

# Response Adaptive Randomisation within Group Sequential Tests

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# My early interest in Response Adaptive Randomisation

While a PhD student, I worked on the problem of selecting the best out of  $K$  treatments with normally distributed responses. We produced procedures with

Early stopping,

Dropping poorly performing treatment arms,

Response adaptive randomisation.

After a slow start, our paper is regularly cited now in the machine learning literature.

C. Jennison, I.M. Johnstone and B.W. Turnbull (1982)

*Asymptotically optimal procedures for sequential adaptive selection of the best of several normal means.*

In *Statistical Decision Theory and Related Topics III*, **2**, 55–86.

# Features of Phase III clinical trials

1. Comparing a new treatment against a control (the current standard of care).

2. Testing — as opposed to selection.

If  $\theta$  represents the “treatment effect”, one hopes to reject the null hypothesis  $H_0: \theta \leq 0$ , showing that the new treatment is superior to the control.

3. Strict control of the Type I error probability —  $\alpha = 0.025$  in a one-sided test.

4. Attain high power:  $1 - \beta = 0.9$ , say, if  $\theta = \delta$ .

5. Implicit asymmetry between the new treatment and control.

6. A small number of analyses in a group sequential design.

## Example of a Phase III trial

For simplicity, consider a trial with responses

$$X_{1,i} \sim N(\mu_1, \sigma^2) \quad \text{on the new treatment,}$$

$$X_{2,i} \sim N(\mu_2, \sigma^2) \quad \text{on the control.}$$

The treatment “effect” is  $\theta = \mu_1 - \mu_2$ . We shall test

$$H_0: \theta \leq 0 \text{ vs } \theta > 0$$

with type I error probability  $\alpha = 0.025$  and power  $1 - \beta = 0.9$  when  $\theta = \delta = 1$ .

In a fixed sample design with equal allocation we require information

$$\mathcal{I} = \frac{\{\Phi^{-1}(1 - \alpha) + \Phi^{-1}(1 - \beta)\}^2}{\delta^2}$$

Suppose  $\sigma^2$  is such that this requires 100 patients per treatment.

# Group sequential design

In a group sequential design, data are analysed on a small number of occasions,  $K$  say, during the trial.

Denote by  $\hat{\theta}_k$  the treatment effect estimate at analysis  $k$ .

Define

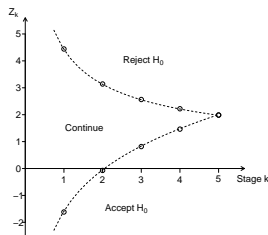
$$\mathcal{I}_{(k)} = \{\text{Var}(\hat{\theta}_k)\}^{-1},$$

calculated as if the observed sample sizes on each treatment at analysis  $k$  had been pre-specified.

A group sequential test monitors

$$Z_k = \hat{\theta}_k \sqrt{\mathcal{I}_{(k)}}$$

and can stop with an early decision to reject or accept  $H_0$ .



Pampallona & Tsiatis (*JSPI*, 1994) design,  $\Delta = 0$ .

# Response Adaptive Randomisation (RAR)

Denote information for  $\mu_1$  and  $\mu_2$  by  $\mathcal{I}_1$  and  $\mathcal{I}_2$ , respectively.

Then  $\mathcal{I}_1$  and  $\mathcal{I}_2$  are proportional to the sample sizes on the new treatment and control arms.

Consider a design that aims to minimise a loss function of the form

$$L(\theta) = \begin{cases} \mathcal{I}_1 + a^{\theta/\delta} \mathcal{I}_2 & \text{if } \theta \geq 0, \\ a^{-\theta/\delta} \mathcal{I}_1 + \mathcal{I}_2 & \text{if } \theta \leq 0, \end{cases}$$

We shall set  $a = 4$ , which implies a target

$$\mathcal{I}_1/\mathcal{I}_2 = a^{\theta/(2\delta)}$$

so we want

$$\mathcal{I}_1 = \mathcal{I}_2 \quad \text{when } \theta = 0,$$

$$\mathcal{I}_1 = \sqrt{2} \mathcal{I}_2 \quad \text{when } \theta = \delta/2,$$

$$\mathcal{I}_1 = 2 \mathcal{I}_2 \quad \text{when } \theta = \delta.$$

# Group sequential designs and RAR

It is straightforward to include RAR in a group sequential design. After each analysis, the allocation ratio for the next group can be chosen, based on the current  $\hat{\theta}$ .

Group sizes are set so that this group of observations will increase the information for  $\theta$  by the desired amount.

Jennison & Turnbull (*Seq. Analysis*, 2001) show this adaption does not change the joint distribution of the estimates  $\hat{\theta}_1, \dots, \hat{\theta}_K$ .

Thus, the original testing boundary can be applied and the design will still have Type I error probability  $\alpha$  and power  $1 - \beta$  if  $\theta = \delta$ .

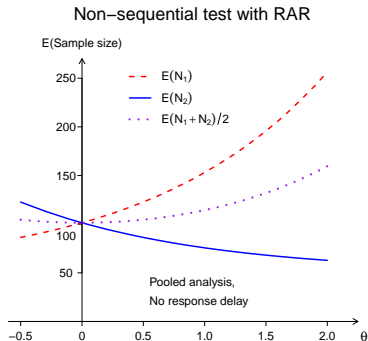
## Pooled analysis

One can estimate  $\mu_1$ ,  $\mu_2$  and  $\theta$  from data pooled across groups.

## Grouped analysis

Or, to counter the effect of a possible time trends, one can estimate  $\theta$  within each group, then combine these estimates.

