

## Previously in MA30087/50087:

- primal (P) and symmetric dual (D) for the standard maximisation problem

$$\begin{array}{ll} \text{maximise} & z = \mathbf{c}^T \mathbf{x} \\ \text{(P) subject to} & \mathbf{Ax} \leq \mathbf{b} \\ & \mathbf{x} \geq \mathbf{0}_n \end{array} \qquad \begin{array}{ll} \text{minimise} & z' = \mathbf{b}^T \mathbf{y} \\ \text{(D) subject to} & \mathbf{A}^T \mathbf{y} \geq \mathbf{c} \\ & \mathbf{y} \geq \mathbf{0}_m \end{array}$$

- Corollary 3
  - if there exists at least one feasible solution to both (P) and (D) then there exist bounded optimal solutions to (P) and (D) with equal objective functions
- (Symmetric) Complementary Slackness Theorem

Consider the standard LP problem (P). Then  $\mathbf{x}$ ,  $\mathbf{y}$  optimal feasible solutions for (P) and (D) respectively if and only if they are feasible solutions and

$$\begin{aligned} y_i[(\mathbf{Ax})_i - b_i] &= 0 \quad \forall i = 1, \dots, m, \\ x_j[(\mathbf{A}^T \mathbf{y})_j - c_j] &= 0 \quad \forall j = 1, \dots, n. \end{aligned}$$

## Today in MA30087/50087:

- Asymmetric Complementary Slackness Theorem

Consider the canonical LP problem. Then  $\mathbf{x}$ ,  $\mathbf{y}$  optimal feasible solutions for the canonical problem and its dual respectively if and only if they are feasible solutions and

$$x_j[(\mathbf{A}^T \mathbf{y})_j - c_j] = 0 \quad \forall j = 1, \dots, n$$

which is equivalent to

$$x_j > 0 \Rightarrow (\mathbf{A}^T \mathbf{y})_j = c_j \quad \text{or} \quad (\mathbf{A}^T \mathbf{y})_j > c_j \Rightarrow x_j = 0.$$