Group Sequential and Adaptive Clinical Trial Designs:

Achievements and Challenges

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Outline of talk

- 1. Some reminiscences about Cornell
- Optimising a group sequential stopping rule
 Problem formulation and optimisation
 Related problems
- International Conference on Harmonisation: ICH E20, Guideline on Adaptive Designs for Clinical Trials
 - General principles
 - Inference after a group sequential or adaptive clinical trial
- 4. Concluding remarks

As a PhD student at Cornell from 1978 to 1982, I learnt from

Jack KieferBob BechhoferShayle SearleLarry BrownTom SantnerWalt FedererRoger FarrellLionel WeissDoug RobsonEugene DynkinLes TrotterPhilip McCarthyBruce TurnbullMike ToddPaul Velleman

Fellow PhD students included

Iain JohnstoneBob VanderbeiWalter PiegorschSusan GroshenRadhika KulkarniChuck McCullochCostas GatsonisCarolyn LichtensteinLuke TierneyMosuk ChowDave GoldsmanRichard Smith

In three summer internships at the Dana Farber Cancer Institute in Boston, I met and learnt from

Marvin Zelen	Cyrus Mehta	Janet Barnes	
Bill Costello	Nitin Patel	Dave Tritchler	
Colin Begg	Dave Schoenfeld	Gregg Dinse	
Marcello Pagano	Jim Hanley	Gordon Flowerdew	
	Steve Lagakos		

This work taught me about applied data analysis and how clinical trials are conducted.

It helped bridge the gap between academic research and applied statistics.

One of the first lectures I attended at Cornell was in the course IOR 676: Survival Data Analysis, given by Bruce Turnbull



Bruce became my PhD supervisor and we have worked together ever since.

A year after I graduated, Bruce Turnbull and Bob Bechhofer invited me back for the summer. This started an annual pattern and I have returned to Ithaca and Cornell almost every year since then.

Bruce and I have written 25 papers together and two books.

GROUP SEQUENTIAL **METHODS** with APPLICATIONS to CLINICAL TRIALS Christopher lennison Bruce W. Turnbull



What we looked like then — at the Kiefer-Wolfowitz Statistical Research Conference, Cornell, 1983:





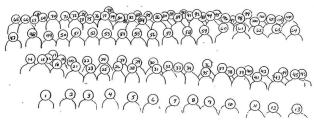






Chris Jennison

Group Sequential and Adaptive Clinical Trial Designs



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2. Optimising a group sequential clinical trial

Reference: Jennison & Turnbull, Kuwait Journal of Science, 2013.

Consider a Phase 3 clinical trial comparing a new treatment against a standard.

Let θ denote the "effect size", a measure of the improvement in the new treatment over the standard.

We shall test the null hypothesis H_0 : $\theta \le 0$ against $\theta > 0$.

Rejecting H_0 allows us to conclude the new treatment is superior.

We allow type I error probability α for rejecting H_0 when it is true.

We specify power $1-\beta$ as the probability of rejecting H_0 when $\theta=\delta$. Here δ is, typically, the minimal clinically significant treatment difference.

The trial design, including the method of analysis and stopping rule, must be set up to attain these error rates.

Sequential distribution theory

Let $\widehat{\theta}_k$ denote the estimate of the treatment effect θ at analysis k.

Information for θ at analysis k is $\mathcal{I}_k = \{ \mathsf{Var}(\widehat{\theta}_k) \}^{-1}, \ k = 1, \dots, K.$

Canonical joint distribution of $\widehat{\theta}_1, \dots, \widehat{\theta}_K$

In many situations, in the absence of early stopping, $\widehat{\theta}_1,\ldots,\widehat{\theta}_K$ are approximately multivariate normal,

$$\widehat{\theta}_k \sim N(\theta, \{\mathcal{I}_k\}^{-1}), \quad k = 1, \dots, K,$$

and

$$\mathsf{Cov}(\widehat{\theta}_{k_1}, \widehat{\theta}_{k_2}) = \mathsf{Var}(\widehat{\theta}_{k_2}) = \{\mathcal{I}_{k_2}\}^{-1} \quad \text{for } k_1 < k_2.$$

References:

Jennison & Turnbull, JASA, 1997,

Scharfstein et al, JASA, 1997.

An optimal stopping problem

Consider a trial designed to test H_0 : $\theta \le 0$ vs $\theta > 0$, with:

Type I error rate α ,

Power $1 - \beta$ at $\theta = \delta$,

Up to K analyses.

