Control Theory Seminars Programme, Semester 1, 2011/12

Time: Thursdays, 12:15 Venue: 4W1.7

13 Oct	E Sarkans	On a platoon model
20 Oct	H Logemann	Finite-dimensional sampled-data stabilization of infinite-dimensional systems, part 1
27 Oct	H Logemann	Finite-dimensional sampled-data stabilization of infinite-dimensional systems, part 2
03 Nov		NO SEMINAR
10 Nov	M R Opmeer	Negative imaginary functions revisited from a complex analysis viewpoint
17 Nov		NO SEMINAR – EPSRC VISIT
24 Nov	E Sarkans	Higher order input-output models, behaviours and state-space systems
01 Dec	E P Ryan	Systems with homogeneous vector fields: stabilization by linear output feedback is sufficient a priori infor- mation for adaptive control
08 Dec	C W Guiver	A gap metric error bound for positive real balanced truncation