

Lecture2: Hybrid numerical-asymptotic methods in high-frequency scattering

Ivan Graham (University of Bath, UK)

A survey of joint work with and work by:

V. Domínguez (Navarra)
E.A. Spence, T.Kim (Bath),
T. Betcke, V. Smyshlyaev (Univ. College London)
S. Chandler-Wilde, S. Langdon, D. Hewitt (Reading)

CUHK, January 2016

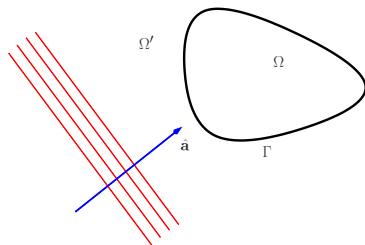
[S.N. Chandler-Wilde, IGG, S.Langdon, E.A. Spence,
Acta Numerica 21 (2012), pp 89-305]

High freq. problem for the Helmholtz equation

Given an object $\Omega \subset \mathbb{R}^d$, with boundary Γ and exterior Ω' ,

Incident plane wave: $u_I(x) = \exp(ik\mathbf{x} \cdot \hat{\mathbf{a}})$

wavelength $\lambda = 2\pi/k$



Total wave $u = u_I + u_S$, where **Scattered wave** u_S satisfies:

$$\Delta u_S + k^2 u_S = 0 \quad \text{in } \Omega'$$

plus **boundary condition** (Here $u_I + u_S = 0$ on Γ) and

radiation condition: $\frac{\partial u^S}{\partial r} - ik u^S = o(r^{-(d-1)/2})$ as $r \rightarrow \infty$

Recap of Lecture 1

- Homogeneous scattering problem : k constant, infinite domain
- Boundary integral equation posed on scattering boundary Γ
- Solve using piecewise polynomial BEM
- Require at least $h \sim k^{-1}$ to resolve oscillations in solution
 \implies complexity $\mathcal{O}(k^{d-1})$
- Proof that $h \sim k^{-(d+1)/2}$ is sufficient
 \implies complexity $\mathcal{O}(k^{(d^2-1)/2})$

Recap of Lecture 1

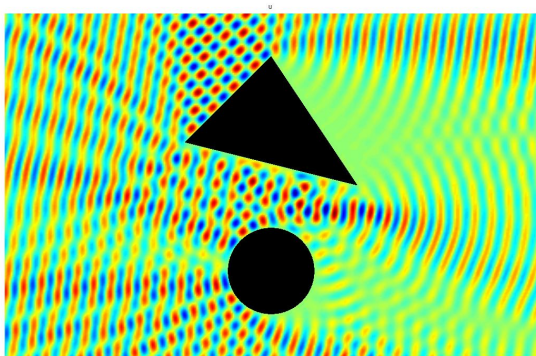
- Homogeneous scattering problem : k constant, infinite domain
- Boundary integral equation posed on scattering boundary Γ
- Solve using piecewise polynomial BEM
- Require at least $h \sim k^{-1}$ to resolve oscillations in solution
 \implies complexity $\mathcal{O}(k^{d-1})$
- Proof that $h \sim k^{-(d+1)/2}$ is sufficient
 \implies complexity $\mathcal{O}(k^{(d^2-1)/2})$

This lecture

- Different methods which have complexity (almost) bounded as $k \rightarrow \infty$

How is this possible?

A multiscale problem



Plane wave incident field $\exp(i\mathbf{k}\mathbf{x}\cdot\hat{\mathbf{a}})$ scale $\mathcal{O}(k^{-1})$.