A fixed sample test needs information

$$\mathcal{I}_{fix} = \{\Phi^{-1}(\alpha) + \Phi^{-1}(\beta)\}^2 / \delta^2.$$

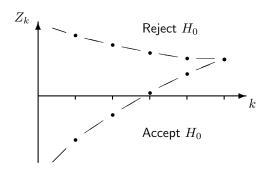
We set the maximum information to be

$$\mathcal{I}_{max} = R \mathcal{I}_{fix},$$

where R > 1, with equal increments between analyses.

Optimal group sequential tests

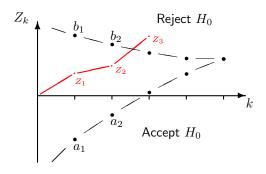
The error rates impose two constraints on the 2K-1 boundary points — leaving a high dimensional space of possible boundaries.



We shall look for a boundary that minimises

$${E_0(\mathcal{I}) + E_\delta(\mathcal{I})}/2.$$

Computations for group sequential tests



We need to be able to calculate the probabilities of basic events such as

$$a_1 < Z_1 < b_1, \ a_2 < Z_2 < b_2, \ Z_3 > b_3.$$

Combining such probabilities gives key properties, such as $Pr_{\theta}\{\text{Reject }H_0\}$ and $E_{\theta}(\mathcal{I})$.

Numerical integration

We can write probabilities as nested integrals, e.g.,

$$Pr\{a_1 < Z_1 < b_1, a_2 < Z_2 < b_2, Z_3 > b_3\} =$$

$$\int_{a_1}^{b_1} \int_{a_2}^{b_2} \int_{b_3}^{\infty} f_1(z_1) f_2(z_2|z_1) f_3(z_3|z_2) dz_3 dz_2 dz_1.$$

Applying numerical integration, we replace each integral by a sum of the form

$$\int_{a}^{b} f(z) dz = \sum_{i=1}^{n} w(i) f(z(i)),$$

where $z(1), \ldots, z(n)$ is a grid of points from a to b.

Numerical integration

Thus, we have

$$Pr\{a_1 < Z_1 < b_1, \ a_2 < Z_2 < b_2, \ Z_3 > b_3\} \approx$$

$$\sum_{i_1=1}^{n_1} \sum_{i_2=1}^{n_2} \sum_{i_3=1}^{n_3} w_1(i_1) f_1(z_1(i_1)) w_2(i_2) f_2(z_2(i_2)|z_1(i_1))$$

$$w_3(i_3) f_3(z_3(i_3)|z_2(i_2)).$$

Multiple integrations and summations will arise, e.g., for an outcome at analysis k,

$$\sum_{i_1=1}^{n_1} \dots \sum_{i_k=1}^{n_k} w_1(i_1) f_1(z_1(i_1)) w_2(i_2) f_2(z_2(i_2)|z_1(i_1))$$

...
$$w_k(i_k) f_k(z_k(i_k)|z_{k-1}(i_{k-1})).$$

Numerical integration

In the multiple summation

$$\sum_{i_1=1}^{n_1} \sum_{i_2=1}^{n_2} \dots \sum_{i_k=1}^{n_k} w_1(i_1) f_1(z_1(i_1)) w_2(i_2) f_2(z_2(i_2)|z_1(i_1))$$

$$\dots w_k(i_k) f_k(z_k(i_k)|z_{k-1}(i_{k-1})),$$

the structure of the k nested summations is such that the computation required is of the order of k-1 double summations.

Using Simpson's rule with 100 to 200 grid points per integral can give accuracy to 5 or 6 decimal places.

For details of efficient sets of grid points, see Ch. 19 of *Group Sequential Methods with Applications to Clinical Trials* by Jennison and Turnbull (2000).

Finding optimal group sequential tests

Recall, we want a group sequential test of H_0 : $\theta \le 0$ vs $\theta > 0$ with

$$Pr_{\theta=0}\{\text{Reject }H_0\}=\alpha$$
,

$$Pr_{\theta=\delta}\{\text{Accept }H_0\}=\beta$$
,

Analyses at
$$\mathcal{I}_k = (k/K) \mathcal{I}_{max}, \ k = 1, \dots, K$$
,

Minimum possible value of $\{E_0(\mathcal{I}) + E_{\delta}(\mathcal{I})\}/2$.

