

Reflection groups and q -reflection groups

Yuri Bazlov

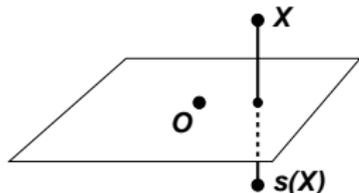
Geometry seminar

24 November 2009

Reflections $V =$ vector space over \mathbb{k} , $\dim V$ is finite.

$s \in GL(V)$ is a **(pseudo)reflection** if s is of finite order, $\text{codim } V^s = 1$.

- real reflections ($\mathbb{k} = \mathbb{R}$):



$$s \sim \text{diag}(1, 1, \dots, 1, -1)$$

$$\text{reflecting hyperplane} = \ker(\text{Id} - s)$$

- complex reflections ($\mathbb{k} = \mathbb{C}$):

$$s \sim \text{diag}(1, 1, \dots, 1, \varepsilon)$$

$$\varepsilon \neq 1 \text{ a root of } 1$$

- $\text{char } \mathbb{k} > 0$:

s may not be diagonalisable

Finite reflection groups (subgps of $GL(V)$ generated by reflections)

NB: Finiteness is a very strong condition!

*Only very special arrangements of reflecting hyperplanes
("mirrors") lead to finite reflection groups.*

Reflection groups over $\mathbb{Q} =$ **Weyl groups**
(extremely important in the theory of semisimple Lie algebras)

\cap

Real reflection groups = **Coxeter groups**

\cap

Complex reflection groups

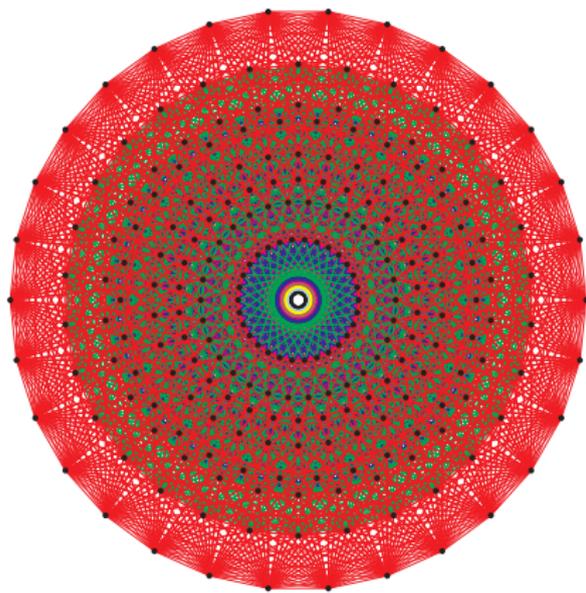
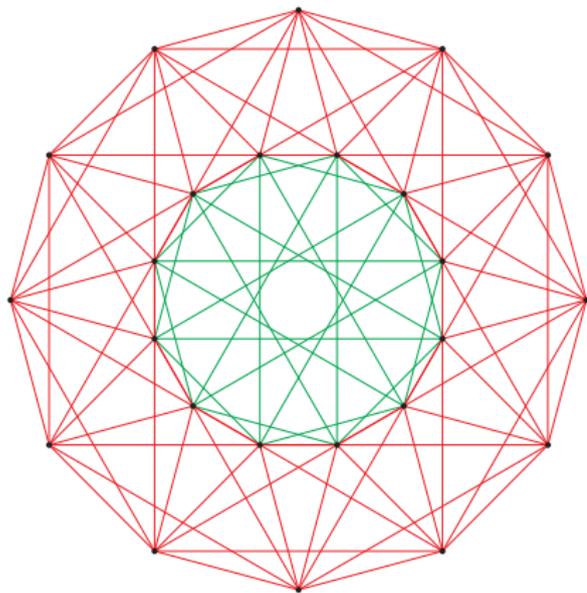
Finite reflection groups: classification over \mathbb{Q} and \mathbb{R}

A reflection group can be characterised by the set of \pm normals to mirrors (*roots*)

