j > c_j \implies x_j = 0.$$

Today in MA30087/50087:

- transporting goods from sources S_1, \ldots, S_m with supplies s_1, \ldots, s_m to destinations D_1, \ldots, D_n with demands d_1, \ldots, d_n
- amount transported from S_i to D_j is x_{ij}
- cost of transporting a unit from S_i to D_j is c_{ij}
- the transportation problem is to

minimise
$$z = \sum_{i=1}^{m} \sum_{j=1}^{n} c_{ij} x_{ij}$$

subject to
$$\sum_{j=1}^{n} x_{ij} \leq s_i \quad i = 1, \dots, m$$

$$\sum_{i=1}^{m} x_{ij} \geq d_j \quad j = 1, \dots, n$$

$$x_{ij} \geq 0 \quad i = 1, \dots, m, j = 1, \dots, n$$

• problem is balanced if $\sum_{i=1}^{m} s_i = \sum_{j=1}^{n} d_j$