We deal with constraints on error rates by introducing Lagrangian multipliers to create the *unconstrained problem* of minimising

$$\{E_0(\mathcal{I})+E_\delta(\mathcal{I})\}/2+\lambda_1 Pr_{\theta=0}\{\text{Reject }H_0\}+\lambda_2\, Pr_{\theta=\delta}\{\text{Accept }H_0\}.$$

We shall find a pair of multipliers $(\lambda_1,\,\lambda_2)$ such that the solution has type I and II error rates α and β , then this design will solve the constrained problem too.

Bayesian interpretation of the Lagrangian approach

Suppose we put a prior on θ with $Pr\{\theta=0\}=Pr\{\theta=\delta\}=0.5$ and specify costs of

- 1 per unit of information observed,
- $2\lambda_1$ for rejecting H_0 when $\theta=0$,
- $2\lambda_2$ for accepting H_0 when $\theta = \delta$.

Then, the total Bayes risk is

$${E_0(\mathcal{I})+E_\delta(\mathcal{I})}/{2+\lambda_1} \frac{Pr_{\theta=0}}{Pr_{\theta=0}} {\text{Reject } H_0} + \lambda_2 \frac{Pr_{\theta=\delta}}{Pr_{\theta=\delta}} {\text{Accept } H_0},$$

just as in the Lagrangian problem.

An advantage of the Bayes interpretation is that it can give insight into solving the problem by using "Dynamic Programming" or "Backwards Induction".

Solution by Dynamic Programming

Denote the posterior distribution of θ given $Z_k=z_k$ at analysis k by

$$p^{(k)}(\theta|z_k), \quad \theta = 0, \delta.$$

At the final analysis, K

There is no further sampling cost, so compare decisions

Reject
$$H_0$$
: $E(\operatorname{Cost}) = 2 \lambda_1 p^{(K)}(0|z_K),$

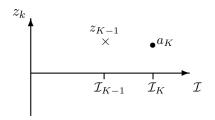
Accept
$$H_0$$
: $E(\mathsf{Cost}) = 2 \, \lambda_2 \, p^{(K)}(\delta|z_K)$.

The boundary point a_K is the value of z_K where these expected losses are equal.

The optimum decision rule is to reject H_0 for $Z_K > a_K$.

Dynamic Programming

At analysis K-1



If the trial stops at this analysis, there is no further cost of sampling and the expected additional cost is

Reject
$$H_0$$
: $2 \lambda_1 p^{(K-1)}(0|z_{K-1})$,

Accept
$$H_0$$
: $2 \lambda_2 p^{(K-1)}(\delta | z_{K-1})$.

At analysis K-1

If the trial continues to analysis K, the expected additional cost is

$$\begin{split} &1 \times (\mathcal{I}_{K} - \mathcal{I}_{K-1}) \\ &+ 2 \lambda_{1} \, p^{(K-1)}(0|z_{K-1}) \, Pr_{\theta=0} \{ Z_{K} > a_{K} | Z_{K-1} = z_{K-1} \} \\ &+ 2 \lambda_{2} \, p^{(K-1)}(\delta|z_{K-1}) \, Pr_{\theta=\delta} \{ Z_{K} < a_{K} | Z_{K-1} = z_{K-1} \}. \end{split}$$

We can now define the optimal boundary points:

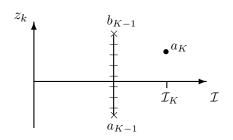
Set b_{K-1} to be the value of z_{K-1} where

 $E(\mathsf{Cost}\ \mathsf{of}\ \mathsf{continuing}) = E(\mathsf{Cost}\ \mathsf{of}\ \mathsf{stopping}\ \mathsf{to}\ \mathsf{reject}\ H_0).$

Set a_{K-1} to be the value of z_{K-1} where

 $E(\text{Cost of continuing}) = E(\text{Cost of stopping to accept } H_0).$

At analysis K-1



Before leaving analysis K-1, we set up a grid of points for use in numerical integration over the range a_{K-1} to b_{K-1} .

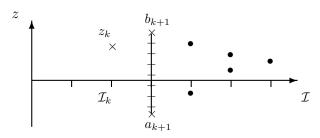
For each point, we sum over the posterior distribution of $\boldsymbol{\theta}$ to calculate

$$\beta^{(K-1)}(z_{K-1}) = E(\text{Additional cost when continuing} | Z_{K-1} = z_{K-1}).$$

We are now ready to move back to analysis K-2.

Analyses 1 to K-2

We work back through analyses k = K - 2, K - 3, ..., 1.



At each analysis, we find the optimal stopping boundary using knowledge of the optimal stopping rule at future analyses.