- For example: $\mathbb{R}^{n+1} \ni \{e_i - e_j : 1 \leq i \neq j \leq n + 1\}$
reflections $s_{ij} : e_i \leftrightarrow e_j$ generate **symmetric group** S_{n+1}
(Weyl group of type A_n , $n \geq 1$)
- Weyl group of type B_n , $n \geq 2$:
 $\mathbb{R}^n \ni \{\pm e_i \pm e_j : 1 \leq i \neq j \leq n\} \cup \{\pm e_i : 1 \leq i \leq n\}$
reflection-generators $s_{ij} : e_i \leftrightarrow e_j$, $t_i : e_i \leftrightarrow -e_i$ (hyperoctahedral group, order $2^n n!$)
- Also, D_n ($n \geq 4$), E_6 , E_7 , E_8 , F_4 , G_2 are Weyl groups
 $I_2(m)$, H_3 , H_4 are “extra” Coxeter groups

Root systems of D_4 and E_8

(planar projection of the polytope which is the convex hull of the root system)



Complex reflection groups

The Shephard – Todd classification of finite complex reflection groups (1954)

They all are direct products of the following groups:

- $G = G(m, p, n) \leq GL_n(\mathbb{C})$, $p|m$
(invertible $n \times n$ matrices with exactly n non-zero entries which are m th roots of 1, their product is an (m/p) th root of 1)
- $G =$ one of the exceptional groups G_4, \dots, G_{37} .

Notation: $S(V)^G = \{p \text{ in } S(V) : g(p) = p \quad \forall g \in G\}$

The Chevalley – Shephard – Todd theorem (1955)

Assume that $\text{char } \mathbb{k} = 0$. A finite $G < GL(V)$ is a complex reflection group, if and only if $S(V)^G$ is a polynomial algebra.

Remark on generators of $S(V)^G$

$S(V)$ is an algebra of polynomials in $n = \dim V$ variables.

If $G < GL(V)$ is a finite complex reflection group, $S(V)^G$ has n algebraically independent generators p_1, \dots, p_n .

Moreover, p_1, \dots, p_n may be chosen to be homogeneous.

p_1, \dots, p_n are not unique, but $\{d_1, \dots, d_n\} = \{\deg p_1, \dots, \deg p_n\}$ is uniquely determined by G (*degrees of G*).

One has $d_1 d_2 \dots d_n = |G|$.

Example $G = \mathbb{S}_n$ symmetric group $\leq GL_n(\mathbb{C})$

p_1, \dots, p_n are, e.g., elementary symmetric polynomials in n variables

Degrees: $d_1 = 1, d_2 = 2, \dots, d_n = n$

Generalisations of the C-S-T theorem

(1) $\text{char } \mathbb{k} > 0$.

Serre (1970s) proved that if $S(V)^G$ is polynomial, then G is a reflection group, and for any proper subspace $W \subset V$, H = the stabiliser of W has polynomial $S(W)^H$.

Kemper, Malle (1997) proved “if and only if” (using a classification of pseudoreflection groups due to Kantor, Wagner, Zaleskii, Serezhin).

(2) Replace $S(V)$ with some noncommutative algebra, on which the group G acts.

(In other words, consider a “*noncommutative space*” with an action of G .)

Below is a particular case of this:

$V = \mathbb{C}$ -span of x_1, \dots, x_n ; $\mathbf{q} = \{q_{ij}\}_{i,j=1}^n$, $q_{ii} = 1$, $q_{ij}q_{ji} = 1 \forall i, j$

$S_{\mathbf{q}}(V) = \langle x_1, \dots, x_n \mid x_i x_j = q_{ij} x_j x_i \rangle$ “the algebra of q -polynomials”

Problem 1: Find finite G such that G acts on $S_q(V)$ and $S_q(V)^G$ is also a q' -polynomial algebra.

(“ q -reflection groups”?)

B.-Berenstein, 2009:

instead of solving Problem 1, solved **a different problem** (Problem 2 below) such that:

- if $q_{ij} = 1 \forall i, j$ (the *commutative case*), the solution to **Problem 1** AND to **Problem 2** are **reflection groups**.

The semidirect product $S(V) \rtimes G$

To see what Problem 2 is about, consider the following.

