Recent advances in real geometric reasoning

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3-4 July 2014

¹Thanks to: Russell Bradford, Matthew England, David Wilson (Bath), Changbo Chen (Chinese Academy of Sciences, Chongqing), Scott McCallum (Macquarie), Marc Moreno Maza (Western Ontario)

History of Quantifier Elimination

 In 1930, Tarski discovered [Tar51] that the (semi-)algebraic theory of Rⁿ admitted quantifier elimination

$$\exists x_{k+1} \forall x_{k+2} \dots \Phi(x_1, \dots, x_n) \equiv \Psi(x_1, \dots, x_k)$$

• "Semi" = "allowing >,
$$\leq$$
 and \neq as well as ="

- Needed as $\exists y : x = y^2 \Leftrightarrow x \ge 0$
- The complexity of this was indescribable
- In the sense of not being primitive recursive!
- In 1973, Collins [Col75] discovered a much better way:
- Complexity (*m* polynomials, degree *d*, *n* variables, coefficient length *l*)

$$(2d)^{2^{2n+8}}m^{2^{n+6}}l^3 \tag{1}$$

- Construct a cylindrical algebraic decomposition of Rⁿ, sign invariant for every polynomial
- Then read off the answer

A Cylindrical Algebraic Decomposition (CAD) is a mathematical object. Defined by Collins who also gave the first algorithm to compute one. A CAD is:

- a decomposition meaning a partition of **R**ⁿ into connected subsets called cells;
- (semi-)algebraic meaning that each cell can be defined by a sequence of polynomial equations and inequations;
- cylindrical meaning the cells are arranged in a useful manner
 their projections are either equal or disjoint.

In addition, there is (usually) a sample point in each cell, and an index locating it in the decomposition

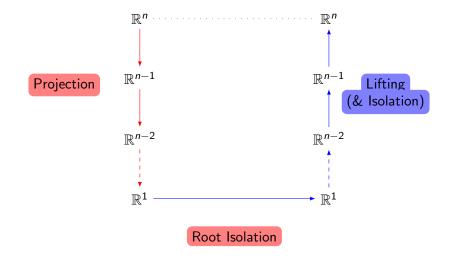
"Read off the answer"

- Each cell is sign invariant, so the the truth of a formula throughout the cell is the truth at the sample point.
- $\forall xF(x) \Leftrightarrow "F(x)$ is true at all sample points"
- $\exists x F(x) \Leftrightarrow$ "F(x) is true at some sample point"
- ∀x∃yF(x, y) ⇔ "take a CAD of R², cylindrical for y projected onto x-space, then check

 \forall sample $x \exists$ sample (x, y) : F(x, y) is true": finite check

NB The order of the quantifiers defines the order of projection So all we need is a CAD!

The basic idea for CAD [Col75]



So how do we project? (Lifting is in fact relatively straight-forward)

Given polynomials $\mathcal{P}_n = \{p_i\}$ in x_1, \ldots, x_n , what should \mathcal{P}_{n-1} be? Naïve (Doesn't work!) Every $\operatorname{disc}_{x_n}(p_i)$, every $\operatorname{res}_{x_n}(p_i, p_i)$

- i.e. where the polynomials fold, or cross: misses lots of "special" cases
- [Col75] First enlarge \mathcal{P}_n with all its reducta, then naïve plus the coefficients of \mathcal{P}_n (with respect to x_n) the principal subresultant coefficients from the $\operatorname{disc}_{x_n}$ and res_{x_n} calculations
- [Hon90] a tidied version of [Col75].
- [McC88] Let \mathcal{B}_n be a squarefree basis for the primitive parts of \mathcal{P}_n . Then \mathcal{P}_{n-1} is the contents of \mathcal{P}_n , the coefficients of \mathcal{B}_n and every $\operatorname{disc}_{x_n}(b_i)$, $\operatorname{res}_{x_n}(b_i, b_j)$ from \mathcal{B}_n

[Bro01] Naïve plus leading coefficients (not squarefree!)

Are these projections correct?