Then, for a grid of values of z_k , compute

$$eta^{(k)}(z_k) = E(\mathsf{Additional}\ \mathsf{cost}\ \mathsf{when}\ \mathsf{continuing}\,|\,Z_k = z_k)$$

to use in evaluating the option of continuing at analysis k-1.

Solving the original problem

For any given (λ_1, λ_2) we can find the Bayes optimal design and compute its type I and II error rates.

We now search for a pair (λ_1, λ_2) for which type I and type II error rates of the optimal design equal α and β , respectively.

The resulting design will be the optimal group sequential test, with the specified frequentist error rates, for our original problem.

Notes

- 1. The method of solving the overall problem demonstrates explicitly that good frequentist procedures should be similar to Bayes procedures.
- 2. The prior and costs in the final Bayes problem are a means to an end, rather than "true" costs of type I and type II errors, or costs of treating patients in the trial.

Properties of optimal designs

Tests with $\alpha=0.025,\ 1-\beta=0.9,\ K$ analyses, $\mathcal{I}_{max}=R\mathcal{I}_{fix}$, and equal group sizes, that minimise $\{E_0(\mathcal{I})+E_\delta(\mathcal{I})\}/2$.

Minimum values of $\{E_0(\mathcal{I})+E_\delta(\mathcal{I})\}/2$, as a percentage of \mathcal{I}_{fix}

			I	Minimum		
K	1.01	1.05	1.1	1.2	1.3	$\mathit{over}\ R$
2	80.8	74.7	73.2	73.7	75.8	73.0 at R =1.13
5	72.2	65.2	62.2	59.8	59.0	58.8 at R =1.38
10	69.2	62.2	59.0	56.3	55.1	54.2 at R =1.6
20	67.8	60.6	57.5	54.6	53.3	51.7 at R =1.8

Observe: $E(\mathcal{I}) \searrow$ as $K \nearrow$ but with diminishing returns, $E(\mathcal{I}) \searrow$ as $R \nearrow$ up to a point.

Optimisation problems we have addressed

One-sided and two-sided group sequential tests
Eales & Jennison, *Biometrika*, 1992
Eales & Jennison, *Sequential Analysis*, 1995
Barber & Jennison, *Biometrika*, 2002

Group sequential tests with data dependent group sizes

Jennison & Turnbull, *Biometrika*, 2006

Group sequential tests of superiority and non-inferiority Öhrn & Jennison, *Statistics in Medicine*, 2010

Group sequential tests for delayed responses Hampson & Jennison, *JRSS*, *B*, 2013

Optimising gain functions from financial models Robbie Peck, *University of Bath, PhD thesis*, 2020

Optimal frequentist and Bayes designs coincide

We have seen that computationally, we can find an optimal frequentist group sequential design by solving a Bayes sequential decision problem.

This demonstrates the results of Complete Class Theorems which state that

The class of admissible frequentist designs =

The class of Bayes optimal designs

See Brown, Cohen & Strawderman (Annals of Statistics, 1980).

Following a Bayes approach but calibrating the problem so the resulting procedure has specified type I and type II error probabilities should lead to the optimal frequentist group sequential design with these error probabilities that minimises the same function of expected sample size.

3. ICH E20: Adaptive Designs for Clinical Trials

The International Conference on Harmonisation (ICH) brings together statisticians from regulatory bodies and pharmaceutical companies to develop guidelines for the drug development process.

The draft ICH E20 Guideline on Adaptive Designs for Clinical Trials was published in June 2025. It lays down general principles, rather than specifying particular designs.

Examples of adaptive designs include

Group sequential tests stopping for efficacy or futility,

Adaptive trials with sample size re-assessment,

Adaptive trials testing multiple hypotheses:

Seamless Phase 2-3 trials with treatment selection,

Multi-arm multi-stage (MAMS) designs,

Enrichment designs.

ICH E20: General principles

The Guideline defines five principles.

1. Adequacy within the development program:

Justifying the selected dose, etc.

2. Adequacy of trial planning:

Pre-planned, as simple as possible, some flexibility.

3. Limiting the chances of erroneous conclusions:

Type I error control.

4. Reliability of estimation:

Estimates and confidence intervals for cost-benefit decisions.

5. Maintenance of trial integrity:

Blinding, avoiding information leakage, role of IDMCs.

Emerging topics: Inference on termination

Inference on termination

Methods are available for some, but not all, cases.