# Non-sequential test and Response Adaptive Randomisation



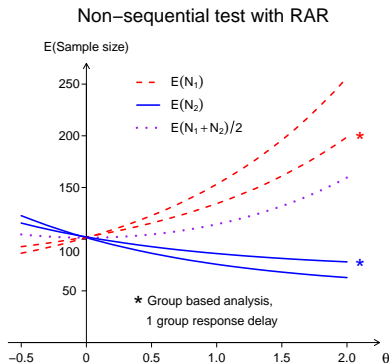
The trial is conducted in 5 stages. From stage 2 onwards, the allocation ratio in each stage is set to achieve  $\mathcal{I}_1/\mathcal{I}_2 = 4^{\hat{\theta}/(2\delta)}$ .

A non-adaptive design needs sample sizes per treatment arm  $N_1 = N_2 = 100$  to achieve the desired Type I error rate and power.

RAR reduces  $E(N_2)$  if  $\theta > 0$  and reduces  $E(N_1)$  if  $\theta < 0$ .



# Non-sequential test with RAR, group based analysis and 1 group delay in observing patient responses

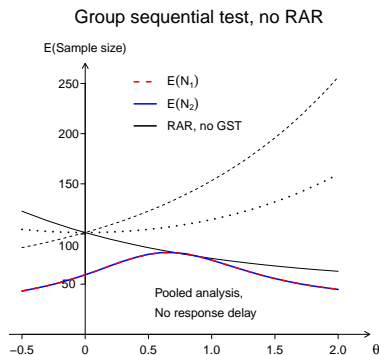


A group based analysis protects against the effects of a time trend.

With delayed response, randomisation is 1 : 1 in the first 2 groups.

RAR is still effective, but its impact is smaller.

# A Group Sequential Test (GST) with 1 : 1 allocation ratio (pooled $\hat{\theta}$ and no delay in observing responses)

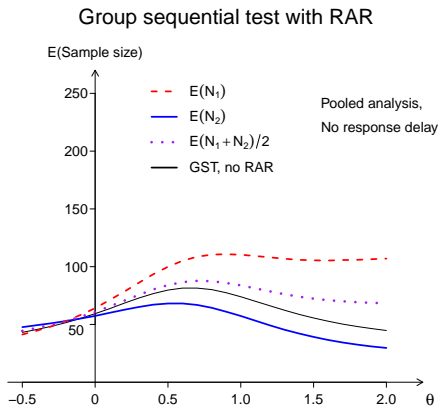


In the GST,  $N_1 = N_2$  by design.

The stopping rule reduces both  $E(N_1)$  and  $E(N_2)$ .

Impact is much greater than that of RAR in a non-sequential test.

# GST plus RAR (pooled $\hat{\theta}$ , no delay in observing responses)



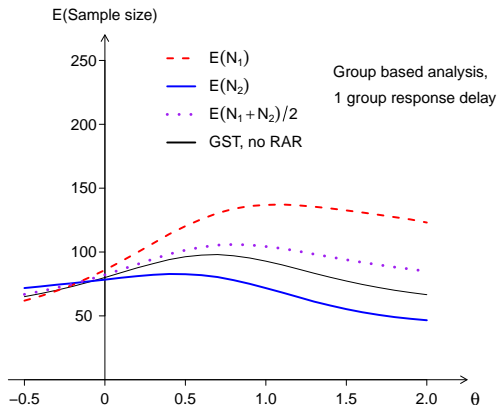
It is straightforward to combine RAR with a group sequential test.

RAR gives further reductions in  $E(N_2)$  if  $\theta > 0$ .

If  $\theta < 0$ , the GST is likely to stop early to accept  $H_0: \theta \leq 0$ .

# GST plus RAR (group based $\hat{\theta}$ , 1 group delay in responses)

## GST with RAR, 1 group response delay

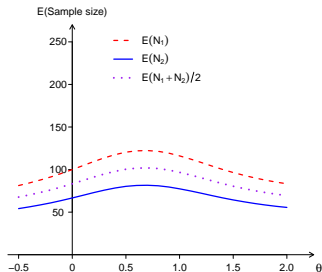


For the GST,  $E(N_1)$  and  $E(N_2)$  increase due to “pipeline data”.

Again, RAR gives further reductions in  $E(N_2)$  if  $\theta > 0$ .

# GST with 3 : 2 allocation ratio new treatment : control (group based $\hat{\theta}$ , 1 group delay in responses)

GST, 3:2 allocation ratio, 1 group response delay



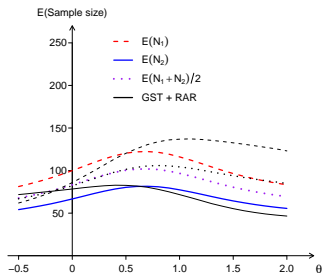
In a Phase III trial, one expects  $\theta \geq 0$ . And if  $\theta < 0$ , the GST is likely to stop early.

Interim estimates of  $\theta$  are noisy, so setting the allocation ratio to give  $\mathcal{I}_1/\mathcal{I}_2 = 4^{\hat{\theta}/(2\delta)}$  does not imply  $\mathcal{I}_1/\mathcal{I}_2 = 4^{\theta/(2\delta)}$ .

**A fixed allocation ratio has logistical advantages.**

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# Conclusions

1. Response Adaptive Randomisation can be incorporated in a group sequential design for a Phase III clinical trial.
2. A group sequential test with RAR can reduce the inferior treatment number when compared to a non-adaptive design with a 1:1 allocation ratio.
3. However, a non-adaptive group sequential test with a fixed 3:2 allocation ratio gives a similar reduction in the inferior treatment number when  $\theta > 0$  — which is all that really matters.
5. RAR may be more suited to multi-arm trials.
6. Also, RAR may be appropriate for trials of treatments for extremely rare diseases, where many of the patients with the disease are in the trial.