

19/10/2015.

LECTURE 7: 30W2.1.

①

EXAMPLE OF BASIC SOLUTIONS CONTINUED.

$$\underline{A} = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} \quad \underline{b} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

②. SELECT $\{x_1, x_3\}$ AS BASIC, x_2 NON-BASIC.

$$\underline{B} = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} \quad \underline{B}^{-1} = \begin{pmatrix} -1 & 1 \\ 1 & 0 \end{pmatrix} \quad \underline{B}^{-1}\underline{b} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}.$$

THE CORRESPONDING BASIC SOLUTION IS $\underline{x} = (-1, 0, 2)^T$ WHICH IS NOT FEASIBLE.

③. SELECT $\{x_2, x_3\}$ AS BASIC, x_1 NON-BASIC.

$$\underline{B} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \quad \underline{B}^{-1} = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \quad \underline{B}^{-1}\underline{b} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

THE CORRESPONDING BASIC SOLUTION IS $\underline{x} = (0, 1, 1)^T$ WHICH IS FEASIBLE AND THUS A **BASIC FEASIBLE SOLUTION (BFS)**.

EXAMPLE.

SUPPOSE WE CHANGE $\underline{b}$ TO $\underline{b} = (0, 1)^T$.

①. SELECT $\{x_1, x_2\}$ BASIC, x_3 NON-BASIC.

$$\underline{B}^{-1}\underline{b} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ \boxed{0} \end{pmatrix}$$

BASIC SOLUTION IS $\underline{x} = (1, \boxed{0}, 0)^T$ WHICH IS FEASIBLE.

NOTE BASIC VARIABLE EQUAL TO ZERO.

(B).

②. SELECT $\{x_1, x_3\}$ BASIC, x_2 NON-BASIC.

$$B^{-1}b = \begin{pmatrix} -1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

BASIC SOLUTION IS $\underline{x} = (1, 0, 0)^T$ WHICH IS FEASIBLE.

NOTE BASIC VARIABLE EQUAL TO ZERO.

++ TWO BASIS GIVE THE SAME SOLUTION ++

③. SELECT $\{x_2, x_3\}$ BASIC, x_1 NON-BASIC

$$B^{-1}b = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

BASIC SOLUTION IS $\underline{x} = (0, -1, 1)^T$ WHICH IS NOT FEASIBLE.

DEFINITION.

A **DEGENERATE BASIC SOLUTION** OCCURS WHEN ONE OR MORE OF THE BASIC VARIABLES IN A BASIC SOLUTION HAS A VALUE OF ZERO.

MOTIVATING EXAMPLES THUS FAR HAVE SHOWN THAT IF A SOLUTION EXISTS, IT CAN BE FOUND / OBTAINED AT AN EXTREME POINT.

EXAMPLE IN THE PROBLEMS CLASS SUGGESTED A ONE-TO-ONE CORRESPONDENCE BETWEEN EXTREME POINTS AND BASIC SOLUTIONS.

[SHOW CORRESPONDENCE BETWEEN EXTREME POINTS IN STANDARD / CANONICAL PROBLEMS IN Q5 OF QUESTION SHEET THREE]. WE'RE NOW GOING TO PROVE THESE RESULTS.

(C).

DEFINITION

SUPPOSE S IS A CONVEX SET. A POINT $x \in S$ IS SAID TO BE AN **EXTREME POINT** OF S IF THERE ARE NO DISTINCT POINTS $v, w \in S$ SUCH THAT, FOR SOME $\lambda \in (0, 1)$, $x = \lambda v + (1 - \lambda)w$.

i.e. x EXTREME POINT IF IT DOESN'T LIE ON A LINE SEGMENT CONNECTING TWO OTHER POINTS.

NOTE: WE'VE SHOWN FEASIBLE REGIONS OF LP PROBLEMS ARE CONVEX SETS.

THEOREM.

CONSIDER A LP PROBLEM IN CANONICAL FORM WITH FEASIBLE REGION $F_{(1)} = \{x \in \mathbb{R}^n : Ax = b, x \geq 0_n\}$. SUPPOSE x IS A BASIC FEASIBLE SOLUTION. THEN x IS AN EXTREME POINT OF $F_{(1)}$.

PROOF.

IDEA: PROOF BY CONTRADICTION. x BASIC FEASIBLE SOLUTION
SO COLUMNS OF A CORRESPONDING TO VARIABLE IN
BASIS OF LINEARLY INDEPENDENT $\therefore \sum_{j=1}^m \alpha_j a_j = 0_m \Rightarrow$
 $\alpha_j = 0 \forall j = 1, \dots, m$.

WE'LL ASSUME x IS NOT AN EXTREME POINT AND
USE LINEAR INDEPENDENCE TO SHOW NO DISTINCT v, w .

LET x BE A BFS. WLOG, $x = \begin{pmatrix} x_B \\ 0_{n-m} \end{pmatrix}$ WITH $A = (B | N)$

WHERE B IS AN INVERTIBLE $m \times m$ MATRIX.

i.e. $B = (a_1, \dots, a_m)$ HAS m LINEARLY INDEPENDENT COLUMNS
WITH $Bx_B = b$

⑥.

→ SUPPOSE THAT $\underline{x}$ IS NOT AN EXTREME POINT $\neq$

$\Rightarrow \exists \underline{v} = (v_1, \dots, v_n)^T, \underline{w} = (w_1, \dots, w_n)^T \in F_{(c)}$ SUCH THAT
 $\underline{x} = \lambda \underline{v} + (1-\lambda) \underline{w}$ WITH $\underline{v}, \underline{w}$ DISTINCT

NOW, $x_j = 0 \forall j = m+1, \dots, n$

$$\Rightarrow 0 = x_j = \lambda v_j + (1-\lambda) w_j \quad \forall j = m+1, \dots, n.$$

AS $\underline{v}, \underline{w} \in F_{(c)}$ THEN $v_j, w_j \geq 0$ AND $\lambda \in (0, 1)$. THUS,

$$x_j - v_j = w_j = 0 \quad \forall j = m+1, \dots, n.$$

THUS, $\underline{v} = \begin{pmatrix} \underline{v}_B \\ \underline{0}_{n-m} \end{pmatrix}$ AND $\underline{w} = \begin{pmatrix} \underline{w}_B \\ \underline{0}_{n-m} \end{pmatrix}$ WHERE $\underline{v}_B, \underline{w}_B \in \mathbb{R}^m$.

NOW, $\underline{b} = \underline{A} \underline{v} = (\underline{B} \mid \underline{N}) \begin{pmatrix} \underline{v}_B \\ \underline{0}_{n-m} \end{pmatrix} = \underline{B} \underline{v}_B$

THUS, $\underline{B} \underline{x}_B = \underline{B} \underline{v}_B \Rightarrow \underline{B} (\underline{x}_B - \underline{v}_B) = \underline{0}_m$

$$\Rightarrow \sum_{j=1}^m (x_j - v_j) \underline{a}_j = \underline{0}_m.$$

BUT $\underline{a}_1, \dots, \underline{a}_m$ ARE LINEARLY INDEPENDENT $\Rightarrow x_j - v_j = 0 \forall j = 1, \dots, m$.

i.e. $\underline{x}_B = \underline{v}_B \Rightarrow \underline{x} = \underline{v}$ AND HENCE $\underline{v} = \underline{w}$.

THUS, $\underline{v}, \underline{w}$ ARE NOT DISTINCT: CONTRADICTION.

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