[Col75] Yes, and it's relatively straightforward to prove that, over a cell in \mathbb{R}^{n-1} sign-invariant for \mathcal{P}_{n-1} , the polynomials of \mathcal{P}_n do not cross, and define cells sign-invariant for the polynomials of \mathcal{P}_n

[McC88] 52 pages (based on [Zar75]) prove the equivalent statement, but for order-invariance, not sign-invariance, provided the polynomials are well-oriented, a test that has to be applied during lifting.

But if they're not known to be well-oriented?

[McC88] suggests adding all partial derivatives

In practice hope for well-oriented, and if it fails use Hong's projection.

[Bro01] Needs well-orientedness and additional checks

If the McCallum projection is well-oriented, the complexity is

$$(2d)^{n2^{n+7}}m^{2^{n+4}}l^3 (2)$$

versus the original

$$(2d)^{2^{2n+8}}m^{2^{n+6}}l^3 \tag{1}$$

and in practice the gains in running time can be factors of a thousand, or, more often, the difference between feasibility and infeasibility

"Randomly", well-orientedness ought to occur with probability 1, but we have a family of "real-world" examples where it often fails

The Heintz construction

$$\Phi_k(x_k, y_k) := \\ \exists z_k \forall x_{k-1} y_{k-1} \begin{bmatrix} y_{k-1} = y_k \land x_{k-1} = z_k \lor y_{k-1} = z_k \land x_{k-1} = x_k \\ \Rightarrow \Phi_{k-1}(x_{k-1}, y_{k-1}) \end{bmatrix}$$

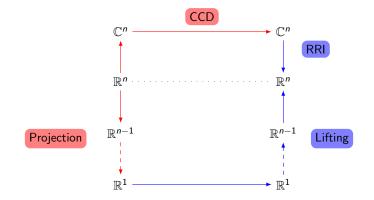
If $\Phi_1 \equiv y_1 = f(x_1)$, then $\Phi_2 \equiv y_2 = f(f(x_2))$, $\Phi_3 \equiv y_3 = f(f(f(x_3))))$ [DH88] shows $\Omega\left(2^{2^{(n-2)/5}}\right)$ (using $y_R + iy_I = (x_R + ix_I)^4$) [BD07] shows $\Omega\left(2^{2^{(n-1)/3}}\right)$ (using a sawtooth) Hence doubly exponential is inevitable, but there's a lot of room! In fact, there are theoretical algorithms which are singly-exponential in *n*, but doubly-exponential in the number of $\exists \forall$ alternations

Useful special cases

Roughly speaking, the effect is to reduce n by 1, which square roots the complexity

An alternative approach [CMMXY09]

Proceed via the complex numbers,



Do a complex cylindrical decomposition via Regular Chains Can be combined with truth table ideas [BCD⁺14]

Example Complex CD

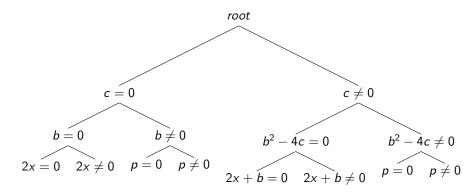


Figure: Complete complex cylindrical tree for the general monic quadratic equation, $p := x^2 + bx + c$, under variable ordering $c \prec b \prec x$.

Note that b = 0 is only tested where relevant

Trivially for \exists problems a positive result, or negative for \forall problems, is easily verified (witness computation)

Negative \exists is essentially refutation [JdM12]

Otherwise we're believing a complicated software package and some maths

[Col75] Algebra system + 3200LOC + "some maths"

[McC88] Algebra system + 3200LOC + "a lot of maths"

[CMMXY09] Algebra system + 5000LOC + "medium maths"

[BDE⁺13] Algebra system + 6200LOC + "medium maths"

Proven software? [CM12] does QE (not full CAD), loosely based on [Col75], in COQ, but terribly impractical Note that CAD has other applications — algebraic simplification [BCD⁺02], robot path planning [SS83], which tends to require adjacency(unsolved in general dimension)

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