May be other **scales in the scattered field**, $k^{-1/2}$, $k^{-1/3}$

Conventional numerical methods (piecewise polynomial bases)

→ at least $O(k^{d-1})$ DOF's

Conventional asymptotic methods work well as $k \rightarrow \infty$.
[Fock, Ludwig, Buslaev, Babich]

Today's topic: "Hybrid numerical-asymptotic Methods"
piecewise oscillatory bases work for all k

require $\sim \mathcal{O}(1)$ DOF's as $k \rightarrow \infty$

Need asymptotic information, so geometry dependent

Related: Plane-wave bases for general geometries

Research Plan

I. Construct oscillatory basis (for Galerkin BEM)

II. Prove error estimates

III. Realise the estimates

First formulate as BIE (last lecture)

$$\Delta u + k^2 u = 0$$

$$G_k(x, y) = \begin{cases} \frac{i}{4} H_0^{(1)}(k|x-y|) & \text{2D} \\ \frac{\exp(ik|x-y|)}{4\pi|x-y|} & \text{3D} \end{cases}$$

single layer potential : $(\mathcal{S}_k \phi)(x) = \int_{\Gamma} G_k(x, y) \phi(y) dS(y)$,

double layer: $(\mathcal{D}_k \phi)(x) = \int_{\Gamma} [\partial_{n(y)} G_k(x, y)] \phi(y) dS(y)$,

adjoint double layer: \mathcal{D}'_k (switch roles of x and y).

Oscillatory integrals with **phase**: $k|x-y|$ **blackboard 1**

combined potential formulation

$$R_k v := \left(\frac{1}{2} I + \mathcal{D}'_k \right) v - ik \mathcal{S}_k v = \partial_n u_I - ik u_I := f_k ,$$

star - combined potential formulation: (requires an origin)

$$R_k v := (\mathbf{x} \cdot \mathbf{n}) \left(\frac{1}{2} I + \mathcal{D}'_k \right) v + \mathbf{x} \cdot (\nabla_{\Gamma} \mathcal{S}_k) v - i\eta \mathcal{S}_k v = f_k ,$$

$(\mathbf{x} \cdot \mathbf{n}) > 0$ **star-shaped**

combined potential formulation

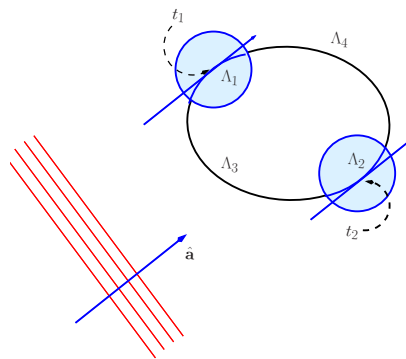
$$R_k v := \left(\frac{1}{2} I + \mathcal{D}'_k \right) v - ik \mathcal{S}_k v = \partial_n u_I - ik u_I := f_k ,$$

star - combined potential formulation: (requires an origin)

$$R_k v := (\mathbf{x} \cdot \mathbf{n}) \left(\frac{1}{2} I + \mathcal{D}'_k \right) v + \mathbf{x} \cdot (\nabla_{\Gamma} \mathcal{S}_k) v - i\eta \mathcal{S}_k v = f_k ,$$

In general $R_k v = f_k$ No spurious frequencies.

Construct basis: 2D smooth convex case



“Physical optics” approx

$$v(\gamma(s)) := k \exp(ik\gamma(s)\cdot\hat{\mathbf{a}}) V(s).$$

$\gamma(s)$ = arclength

blackboard 2

V = “Slowly varying” factor in $v = \partial u / \partial n$.

- Λ_1, Λ_2 : **Fock zones** V oscillates on scale $k^{-1/3}$

+ other complications!

- Λ_3 : **Illuminated** V smooth, not oscillatory.
- Λ_4 : **Deep Shadow** $V \approx 0$ exponentially

Ex: 2D smooth convex case : prove error estimate

Solve combined potential formulation with basis:

$$v_h(s) := \begin{cases} k \exp(ik\gamma(s) \cdot \hat{\mathbf{a}}) P_p(s) & \text{Illuminated zone} \\ k \exp(ik\gamma(s) \cdot \hat{\mathbf{a}}) P_p(s) & \text{Fock zones } \mathcal{O}(k^{-1/3}) \\ 0 & \text{Shadow} \end{cases}$$

where $P_p =$ polynomial of degree p

Theorem (Dominguez, IGG, Smyshlyaev, 07)

$$\frac{\|v - v_h\|_{L^2(\Gamma)}}{k} \leq C_n k^{1/18} \left\{ \left(\frac{k^{1/9}}{p} \right)^n + \exp(-\beta k^\epsilon) \right\},$$

for all p and $n \approx p + 1$. C_n, β are constants independent of k and $\epsilon \approx 0$.