Definition: The **semidirect product** $S(V) \rtimes G$ is the algebra generated by V and by the algebra $\mathbb{C}G$ subject to relations

$$g \cdot v = g(v) \cdot g \text{ for } g \in G, v \in V; \quad [v_1, v_2] = 0 \quad \forall v_1, v_2 \in V.$$

Important property: if x_1, \dots, x_n are a basis of V ,

$$\{x_1^{k_1} \dots x_n^{k_n} g \mid k_i \in \mathbb{Z}_{\geq 0}, g \in G\}$$

is a basis of $S(V) \rtimes G$.

In other words, $S(V) \rtimes G$ is $S(V) \otimes \mathbb{C}G$ as a vector space.

Drinfeld's degenerate affine Hecke algebra

Drinfeld (1985) suggested the following **deformation** of the defining relations of $S(V) \rtimes G$. Let A be the algebra generated by V and by the algebra $\mathbb{C}G$ subject to relations

$$g \cdot v = g(v) \cdot g \text{ for } g \in G, v \in V; \quad [v_1, v_2] = \sum_{g \in G} a_g(v_1, v_2)g.$$

Here $a_g: V \times V \rightarrow \mathbb{C}$ are bilinear forms.

Clearly, the above set

$$\{x_1^{k_1} \dots x_n^{k_n} g\} \tag{\dagger}$$

of monomials spans A , but it may now be linearly dependent, and A may be “strictly smaller” than $S(V) \otimes \mathbb{C}G$.

The set $\{a_g : g \in G\} \subset (V \otimes V)^*$ is called **admissible**, if the monomials (\dagger) are a basis of A .

- PBW-type basis
 - A is a flat deformation of $S(V) \rtimes G$

The following conditions are **necessary** for $\{a_g : g \in G\}$ to be admissible: for $v_i \in V$, $g \in G$,

- $[v_1, v_2] = -[v_2, v_1]$, so a_g is skew-symmetric;
- $g \cdot [v_1, v_2] = [g(v_1), g(v_2)] \cdot g$, so $a_h(v_1, v_2) = a_{ghg^{-1}}(g(v_1), g(v_2))$;
- $[[v_1, v_2], v_3] + [[v_2, v_3], v_1] + [[v_3, v_1], v_2] = 0$ (Jacobi identity), which rewrites as

$g \neq 1, a_g \neq 0 \Rightarrow \ker(a_g) = V^g$ and $\text{codim}(V^g) = 2$.
Here $V^g = \{v \in V : g(v) = v\}$.

Drinfeld claimed that the above conditions are **sufficient** for $\{a_g\}$ to be admissible. This claim is true.

Definition A , which is a flat deformation of $S(V) \rtimes G$, is called a degenerate affine Hecke algebra.

Problem 2(D): Find such A for a given $G < GL(V)$. ([Dr'85]:
 $G = S_n$ or Coxeter gp.)

History

Q. Why study flat deformations of $S(V) \rtimes G$?

A. Representation theory, geometry (orbifolds V/G), Lie theory etc.

For example:

- **Lusztig (1989)** introduced the “graded affine Hecke algebra” of a Weyl group G , a deformation of the **semidirect product** relation in $S(V) \rtimes G$.
- **Etingof, Ginzburg (2002)** introduced the **symplectic reflection algebras** which are degenerate affine Hecke algebras for G which preserves a symplectic form ω on V .

(Both were done without knowing about Drinfeld's earlier construction.)

Particular case: The split symplectic case

$G < \mathrm{GL}(V)$, the algebra to be deformed is $S(V \oplus V^*) \rtimes G$.

There is always a non-trivial deformation, **the Heisenberg-Weyl algebra** $\mathcal{A}(V)$:

$$\forall x, x' \in V^*, v, v' \in V \\ [x, x'] = 0, \quad [v, v'] = 0, \quad [v, x] = \langle v, x \rangle \cdot 1,$$

where $\langle \cdot, \cdot \rangle$ is the canonical pairing between V and V^* .

$\mathcal{A}(V)$ is the most straightforward quantisation of the phase space $V \oplus V^*$.

If $\langle \xi, x \rangle \cdot 1$ is replaced by an expression in $\mathbb{C}G$ and the deformation is still flat, one has a **rational Cherednik algebra** of G .

These are introduced and classified in [EG, Invent. Math., '02] and correspond to **complex reflection groups**.

