

Equational Constraints and Cylindrical Algebraic Decomposition

James Davenport (Bath)
with Russell Bradford (Bath)
and Matthew England (Bath/Coventry)

Thanks to David Wilson (Bath/Silicon Valley), Marc Moreno Maza (U.W.O.),
Changbo Chen (Chongqing), Scott McCallum (Macquarie)

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- 0 Introduction
- 1 Local equational constraints [BDE⁺13, BDE⁺14]
- 2 Multiple/Better Equational Constraints [EBD15]

Cylindrical Algebraic Decomposition in $\mathbf{R}[x_1, \dots, x_n]$, with x_n the first variable to be eliminated.

General method via Projection/Lifting in the style of [Col75, W76].

Open Problem

Extend part 2 of this to the Regular Chains approach [CMXY09]

[Col75] A cylindrical decomposition of \mathbf{R}^n *sign-invariant* for each polynomial

[McC84] A cylindrical decomposition of \mathbf{R}^{n-1} *order-invariant* for each polynomial at this stage, and a cylindrical decomposition of \mathbf{R}^n *sign-invariant* for each polynomial



or failure if the polynomials were not well-oriented which occurs with probability 0 in theory, but quite often in practice.

EC An *equational constraint* is $f(\mathbf{x}) = 0 \wedge \dots$

Motivations for cylindrical algebraic decomposition

- 1 Quantifier elimination — the original one
 - * May have local or global equational constraints
- 2 Robot Motion Planning — [SS83]
 - * Normally has local and global equational constraints
- 3 Branch Cut analysis [BBDP07]
 - * Normally has local equational constraints

Note that we can sometimes transform local ECs into global:

$$(f_1 = 0 \wedge \phi_1) \vee (f_2 = 0 \wedge \phi_2)$$

is equivalent to

$$f_1 f_2 = 0 \wedge [(f_1 = 0 \wedge \phi_1) \vee (f_2 = 0 \wedge \phi_2)]$$

Mostly applicable to Quantifier Elimination

Complexity Analysis for [McC84]

Assume m polynomials of degree (in each variable) $\leq d$.
Measure the *number of cells* in the output.

Upper bounds

[McC85, Theorem 6.1.5] $m^{2^n} (2d)^{n2^n}$

[BDE⁺14, (12)] $2^{2^{n-1}} m(m+1)^{2^n-2} d^{2^n-1}$

* (Same algorithm, better analysis)

Lower bounds (actually of cells in \mathbf{R}^1)

[DH88]; $d = 4$ $2^{2^{(n-1)/5}}$, and these are the roots of a polynomial of this degree

[BD07]; $d = 1$ $2^{2^{(n-1)/3}}$, and in \mathbf{R}^1 these are rationals with a succinct description.

The original EC observation [Co198, McC99b]

If we have a global equational constraint $f = 0 \wedge \phi$, then all we need is a decomposition that is

- 1 Sign (or order) invariant for f
- 2 Sign (or order) invariant for the polynomials g_i of ϕ *when*
 $f = 0$

Intuitively, we can do this by considering f and $\text{Res}_{x_n}(f, g_i)$ rather than f and g_i for the first projection level, build the order-invariant decomposition of \mathbf{R}^{n-1} for these polynomials (as before), then lift to a sign-invariant decomposition of \mathbf{R}^n

Number of cells bounded by [BDE⁺14, (14)]

$$2^{2^{n-1}} d^{2^{n-1}} m(3m + 1)^{2^{n-1}-1},$$

which is “intuitively reasonable” — we can do nothing about degree growth, but combinatorial growth is as for one fewer variable

The theorem that justifies this [McC99b]

Theorem (McCallum1999)

Let f and g be integral polynomials with mvar x_n , and $r(x_1, \dots, x_{n-1}) \neq 0$ be their resultant. Let S be a connected subset of \mathbf{R}^{n-1} on which f is delineable and r *order*-invariant. Then g is *sign*-invariant in every section of f over S .

