Block coding: some definitions

- Performed by subdividing the message stream into a sequence of blocks each "k" bits long
- Each "k" bit data block is mapped to an "n" digit block of output digits by the encoder, where n > k

SOURCE k-bit mesage word

ENCODER n-bit codeword



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Block coding: some definitions

- *k/n* is the *code rate* (or *code efficiency*)
- 1-k/n is the code redundancy
- The encoder produces an (n,k) code, e.g. a
 (7,4) code maps 4 message bits into 7 output bits. The 7-4=3 extra digits are called parity check bits



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Block coding: some definitions

For example; (15,11) code has ...

- 15 codeword bits (=n)
- 11 message bits (=*k*)
- 4 parity check bits (=r)
- 11/15 code rate, or efficiency, <1
- 4/15 code redundancy



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Block coding: single parity

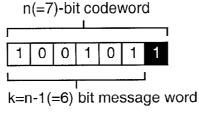
- The simplest (trivial!) example of an (n,k) block code is where n=k+1 - that is the addition of a single parity bit
- The additional bit, a parity check bit is used to detect an odd number of errors. There is no error correction capability
- In many systems it is unlikely that more than one error will occur



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Block coding: single parity

- The *even* parity scheme is most commonly used in single extra bit type encoding
- The single parity bit is the modulo-2 sum of the message bits, e.g.,





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Modulo-2 (mod-2) arithmetic

- mod-2 addition
 - $0 \oplus 0 = 0$
 - $0 \oplus 1 = 1$
 - $1 \oplus 0 = 1$
 - $1 \oplus 1 = 0$

- mod-2 multiplication
 - $0 \otimes 0 = 0$
 - $0 \otimes 1 = 0$
 - $1 \otimes 0 = 0$
 - $1 \otimes 1 = 1$
- mod-2 subtraction is mod-2 division is the the same as addition multiplication



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Block coding: single parity

- At the receiver the mod-2 sum is repeated on the whole codeword, if the resultant sum is not equal to 0, then an odd number of errors has occurred.
- Note, an even number of errors, e.g. 2 cannot be detected.



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Block coding: parity interleaving

- In many applications errors tend to occur in *bursts* of several successive digits (e.g. short term fading on radio channels)
- Multiple errors cause havoc on parity checking, so the parity bits are often *interlaced* so that the digits that are being checked are widely spaced ...

m m m c m m m c m m m c m m m c



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Block coding: parity correction

- Parity check coding can be readily extended to provide error correction
- In order to correct an error, we need to detect the error and find the location of the error. This requires two checks on the same codeword in two different positions
- The simplest system is the square array parity check (or rectangular block code) in which the k message bits are arranged in a square matrix, with a parity check for each row and column



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Block coding: parity correction

e.g. for k=9 message bits ...

010110010110101 110

110010010110001

Each complete (n=15) digit codeword is read out row by row for transmission and is re-matrixed at the receiver. A single error in the received data shows up as row and column parity errors



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Block coding: parity correction

- For multiple errors it may be possible to detect the presence of the errors without being able to locate and correction them
- No correction and detection scheme can protect against all possible combinations of errors
- There are however more effective error detection and correction techniques which we will now investigate ...



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Linear block codes

 A message block of k information bits input to the channel encoder is denoted by a k-vector, i.e. a vector k digits long;

$$M = \{m_1, m_2, m_3, \dots, m_k\}$$
 where $m_i \in \{0,1\}$

- Assuming the message is binary, there are 2^k distinct encoder input messages
- Each unique message block is mapped into a codeword of length n-bits;

$$C = \{c_1, c_2, c_3, ..., c_n\}$$
 where $n > k$



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Linear block codes

- Only 2^k of the possible 2^n codewords are used.
- This makes it possible to generate codewords selected so that a number of transmission e%r0rs must occur before one codeword is confused with another at the receiver
- The most important class of block codes are linear block codes



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Properties of linear block codes

- The parity bits are given by appropriate mod-2 sums taken from the message block
- Each of the 2^k code vectors can be expressed as a linear combination (mod-2 sum) of k linearly independent code vectors
 e.g. if

 C_x = 1 0 0 0 1 1, and C_y =0 1 0 1 0 1 are code vectors so is C_z = $C_x \oplus C_y$

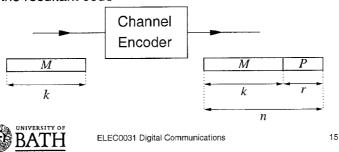
 The all-zero vector is a code vector corresponding to the all-zero message vector



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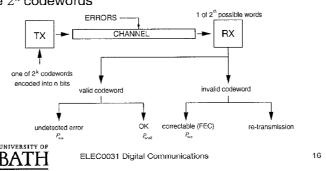
Properties of linear block codes

- Codes in which the message bits appear at the beginning of the codeword are called *systematic* linear block codes
- This constraint does not restrict the performance of the resultant code



Decoding linear block codes

- The decoder is presented with a word of n bits which has been corrupted by errors
- The decoded word is therefore not necessarily one of the 2^k codewords



Hamming Distance & Hamming Weight

A typical block code: (n,k)=(6,3)

| Message | Codeword | |
|---------|----------|-------------------|
| 000 | 000 000 | |
| 001 | 001 110 | |
| 010 | 010 101 | |
| 011 | 011 011 | Code rate $R=3/6$ |
| 100 | 100 011 | |
| 101 | 101 101 | |
| 110 | 110 110 | |
| 111 | 111 000 | |
| | | |



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Hamming Distance & Hamming Weight

- Since n=6 there are $2^6=64$ possible codewords, of which only $8(2^k=2^3=8)$ have been used
- Each codeword has been chosen so that it differs from any other in at least 3 positions.
- Hence 3 transmission errors can transform one codeword into another ...
- However, 1 or 2 errors can be detected ...
- A single error can be corrected (as the received codeword will be closest to the true codeword)



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Hamming Distance & Hamming Weight

- The number of differences between two adjacent codewords is an important parameter and is called the *Hamming distance*
- The minimum Hamming distance is called the minimum distance
- The *Hamming weight* of a codeword *C* is defined as the number of "1"s in *C*
- The minimum distance of a linear block code is equal to the minimum weight of any non-zero codeword



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Hamming Distance & Hamming Weight

- A linear block code with minimum distance d_{\min} can correct up to

$$\left| \frac{d_{\min} - 1}{2} \right|$$

errors.

 For single error correction then d_{min}=3, and the n-k=r check or parity bits have to indicate in which position of the codeword the error has occurred



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