Problem 2: Find finite G for which there is a q -analogue of the **rational Cherednik algebra** of G .

Dunkl operators

$\frac{\partial}{\partial v}$, $v \in V$, are commuting operators on $S(V^*)$.

NB: $\frac{\partial}{\partial v} p = [v, p]$ in the algebra $\mathcal{A}(V)$, where $p \in S(V^*)$.

Deformation: Replace $\mathcal{A}(V) \cong S(V \oplus V^*)$ with a rational Cherednik algebra $H_C(G) \cong S(V \oplus V^*) \otimes \mathbb{C}G$ of $G < GL(V)$:

$$\nabla_v p = \frac{\partial p}{\partial v} + \sum_s c_s \cdot \alpha_s(v) \cdot \frac{p - s(p)}{\alpha_s}, \text{ where}$$

- s runs over complex reflections in $G < GL(V)$
- c_s are scalar parameters such that $c_{gsg^{-1}} = c_s$ for all $g \in G$
- $\alpha_s \in V^*$ is the root of s : $s(v) = v - \alpha_s(v)\alpha_s^\vee$ for some $\alpha_s^\vee \in V$

These operators were first introduced by **Dunkl (1989)** for Coxeter groups (in harmonic analysis).

Dunkl operators commute

Theorem [Du,EG]: $\nabla_v(\text{polynomials}) \subseteq \text{polynomials}$,
 $\nabla_u \nabla_v = \nabla_v \nabla_u$

Proof (using rational Cherednik algebras): $H_C(G)$ acts on $S(V^*)$ via induced representation. The action of $v \in V$ is via the Dunkl operator ∇_v . But $v \in V$ commute in $H_C(G)$.

Example for $G = S_n$:

$$\nabla_i = \frac{\partial}{\partial x_i} + c \sum_{j \neq i} \frac{1}{x_i - x_j} (1 - s_{ij})$$

$\nabla_1, \dots, \nabla_n$ act on $\mathbb{C}[x_1, \dots, x_n]$ and commute.

Braided doubles

The rational Cherenik algebra is a flat deformation of

$$\mathcal{A}(V) \rtimes G \cong S(V) \otimes \mathbb{C}G \otimes S(V^*) \text{ (triangular decomposition).}$$

[EG] prove this, using the Koszul deformation principle.

[B.-Berenstein, Adv. Math. '09] introduce *braided doubles* (a more general class of algebras defined by triangular decomposition):

$$T(V)/I^- \otimes H \otimes T(W)/I^+ \text{ where } V, W \text{ are modules over a Hopf algebra } H, I^\pm \text{ are two-sided ideals, } [V, W] \subset H.$$

Example (the differential calculus on a noncommutative space):

Y is a space with a **braiding** $\Psi \in \text{End}(Y \otimes Y)$,

$$\text{i.e., } (Id \otimes \Psi)(\Psi \otimes Id)(Id \otimes \Psi) = (\Psi \otimes Id)(Id \otimes \Psi)(\Psi \otimes Id).$$

\rightsquigarrow **braided Weyl algebra** $\mathcal{A}(Y, \Psi) \cong \mathcal{B}(Y) \otimes \mathcal{B}(Y^*)$.

Here $\mathcal{B}(Y), \mathcal{B}(Y^*)$ are **Nichols algebras** which have relations that depend on Ψ .

Anticommuting Dunkl operators

Theorem [B.-Berenstein] If $D = T(V)/I^- \otimes \mathbb{k}G \otimes T(W)/I^+$ is a minimal braided double, there exist a finite-dimensional braided space (Y, Ψ) so that D embeds in $\mathcal{A}(Y, \Psi) \rtimes G$.

Thus, one may look for algebras with triangular decomposition and with given relations among certain subalgebras of braided Weyl algebras $\mathcal{A}(Y, \Psi) \rtimes G$.