So we can use the McCallum projection

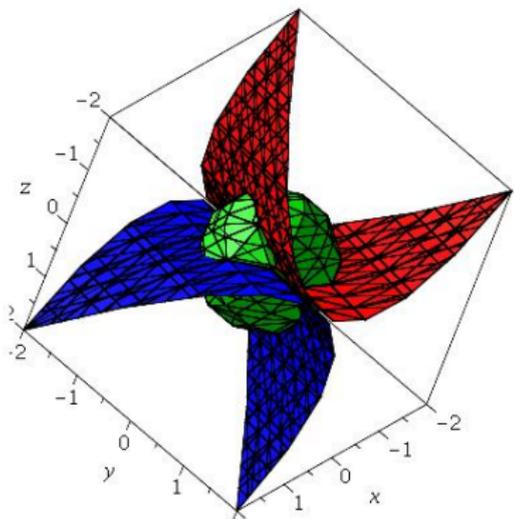
$$P(B) := \text{coeff}(B) \cup \text{Disc}(B) \cup \text{Res}(B)$$

after x_n , where B is the square-free basis of the polynomials, and

$$P_F(B) := P(F) \cup \{\text{Res}(f, g) \mid f \in F; g \in B \setminus F\}$$

at x_n , where F is the square-free basis of the equational constraint. Note that this theorem does not compose nicely with itself.

Example



$$\begin{aligned}f_1 &= x + y^2 + z \\f_2 &= x - y^2 + z \\g &= x^2 + y^2 + z^2 - 1 \\f_1 = 0 \wedge f_2 = 0 \wedge g &\geq 0\end{aligned}$$

Solutions: $y = 0$, $|x| \geq \frac{1}{2}\sqrt{2}$, $z = -x$ (4 cells)

Sign-invariant c.a.d. for $\{f_1, f_2, g\}$ has 1487 cells

Declaring either equational constraint gives 289 cells, but the

solution is 8 cells since we have $x = \frac{1}{2}(1 \pm \sqrt{6})$ as additional points from $\text{Disc}_y(\text{Res}_z(f_1, g))$

Part 1: local equational constraints [BDE⁺13]

Suppose we are doing quantifier elimination on $\phi_1 \vee \phi_2 \vee \dots$, where each ϕ_i is $f_i = 0 \wedge g_i > 0$ (for simplicity).

There is an implicit equation constraint $F := \prod f_i = 0$, and using [McC99a] our first projection is (ignoring coefficients)

$\text{Disc}(F) \cup \{\text{Res}(F, g_i)\}$, which is

$$\{\text{Disc}(f_i)\} \cup \{\text{Res}(f_i, f_j)\} \cup \{\text{Res}(f_i, g_j)\}$$

But this includes $\text{Res}(f_i, g_j)$ ($i \neq j$), which is logically unnecessary, but is needed to give us a decomposition sign-invariant for each f_i, g_j when $F = 0$.

Relax to demanding a decomposition that's **truth-invariant** for each ϕ_i :

$$\{\text{Disc}(f_i)\} \cup \{\text{Res}(f_i, f_j)\} \cup \{\text{Res}(f_i, g_i)\}$$

Very useful for the branch cut problem

But suppose only *some* ϕ_i have equational constraints, so there isn't a global implicit equational constraint.

Then for those ϕ_i that *do* have an equational constraint $f_i = 0$, the corresponding g_i (possibly many) need only feature in $\text{Res}(f_i, g_i)$: for those ϕ_i with no equational constraint, the g_i feature as usual.

Theorem (McCallum2001)

Let f and g be integral polynomials with m var x_n , and $r(x_1, \dots, x_{n-1}) \neq 0$ be their resultant, $d(x_1, \dots, x_{n-1}) \neq 0$ be the discriminant of g . Let S be a connected subset of \mathbf{R}^{n-1} on which f is *analytic* delineable, g not nullified and r, d *order*-invariant. Then g is *order*-invariant in every section of f over S .