Type of design	Treatment effect estimate with negligible bias	Confidence interval, median unbiased estimate
Group sequential test (GST)	✓	✓
$GST + sample \; size \; re\text{-}assessment \; (fixed)$	✓	✓
$GST + sample \; size \; re\text{-assessment} \; (flexible)$	~ ✓	~ ✓
Phase 2/3 with treatment selection, always selecting 1 treatment for Phase 3	✓	✓
Phase 2/3 with treatment selection, selecting 1 or more treatments for Phase 3	✓	√?
Multi-arm multi-stage design (fixed)	✓	√?
Multi-arm multi-stage design (flexible)	?	?
Enrichment design (flexible)	✓	√?

Emerging topics: Inference on termination

Two common difficulties arise.

(i) Flexible designs

Since the sample space is not completely known, frequentist properties, such as the expected value of an estimate, cannot be calculated.

(ii) Confidence intervals in multiple testing problems

A confidence interval for a parameter is the result of testing a family of hypotheses concerning all possible parameter values.

A multiple testing procedure may "exhaust" the type I error probability α , leaving nothing to test non-null parameter values.

This can lead to the situation where H_0 : $\theta \leq 0$ is rejected but the upper confidence interval for θ is $(0,\infty)$ — an uninformative confidence interval

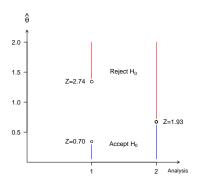
Emerging topics: Inference on termination

Point estimates

ICH E20 refers to estimates that are unbiased or have small bias.

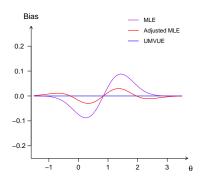
While being exactly unbiased may seem desirable, estimators that achieve this can have some strange properties.

Consider a group sequential test with two analyses.



The test of H_0 : $\theta \le 0$ against $\theta > 0$ has power 0.8 for $\theta = 1$.

The bias of several estimates:



We denote the maximum likelihood estimate (MLE) on termination by $\widehat{\theta}$.

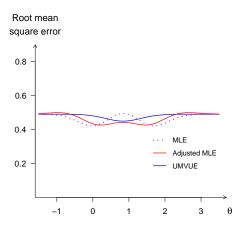
The Adjusted MLE is formed by subtracting the bias when $\theta = \widehat{\theta}$ from $\widehat{\theta}$.

(Whitehead, Bmka, 1986)

The Uniform Minimum Variance Unbiased Estimate (UMVUE) uses the fact that $\widehat{\theta}_1$, the MLE at analysis 1, is unbiased for θ .

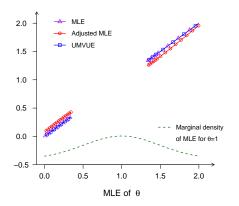
Applying "Rao-Blackwellization", the UMVUE is the conditional expectation of $\widehat{\theta}_1$, given the final data.

The root mean square error of several estimates:



The UMVUE has a higher variance than the Adjusted MLE, and this results in a higher mean square error.

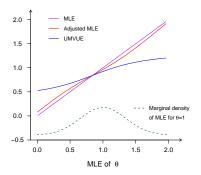
Estimates on termination at analysis 1



When stopping at analysis 1, the UMVUE is $\widehat{\theta}_1$, the MLE of θ .

So there is no "adjustment for bias" in the UMVUE!

Estimates on termination at analysis 2



When stopping at analysis 2, the UMVUE can be substantially lower than the MLE.

If the MLE is $\widehat{\theta}_2=1.5$, the UMVUE is only 1.12 — but the bias in the MLE is at most 0.09 for any value of θ .

In more complex adaptive designs, bias may arise

- (i) from selecting a treatment arm or patient sub-population based on promising early results,
- (ii) from early stopping on a "random high".

Some of the methods proposed for estimation after such trials also use Rao-Blackwellization to find UMVUE or Uniform Minimum Variance Conditionally Unbiased Estimates.

Given the behaviour of the UMVUE estimate in our simple example of a two-stage group single trial with a single parameter to estimate, we should look more closely at how these estimates may behave.

Adjusted estimates with a small bias may well be preferable.

4. Concluding remarks: Thank you, Cornell

I benefitted tremendously from the training I received as a Cornell student, many subsequent research visits, and my long and productive collaboration with Bruce Turnbull.

In welcoming students from around the world, Cornell promotes learning, instigates path-breaking research, and nurtures international collaboration.

In return, Cornell reaps the rewards of a vibrant and dynamic research community.

Today's environment is not an easy one.

I trust Cornell will ride the current wave of adversity and prosper again under a more enlightened administration.