For example [B.-Berenstein, *Selecta Math.* '09]:

Let $\underline{x}_1, \dots, \underline{x}_n$ be **anticommuting** variables, $\underline{x}_i \underline{x}_j = -\underline{x}_j \underline{x}_i$, $i \neq j$

Look for algebras of the form

$$\mathbb{C}\langle \underline{v}_1, \dots, \underline{v}_n \rangle \otimes \mathbb{C}G \otimes \mathbb{C}\langle \underline{x}_1, \dots, \underline{x}_n \rangle, \underline{x}_i \underline{v}_j - (-1)^{\delta_{ij}} \underline{v}_j \underline{x}_i \in \mathbb{C}G$$

Classification of “anticommutative Cherednik algebras”

Theorem 1 (Solution to Problem 2) The above algebras with triangular decomposition exist for, and only for, the following groups:

- $G = G(m, p, n)$, (m/p) even
- $G = G(m, p, n)_+$, (m/p) even, $(m/2p)$ odd

Definition For finite $G < GL(V)$, consider the character $\det: G \rightarrow \mathbb{C}^\times$ and put $\mathcal{C} = \det(G)$ (finite cyclic group). Then

$$G_+ = \{g \in G : \det(g) \in \mathcal{C}^2\}$$

(the subgroup of even elements of G).

(**NB** Either $G_+ = G$ or $|G : G_+| = 2$)

Smallest group in rank n : $G = G(2, 1, n)_+ =$ even elements in the Coxeter group of type B_n (denoted B_n^+)

Anticommuting Dunkl operators for B_n^+

$$\underline{\nabla}_i = \underline{\partial}_i + c \sum_{j \neq i} \frac{\underline{x}_i + \underline{x}_j}{\underline{x}_i^2 - \underline{x}_j^2} (1 - \sigma_{ij}) + \frac{\underline{x}_i - \underline{x}_j}{\underline{x}_i^2 - \underline{x}_j^2} (1 - \sigma_{ji}),$$

$$i = 1, \dots, n$$

- $\underline{\partial}_i$ are anticommuting skew-derivations of $\mathbb{C}\langle \underline{x}_1, \dots, \underline{x}_n \rangle$
- σ_{ij} is an automorphism of $\mathbb{C}\langle \underline{x}_1, \dots, \underline{x}_n \rangle$ of order 4,

$$\sigma_{ij}(\underline{x}_i) = \underline{x}_j, \quad \sigma_{ij}(\underline{x}_j) = -\underline{x}_i, \quad \sigma_{ij}(\underline{x}_k) = \underline{x}_k, \quad k \neq i, j.$$

- **NB** $\underline{x}_i^2 - \underline{x}_j^2$ is central in $\mathbb{C}\langle \underline{x}_1, \dots, \underline{x}_n \rangle$, division is well-defined; $\underline{x}_i^2 - \underline{x}_j^2 \neq (\underline{x}_i - \underline{x}_j)(\underline{x}_i + \underline{x}_j)$

Theorem 2 $\underline{\nabla}_i$ (skew-polynomials) \subseteq skew-polynomials,
 $\underline{\nabla}_i \underline{\nabla}_j = -\underline{\nabla}_j \underline{\nabla}_i$ for $i \neq j$

Questions • What is $\mathbb{C}\langle \underline{x}_1, \dots, \underline{x}_n \rangle^G$?

— i.e., can the above class of groups be characterised by polynomiality of the invariants?

Example $\mathbb{C}\langle \underline{x}_1, \dots, \underline{x}_n \rangle^{B_n^+}$ is *polynomial* and is generated by

- $\underline{x}_1^{2k} + \dots + \underline{x}_n^{2k}, \quad k = 1, 2, \dots, n - 1;$
- $\underline{x}_1 \underline{x}_2 \dots \underline{x}_n,$

That is, B_n^+ (not a reflection group in the usual sense) has polynomial “anticommutative invariants” and has exponents $2, 4, \dots, 2(n - 1), n$.

NB: the product of the exponents is precisely $|B_n^+|$.

Kirkman, Kuzmanovich, Zhang (2009) proved [independently of B.-B.]:

$S_q(V)^G$ is q' -polynomial, if and only if G is one of the above B.-B. groups.

(This settles the C-S-T theorem for $S_q(V)^G$ — **Problem 1** is now solved.)

- The algebra of q -commuting variables x_1, \dots, x_n (the quantum hyperplane):

if $q \neq -1$, need to consider finite-dimensional quotients of Manin's quantum group $GL_q(n, \mathbb{C})$;

“Dunkl operators” will be a deformation of the Wess-Zumino braided differential calculus.

Thank you.