This justifies using

$$P_F^*(B) := P_F(B) \cup \text{Disc}(B \setminus F)$$

at levels below x_n where there is an equational constraint, however we need to assume the constraints are primitive.

If we have $f_1 = f_2 = 0$ at x_n , we use $f_1 = 0$ here, and $\text{Res}(f_1, f_2)$ at level x_{n-1} , etc.

The double exponent of m is reduced by the number of equational constraints.

Everyone knows that the main cost of c.a.d. is in the lifting. We can also get better lifting, providing we abandon two key principles:

- 1 That the projection polynomials are a fixed set.
- 2 That the invariance structure of the final CAD can be expressed in terms of sign-invariance of polynomials.

Idea 1: forget polynomials

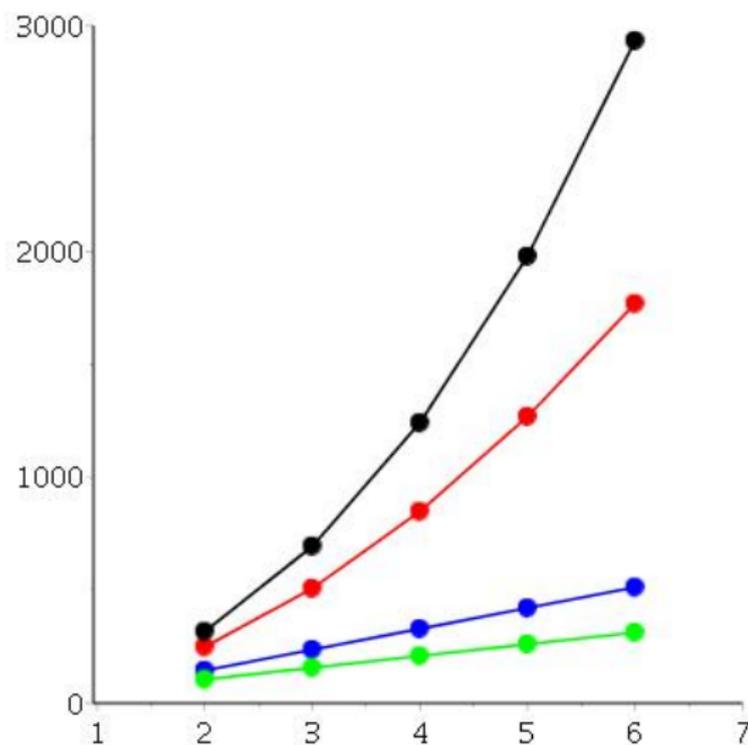
The 1999 theorem states “ g is **sign**-invariant in every section of f over S .”

Hence g is unnecessary at the final lift.

Follows from [McC99a], but only noticed in [BDE⁺13]

Pragmatically very important, but we don't have a theoretical analysis

Idea 1 — Graph of #cells ($n = 2; d = 2; m = 2 \times \text{x-axis}$)



Full CAD
QEPCAD with EC
Our EC with Idea 1
TTICAD

Idea 2: forget sign-invariance

If a cell in \mathbf{R}^k is already known to be false, there is no point doing any (non-trivial) lifting over it.

If we have $f_1 = 0 \wedge f_2 = 0 \wedge \dots$, then in R^{n-2} we will be looking at the zeros of $\text{Res}_{x_n}(f_1, f_2)$. Away from the zeros of this, $f_1 = 0 \wedge f_2 = 0$ is trivially false, so we needn't do any lifting.

Also, no lifting over C means no nullification worries over C , since this is a *local* concern.

Open Problem

Extend the Phase 2 ideas to merge with Phase 1 (done for some of the lifting reduction)

This seems needed for

Open Problem

Handle non-primitive equational constraints:

$$f = 0 \Leftrightarrow \text{pp}_{x_n}(f) = 0 \vee \text{cont}_{x_n}(f) = 0$$

Open Problem

Combine this with [BM09] on iterated resultants.



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