

30/11/2015

LECTURE 20: CBI.11.

$$A x = b$$

- NOTE:
- ① A has entries which are either zero or one.
 - ② Each column has only two non-zero entries.
 $\hookrightarrow$ Each row of A^T has only two non-zero entries.

Let $\underline{e}_i^{(m)}$ denote the i th column of the $m \times m$ identity matrix
 $\underline{e}_j^{(n)}$ denote the j th column of the $n \times n$ identity matrix

Then $A = (\underline{e}_{11} \dots \underline{e}_{1n} \underline{e}_{21} \dots \underline{e}_{2n} \dots \underline{e}_{m1} \dots \underline{e}_{mn})$ where

$$\underline{e}_{ij} = \begin{pmatrix} \underline{e}_i^{(m)} \\ \underline{e}_j^{(n)} \end{pmatrix}$$

Let $\underline{x} = (\underline{x}_1^T, \dots, \underline{x}_m^T)^T \in \mathbb{R}^{mn}$ where $\underline{x}_i = (x_{i1}, \dots, x_{in})^T$
 $\underline{c} = (\underline{c}_1^T, \dots, \underline{c}_m^T)^T \in \mathbb{R}^{mn}$ where $\underline{c}_i = (c_{i1}, \dots, c_{in})^T$
 $\underline{b} = (s_1, \dots, s_m, d_1, \dots, d_n)^T \in \mathbb{R}^{m+n}$ then the balanced transportation problem can be written as:

$$\begin{aligned} \text{maximize} \quad & z = \underline{c}^T \underline{x} \\ \text{subject to} \quad & A \underline{x} = \underline{b} \\ & \underline{x} \geq \underline{0}_{mn} \end{aligned}$$

(B)

The dual is.

$$\begin{array}{ll} \text{maximize} & z' = \underline{b}^T \underline{y} \\ \text{subject to} & \underline{A}^T \underline{y} \leq \underline{c} \end{array}$$

$$\left[\begin{array}{ll} \text{(P) maximize} & -\underline{c}^T \underline{x} \text{ subject to } -\underline{A} \underline{x} = -\underline{b}, \underline{x} \geq \underline{0}_{mn} \\ \text{(D) minimize} & -\underline{b}^T \underline{y} \text{ subject to } (-\underline{A})^T \underline{y} \geq -\underline{c} \end{array} \right]$$

Let $\underline{y} = (u_1, \dots, u_m, v_1, \dots, v_n)^T = (\underline{u}^T, \underline{v}^T)^T$ then:

$$\underline{A}^T \underline{y} = \begin{bmatrix} \underline{e}_1^{(m)T} & \underline{e}_1^{(n)T} \\ \vdots & \vdots \\ \underline{e}_i^{(m)T} & \underline{e}_j^{(n)T} \\ \vdots & \vdots \\ \underline{e}_m^{(m)T} & \underline{e}_n^{(n)T} \end{bmatrix} \begin{pmatrix} \underline{u} \\ \underline{v} \end{pmatrix} = \begin{bmatrix} \underline{e}_1^{(m)T} \underline{u} + \underline{e}_1^{(n)T} \underline{v} \\ \vdots \\ \underline{e}_i^{(m)T} \underline{u} + \underline{e}_j^{(n)T} \underline{v} \\ \vdots \\ \underline{e}_m^{(m)T} \underline{u} + \underline{e}_n^{(n)T} \underline{v} \end{bmatrix} \leq \begin{bmatrix} c_{11} \\ \vdots \\ c_{ij} \\ \vdots \\ c_{mn} \end{bmatrix}$$

$$\text{i.e. } u_i + v_j \leq c_{ij} \quad i=1, \dots, m, j=1, \dots, n.$$

$$\text{Similarly, } \underline{b}^T \underline{y} = \sum_{i=1}^m s_i u_i + \sum_{j=1}^n d_j v_j$$

That is, the dual is

$$\begin{array}{ll} \text{maximize} & z' = \sum_{i=1}^m s_i u_i + \sum_{j=1}^n d_j v_j \\ \text{subject to} & u_i + v_j \leq c_{ij} \quad i=1, \dots, m, j=1, \dots, n. \end{array}$$

6.2 KEY PROPERTIES OF THE TRANSPORTATION PROBLEM.

THEOREM.

The balanced transportation problem has a finite optimal solution.

Proof.

We shall show both the balanced transportation problem and its dual are both feasible.

©

$$\text{Let } x_{ij} = \frac{s_i d_j}{\sum_{i=1}^m s_i} \text{ then } \sum_{i=1}^m x_{ij} = \frac{(\sum_{i=1}^m s_i) d_j}{\sum_{i=1}^m s_i} = d_j$$

$$\sum_{j=1}^n x_{ij} = \frac{s_i (\sum_{j=1}^n d_j)}{\sum_{i=1}^m s_i} = s_i \text{ as balanced.}$$

$x_{ij} \geq 0$ so btp feasible. For dual, as $c_{ij} \geq 0$ then $u_i = v_j = 0$ so the dual is feasible.

A consequence of weak duality and duality was Corollary 3 which states: if (P) and (D) are feasible then $\exists$ finite optimal solutions to (P) and (D) with equal values of their objective functions. $\square$

$$\text{In the btp, } \sum_{j=1}^n x_{ij} = s_i, \sum_{i=1}^m x_{ij} = d_j \text{ with } \sum_{j=1}^n d_j = \sum_{i=1}^m s_i$$

so that the $m+n$ constraints are NOT linearly independent.

THEOREM.

$$\text{Rank}(A) = m+n-1$$

Proof

See Question Sheet Nine.

Conclusions.

- Using Fundamental Theorem of LP, optimal solution occurs at bfs.
- Rank(A) = $m+n-1$. So, bfs has at most $m+n-1$ non-zero values.

①

6.3 THE TRANSPORTATION ALGORITHM.

We make use of the asymmetric CS theorem. For the btp we have

$\underline{x}$ is an optimal feasible solution for (P) and $\underline{y}$ is an optimal feasible solution for (D) if and only if they are feasible solutions and

$$x_{ij} [u_i + v_j - c_{ij}] = 0 \quad \forall i=1, \dots, m, j=1, \dots, n$$

which is equivalent to

$$x_{ij} > 0 \Rightarrow u_i + v_j = c_{ij} \quad \text{or} \quad u_i + v_j < c_{ij} \Rightarrow x_{ij} = 0.$$

STRATEGY.

- ① Find a bfs with at most $m+n-1$ non-zero values of x_{ij}
[INITIAL FEASIBILITY]
- ② Use asymmetric CS, write down $m+n-1$ equations $u_i + v_j = c_{ij}$. Set (for example) $u_1 = 0$ and solve.
[SATISFYING CS CONDITIONS]
- ③ If u_i, v_j satisfy $u_i + v_j \leq c_{ij} \quad \forall i, j$ optimal solution found
[DUAL FEASIBLE].
If not, move to another bfs of btp and repeat.

6.3.1 FINDING AN INITIAL BFS: THE NORTH-WEST CORNER METHOD.

Represent shipments from S_i to D_j as an $m \times n$ matrix.

	d_1	...	d_n
s_1	x_{11}	...	x_{1n}
$\vdots$	$\vdots$	$\ddots$	$\vdots$
s_m	x_{m1}	...	x_{mn}

$$\sum_{j=1}^n x_{ij} = s_i$$

$$\sum_{j=1}^n x_{mj} = s_m$$

$$\sum_{i=1}^m x_{i1} = d_1, \dots, \sum_{i=1}^m x_{in} = d_n$$