Corollary Choosing $p \sim k^{1/9+\delta}$ “is sufficient” as $k \rightarrow \infty$.

k – explicit regularity

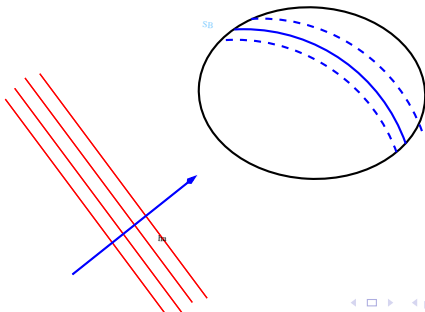
G.O. $v(\mathbf{x}) := \partial u / \partial n = kV(\mathbf{x}, k) \exp(ik\mathbf{x} \cdot \hat{\mathbf{a}}), \quad x \in \Gamma,$

Theorem Dominguez, et. al, 2007

$$|D^n V(x, k)| \leq \begin{cases} C_n, & n = 0, 1, \\ C_n k^{-1} (k^{-1/3} + \text{dist}(x, SB))^{-(n+2)} & n \geq 2, \end{cases}$$

where $SB = \{x \in \Gamma : \mathbf{n}(x) \cdot \hat{\mathbf{a}} = 0\}$ shadow boundary.

Proof Development of Melrose and Taylor (1985) plus matched asymptotic expansions. **Justifies HF Galerkin method above**



Ex: 2D smooth convex case: realise the estimates

Scattering by circle

Galerkin (with quadrature - see later)

Degree of the polynomials $p_I = p_{F_1} = p_{F_2} = \mathbf{p}$

Relative error $\|v - v_h\|/k$ **[All norms $\|\cdot\|_{L^2(\Gamma)}$]**

	$k = 250$	$k = 4,000$	$k = 64,000$
$\mathbf{p} = 4$	5.57E - 03	1.57E - 03	4.69E - 04
$\mathbf{p} = 8$	6.62E - 04	2.72E - 04	7.96E - 05
$\mathbf{p} = 12$	4.43E - 04	4.55E - 05	1.50E - 05
$\mathbf{p} = 16$	1.42E - 03	3.92E - 05	6.91E - 06
$\mathbf{p} = 20$	2.47E - 03	2.74E - 04	7.43E - 06

Ex: 2D Smooth convex case: computation times

$p = 20$: 63 degrees of freedom

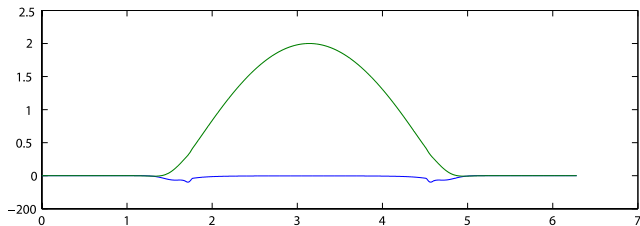
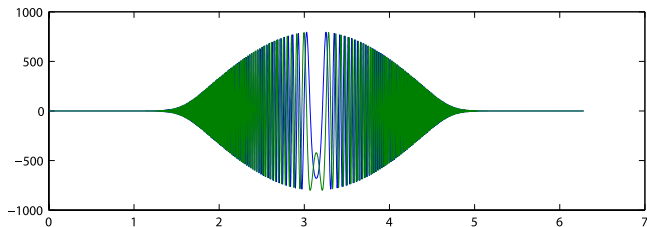
Times (sec) to achieve a relative error: $\leq 10^{-3}$:

k	setting up quadrature rules	assembling matrix
256	248 s	227 s
6400	227 s	230 s

Solution on circle $k = 400$

full wave solution (top)

computed slowly oscillatory part (bottom):



I. Construct oscillatory basis functions More later

II. Prove error estimates

III. Implement the methods (oscillatory integration)

1/3

II. Error Estimates: Hybrid methods

Exotic (k -dependent) subspace: $\mathcal{V}_{h,k} \subset L_2(\Gamma)$.

