

23/11/2015.

LECTURE 17: 3LN2.1.

①

PROOF.

As x_0 is feasible to (P) then $A x_0 \leq b$ with $x_0 \geq 0_n$.As y_0 is feasible to (D) then $A^T y_0 \geq c$ with $y_0 \geq 0_m$.Premultiplying $A x_0 \leq b$ by $y_0^T \geq 0_m^T$ gives

$$y_0^T A x_0 \leq y_0^T b = b^T y_0 \quad (\text{as } \mathbb{R}).$$

No change in inequality sign as $y_0 \geq 0_m$

Similarly, premultiplying $A^T y_0 \geq c$ by $x_0^T \geq 0_n^T$ gives

$$y_0^T A x_0 = x_0^T A^T y_0 \geq x_0^T c = c^T x_0 \quad (\text{as } \mathbb{R})$$

$$\Rightarrow c^T x_0 \leq x_0^T A^T y_0 = y_0^T A x_0 \leq b^T y_0 \quad \square.$$

Let $F_{(P)}$ denote the feasible set of the primal and $F_{(D)}$ the feasible set of the dual. As x_0, y_0 were arbitrary feasible solutions to (P) and (D) respectively,

$$\sup_{x \in F_{(P)}} c^T x = \inf_{y \in F_{(D)}} b^T y$$

COROLLARY.

IF the primal problem (P) has a feasible solution but no bounded optimum then (D) has no feasible solution. Likewise, if (D) has a feasible solution but no bounded optimum then (P) has no feasible solution.

Proof.

(P) unbounded $\Rightarrow \exists \alpha \in \mathbb{R}$ such that $c^T x_0 > \alpha$ for some $x_0 \in F_{(P)}$.Thus, for ANY $y_0 \in F_{(D)}$, $b^T y_0 > \alpha$ where α is arbitrary.

There's no finite y_0 with this property (if $b^T y_0$ finite then $b^T y_0 = \beta$ so does $\alpha > \beta$) so no feasible solution to (D).

The alternate argument follows by switching roles. □

[Essentially, $\infty \leq \underline{b}^T y_0$; $\underline{c}^T x_0 \leq -\infty$ no space].

COROLLARY.

Suppose there exist feasible solutions for (P) and (D), say x_0 and y_0 respectively such that $\underline{c}^T x_0 = \underline{b}^T y_0$. Then x_0 and y_0 are optimal for (P) and (D) respectively.

Proof.

For any pair of solutions we have

$$\underline{c}^T x_0 \leq \sup_{x \in F(P)} \underline{c}^T x \leq \inf_{y \in F(D)} \underline{b}^T y \leq \underline{b}^T y_0.$$

If $\underline{c}^T x_0 = \underline{b}^T y_0$ then all above inequalities must be equalities so that x_0 and y_0 are optimal.

THEOREM (DUALITY THEOREM).

The primal problem (P) has a finite optimal solution IF AND ONLY IF the dual problem (D) does too, in which case the optimal value of their objective functions are the same.

Proof.

Outside the scope of the course.

A very nice observation, useful for the transportation problem, is the following:

(C)

Corollary.

Suppose there exists at least one feasible solution to each of (P) and (D). Then there exist bounded optimal solutions to both (P) and (D) with equal values of the objective functions.

Proof.

Follows from the first corollary and the duality theorem.

3.4 COMPLEMENTARY SLACKNESS.

We look at a further theorem relating primal and dual problems.

Note: $\underline{A}\underline{x} \in \mathbb{R}^m$ and $\underline{A}^T\underline{y} \in \mathbb{R}^n$. Let

$$\begin{aligned} (\underline{A}\underline{x}) &= ((\underline{A}\underline{x})_1, \dots, (\underline{A}\underline{x})_m)^T & [(\underline{A}\underline{x})_i: \text{LHS of } i\text{-th constraint}] \\ (\underline{A}^T\underline{y}) &= ((\underline{A}^T\underline{y})_1, \dots, (\underline{A}^T\underline{y})_n)^T \end{aligned}$$

$$\begin{aligned} [\underline{A}\underline{x} \leq \underline{b} & \text{ equivalent to the system } (\underline{A}\underline{x})_i \leq b_i \quad i=1, \dots, m \\ \underline{A}^T\underline{y} \geq \underline{c} & \text{ equivalent to the system } (\underline{A}^T\underline{y})_j \geq c_j \quad j=1, \dots, n] \end{aligned}$$

THEOREM [SYMMETRIC COMPLEMENTARY SLACKNESS].

Consider the standard LP problem (P). Then $\underline{x} \in \mathbb{R}^n$ is an optimal feasible solution for (P) and $\underline{y} \in \mathbb{R}^m$ is an optimal solution for (D) if and only if they are feasible solutions and

$$\begin{aligned} [\underline{y}^T \underline{A}\underline{x} &= \underline{y}^T \underline{b} \text{ and component wise}] & y_i [(\underline{A}\underline{x})_i - b_i] &= 0 \quad \forall i=1, \dots, m \\ [\underline{x}^T \underline{A}^T\underline{y} &= \underline{x}^T \underline{c} \text{ and component wise}] & x_j [(\underline{A}^T\underline{y})_j - c_j] &= 0 \quad \forall j=1, \dots, n \end{aligned}$$

Proof.

 $\Leftarrow$

If $y_i > 0$ then $(\underline{A}\underline{x})_i = b_i$ [i.e. CONSTRAINT IS TIGHT].