Galerkin method for $R_k v = f_k$:

Seek $v_h \in \mathcal{V}_{h,k}$ such that

$$(R_k v_h, w_h) = (f_k, w_h) \quad \text{for all } w_h \in \mathcal{V}_{h,k}$$

Céa's lemma Assume there exist $B_k > 0, \alpha_k > 0$ such that

Continuity: $\|R_k\| \leq B_k$,

Coercivity[†]: $|(R_k v, v)| \geq \alpha_k \|v\|^2$

Then we have (**with no mesh restriction**),

$$\|v - v_h\| \leq \left(\frac{B_k}{\alpha_k} \right) \inf_{w_h \in \mathcal{V}_{h,k}} \|v - w_h\|.$$

[†] Stronger than invertibility.

blackboard 3

II. Error Estimates: Hybrid methods

Exotic (k -dependent) subspace: $\mathcal{V}_{h,k} \subset L_2(\Gamma)$.

Galerkin method for $R_k v = f_k$:

Seek $v_h \in \mathcal{V}_{h,k}$ such that

$$(R_k v_h, w_h) = (f_k, w_h) \quad \text{for all } w_h \in \mathcal{V}_{h,k}$$

Céa's lemma Assume there exist $B_k > 0, \alpha_k > 0$ such that

Continuity: $\|R_k\| \leq B_k \sim k^{(d-1)/2}$ Lecture 1 ,

Coercivity[†]: $|(R_k v, v)| \geq \alpha_k \|v\|^2$???

Then we have (with no mesh restriction),

$$\|v - v_h\| \leq \left(\frac{B_k}{\alpha_k} \right) \inf_{w_h \in \mathcal{V}_{h,k}} \|v - w_h\| .$$

[†] Stronger than invertibility.

blackboard 3

II. Some recent (positive) results - nontrapping

Combined potential formulation is **uniformly coercive** with $\alpha_k = 1/2 - \epsilon$, $\epsilon > 0$ for circle and sphere

[DoGrSm]

Fourier analysis symbol: $\frac{\pi k}{2} H_{|m|}^{(1)}(k)(J_{|m|}(k) + iJ'_{|m|}(k)).$

blackboard 4

II. Some recent (positive) results - nontrapping

Combined potential formulation is **uniformly coercive** with $\alpha_k = 1/2 - \epsilon$, $\epsilon > 0$ for circle and sphere

[DoGrSm]:

Fourier analysis symbol: $\frac{\pi k}{2} H_{|m|}^{(1)}(k)(J_{|m|}(k) + iJ'_{|m|}(k)).$

blackboard 4

The star combined formulation is **uniformly coercive**

$\alpha_k = \frac{1}{2} \text{ess inf}_{\mathbf{x} \in \Gamma} (\mathbf{x} \cdot \mathbf{n}(\mathbf{x}))$ for star-shaped Lipschitz domains.

[SpChGrSm]

II. Some recent (positive) results - nontrapping

Combined potential formulation is **uniformly coercive** with $\alpha_k = 1/2 - \epsilon$, $\epsilon > 0$ for circle and sphere

[DoGrSm]:

Fourier analysis symbol: $\frac{\pi k}{2} H_{|m|}^{(1)}(k)(J_{|m|}(k) + iJ'_{|m|}(k))$
blackboard 4

The star combined formulation is **uniformly coercive**

$\alpha_k = \frac{1}{2} \operatorname{ess\,inf}_{\mathbf{x} \in \Gamma} (\mathbf{x} \cdot \mathbf{n}(\mathbf{x}))$ for star-shaped Lipschitz domains.

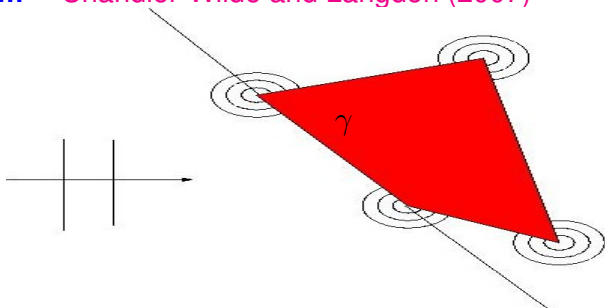
[SpChGrSm]

The combined potential formulation is **uniformly coercive** (for k large enough) for strictly convex smooth domains.

Spence, Kamotski and Smyshlyaev, 2014

More general geometries?

Theorem Chandler-Wilde and Langdon (2007)



$$\frac{\partial u}{\partial n}(s) = 2 \frac{\partial u^I}{\partial n}(s) + e^{iks} v_+(s) + e^{-iks} v_-(s)$$

where s is distance along γ , and

$$k^{-n} |v_+^{(n)}(s)| \leq \begin{cases} C_n (ks)^{-1/2-n}, & ks \geq 1, \\ C_n (ks)^{-\alpha-n}, & 0 < ks \leq 1, \end{cases}$$

where $\alpha < 1/2$ depends on the corner angle.

convex polygon - error estimate

Mesh with $\mathcal{O}(N)$ points, graded towards corners

Piecewise polynomials of degree p .

Then (under some reasonable assumption)

$$\frac{\|v - v_N\|}{k^{1/2}} \lesssim (\log(k))^{1/2} \left(\frac{\log(k)}{N} \right)^{p+1}$$

hp-version: **Hewett, Langdon, Melenk, 2012**

$$\frac{\|v - v_N\|}{k^{1/2}} \lesssim k^\epsilon \exp(-N^{1/2}\tau), \quad \epsilon \in (0, 1/2), \quad \tau > 0.$$

where N is the dimension of the approximating space.

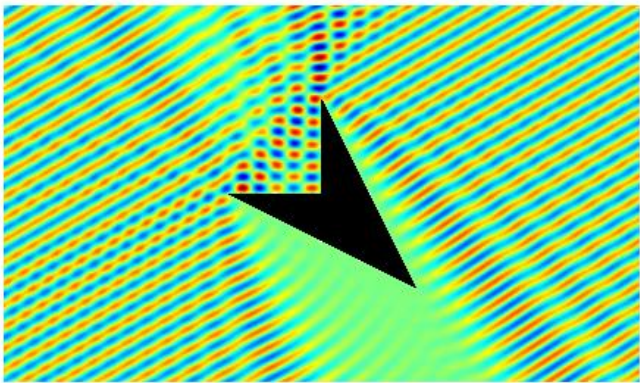
Convex Polygon

hp-scheme of Hewett, Langdon & Melenk with $N = 192$

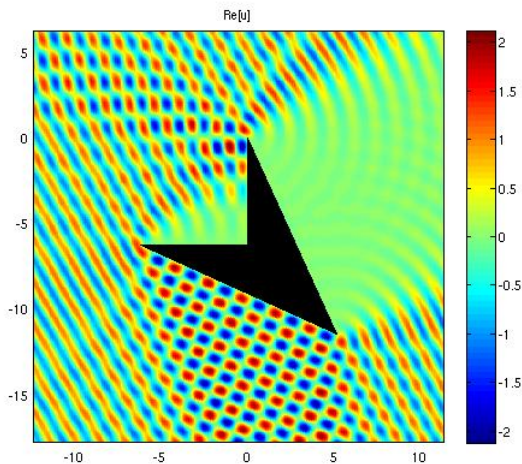
k	Relative L^2 error in $\frac{\partial u}{\partial n}$	Time (s)
10	1.46×10^{-2}	461
40	1.50×10^{-2}	615
160	1.55×10^{-2}	615
640	1.58×10^{-2}	732
2560	1.73×10^{-2}	844
10240	1.74×10^{-2}	940

Logarithmic in k

non-convex polygon



non-convex polygon



Chandler-Wilde, Hewett, Langdon, Twigger, 2011:
HF Ansatz taking account of diffractions at corners and reflections

hp-BEM: Non-convex polygon
Chandler-Wilde, Hewett, Langdon, Twigger, 2011

k	dof	dof per λ	L^2 error	Relative L^2 error
5	320	10.7	2.09e-2	1.51e-2
10	320	5.3	1.07e-2	1.11e-2
20	320	2.7	4.60e-3	6.91e-3
40	320	1.3	3.13e-3	6.83e-3

Recent work from the group at Reading (UK)

S. N. Chandler-Wilde, D. P. Hewett, S. Langdon, A. Twigger, A high frequency boundary element method for scattering by a class of nonconvex obstacles, *Numer. Math.*, 129(4), 2015

S. P. Groth, D. P. Hewett, S. Langdon, Hybrid numerical-asymptotic approximation for high frequency scattering by penetrable convex polygons, *IMA J. Appl. Math.*, 80(2), 2015

D. P. Hewett, S. Langdon, S. N. Chandler-Wilde, A frequency-independent boundary element method for scattering by two-dimensional screens and apertures, *IMA J. Numer. Anal.*, 35(4), 2015

D. P. Hewett, Shadow boundary effects in hybrid numerical-asymptotic methods for high frequency scattering, *Euro. J. Appl. Math.*, 26(5), 2015

I. Construct oscillatory basis functions

II. Prove error estimates

III. Implement the methods (oscillatory integration)

III Implementing the methods: oscillatory integration

Galerkin matrix involves **oscillatory integrals**, e.g. (in 2D):

$$\begin{aligned} & \int \exp(-ik \hat{\mathbf{a}} \cdot \mathbf{x}) P_\ell(\mathbf{x}) \int H_0^{(1)}(k|\mathbf{x} - \mathbf{y}|) \exp(ik \hat{\mathbf{a}} \cdot \mathbf{y}) P_{\ell'}(\mathbf{y}) dy dx \\ &= \int \int \exp(ik \{|\mathbf{x} - \mathbf{y}| + \hat{\mathbf{a}} \cdot (\mathbf{y} - \mathbf{x})\}) M_k(\mathbf{x}, \mathbf{y}) dy dx \end{aligned}$$

M_k not oscillatory. Arc-length: $\mathbf{x} = \gamma(s)$, $\mathbf{y} = \gamma(t)$

$$\int \int \exp(ik \Psi(s, t)) M_k(s, t) dt ds ,$$

Phase:

blackboard 5

$$\Psi(s, t) = |\gamma(s) - \gamma(t)| + \hat{\mathbf{a}} \cdot (\gamma(t) - \gamma(s)) =: \psi_{[s]}(t) .$$

Strategy: change of variable $t \rightarrow \tau$, with $\tau = \psi_{[s]}(t)$ for each s .

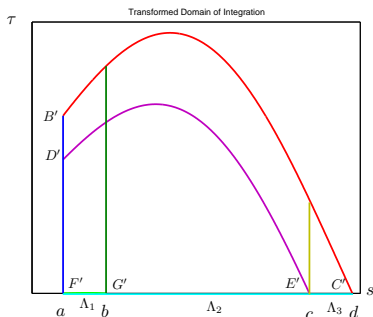
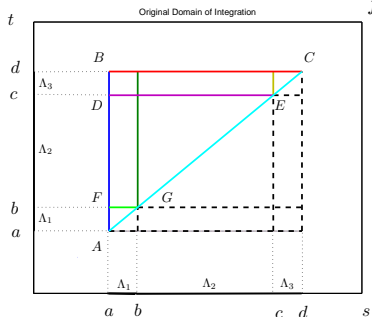
Stationary points? - **Ignore for the moment**

Change of variable - example

$$\begin{aligned}
 I &:= \int_b^c \int_s^c \exp(ik\Psi(s, t)) M_k(s, t) dt ds \\
 &= \int_b^c \left[\int_0^{\psi_{[s]}(c)} \exp(ik\tau) M_k(s, \psi_{[s]}^{-1}(\tau)) |J(s, \tau)| d\tau \right] ds,
 \end{aligned}$$

Switching order of integration:

$$= \int_0^{\tau_{\max}} \underbrace{\left[\int_{r_1(\tau)}^{r_2(\tau)} M_k(s, \psi_{[s]}^{-1}(\tau)) |J(s, \tau)| ds \right]}_{f(\tau)} \exp(ik\tau) d\tau$$



Filon-Censhaw-Curtis rules

$$\int_{-1}^1 f(\tau) \exp(ik\tau) d\tau \approx \int_{-1}^1 (Q_N f)(\tau) \exp(ik\tau) d\tau$$

Polynomial interpolant $(Q_N f)(\cos(j\pi/N)) = f(\cos(j\pi/N))$
Nested, Implementation via FFT in $\mathcal{O}(N \log N)$ operations.
Stable implementation: [DoGrSm].

Theorem For $r \in [0, 1]$, and all $m \geq 1$,

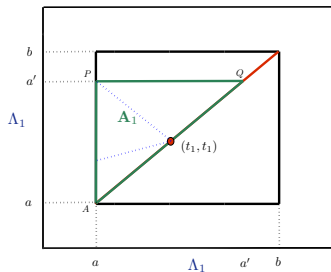
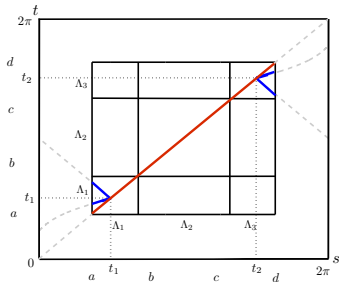
$$\left| \int_{-1}^1 (f - Q_N f)(\tau) \exp(ik\tau) d\tau \right| \lesssim \left(\frac{1}{k}\right)^r \left(\frac{1}{N}\right)^{m-r} \int_{-1}^1 \frac{|f^{(m)}(x)|^2}{\sqrt{1-x^2}}$$

M - point composite version for singularities

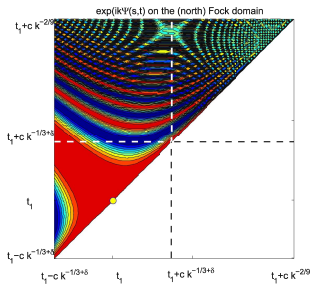
$$\left(\frac{1}{k}\right)^r \left(\frac{1}{M}\right)^{N+1-r} \|f\|_{N+1, \text{singular}}$$

Allowing stationary points in f [DoGrKi]

Stationary points of $\psi_{[s]}$ (T. Kim, PhD)



In A_1 $|D_{(s,t)}^{\mathbf{P}} \exp(ik\Psi(s, t))| \lesssim k^{|\mathbf{P}|/3}$ **Use conventional rules**



Ellipse with $a = 3$, $b = 1$. Relative errors at the point where the incident wave is orthogonal to Γ . (T. Kim)

p	$k = 1000$	$k = 4000$	$k = 8000$	$k = 16000$	relative time
6	3.70(-3)	2.43(-2)	4.31(-2)	8.32(-2)	1
8	3.24(-3)	8.62(-3)	1.74(-2)	2.56(-2)	1.5
10	2.69(-3)	3.35(-3)	7.23(-3)	9.79(-3)	2.3
12	2.47(-3)	1.97(-3)	3.07(-3)	2.90(-3)	3.1
14	3.15(-3)	1.27(-3)	1.39(-3)	1.49(-4)	4.1
16	4.06(-3)	9.28(-4)	6.15(-4)	8.12(-5)	5.3
18	2.84(-3)	1.43(-3)	5.46(-4)	2.81(-5)	6.8
			$\mathcal{O}(\exp(-0.4p))$		$\approx \mathcal{O}(p^2)$

Table: $|2i - \tilde{V}_d(\pi, k)|$, $a = 3, b = 1$.

- In this variant computational times are fixed w.r.t. k .
- For fixed very small p , errors grow slightly with k . For larger p , errors decrease as $k \rightarrow \infty$.
- For fixed k the rate of convergence appears exponential in p and computational time is about $\mathcal{O}(p^2)$.

Summary

- Highly oscillatory scattering problem solved in time which is empirically close to $\mathcal{O}(1)$ as $k \rightarrow \infty$.
- The method and analysis are geometry dependent
So are ray tracing algorithms
- Galerkin approach and knowledge of asymptotics allow rigorous error estimates
- New results: asymptotics of solutions, estimates for oscillatory integral operators and quadrature for oscillatory integrals
- 3D presents significant challenges:
3D screen problems: [Chandler-Wilde, Langdon, Hewett, 2012, 2015]