

Directed Atomic λ -Calculus

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08/03/2018

Swansea University Theory Tea
Theori Te Prifysgol Abertawe

1 Why

- Efficient reduction of λ -terms
- Atomic λ -calculus
- Director Strings

2 What

- The directed atomic λ -calculus

3 How

- Prerequisites
- Permutation Equivalence
- Beta Rule
- Atomic Duplication
- Translations

Before we begin...

Sharing

Use of a single representation for multiple instances of some subterm

Duplication

Extraction of an object from a sharing to its context within some term

$$t[x_1, x_2 \leftarrow s] \rightsquigarrow t\{s/x_1\}\{s/x_2\}$$

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Lazy Evaluation

$$(\lambda x.t)s \rightsquigarrow_{\beta} t\{s/x\}$$

- Delays evaluation of terms until a value is required
- Avoids duplication of work (does not repeat the same evaluation)

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- Avoids duplication of work (does not repeat the same evaluation)

NOT TRUE FOR FUNCTIONAL COMPILERS

$$(\lambda f.fl(fl))(\lambda w.(ll)w)$$

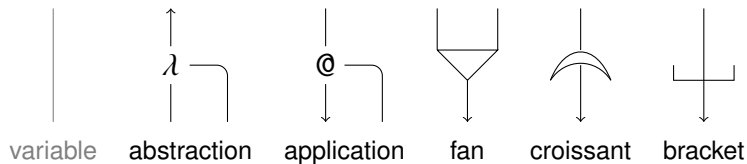
$$l = \lambda x.x$$

Optimal Reduction

To avoid useless repetition of work in the reduction of terms

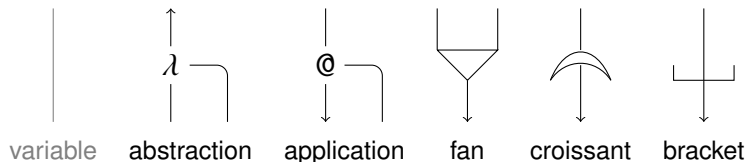
- Concept of optimality formally introduced by Lévy (1970)
- Lamping defined an evaluator satisfying optimality requirements (1989/90) called *Sharing Graphs*
- Algorithm based on *Atomic Duplication*

Sharing graph operators



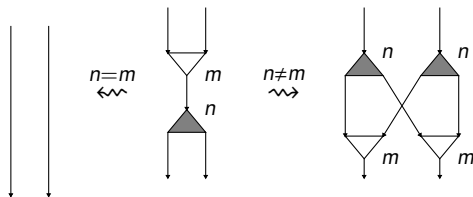
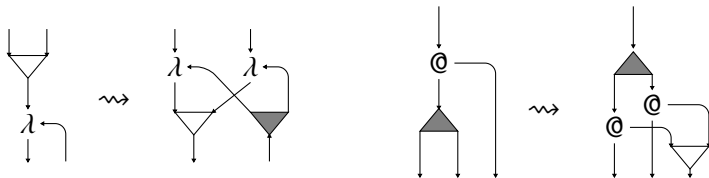
- Each operator has a *principle port*

Sharing graph operators



- Each operator has a *principle port*
- Each operator has an index $i \in \mathbb{N}$ associated with it
- The index indicates the 'level' of a term
e.g. $s^0(t^1u^2)$

Sharing Graphs: Some Duplication



As an evaluator, the work of maintaining the nodes outweighs the value of optimal reduction/sharing graphs

The atomic λ -calculus is the first use of atomic duplication in a term calculus

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The atomic λ -calculus - Deep Inference

$$\begin{array}{c} A \\ \Downarrow \\ C \end{array} := A \mid \begin{array}{c} A_1 \\ \Downarrow \\ C_1 \end{array} \wedge \begin{array}{c} A_2 \\ \Downarrow \\ C_2 \end{array} \mid \begin{array}{c} A_1 \\ \Uparrow \\ C_1 \end{array} \rightarrow \begin{array}{c} A_2 \\ \Downarrow \\ C_2 \end{array} \mid \begin{array}{c} A \\ \Downarrow \\ B_1 \\ \hline B_2 \\ \Downarrow \\ C \end{array} r$$

$$\frac{B}{A \rightarrow (A \wedge B)} \lambda \quad \frac{A \wedge (A \rightarrow B)}{B} @ \quad \frac{A}{A \wedge \dots \wedge A} \Delta$$

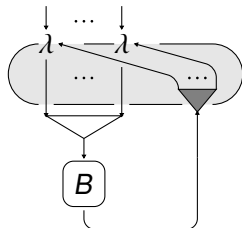
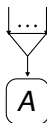
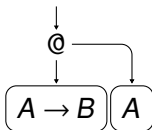
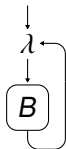
Guglielmi, Gundersen, and Parigot. *A proof calculus which reduces syntactic bureaucracy*. (2010): 135-150.

$$\frac{A \rightarrow (B \wedge C)}{(A \rightarrow B) \wedge (A \rightarrow C)} \quad d$$

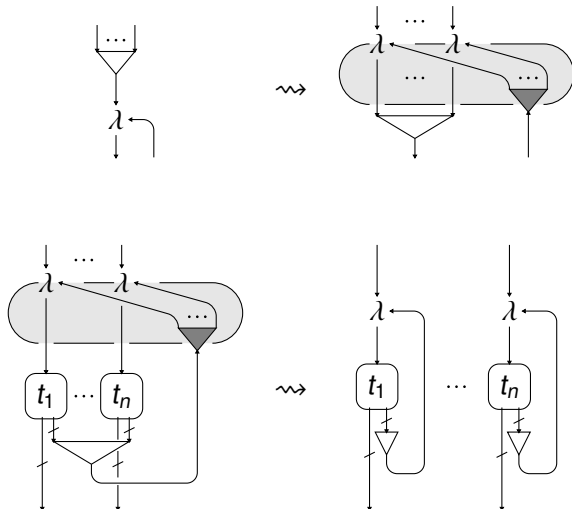
- A typed term calculus with explicit sharing
- Atomic duplication (on individual constructors)
- Achieves fully lazy sharing

Graphical Intuition

$$\frac{B}{A \rightarrow (A \wedge B)} \lambda \quad \frac{A \wedge (A \rightarrow B)}{B} @ \quad \frac{A}{A \wedge \dots \wedge A} \Delta \quad \frac{A \rightarrow \frac{B}{(B \wedge \dots \wedge B)} \Delta}{(A \rightarrow B) \wedge (A \rightarrow B)} d$$



Differences to Sharing Graphs - Duplication of Abstraction



Duplication of Abstraction - Proof Transformations

$$\frac{
 \frac{
 \frac{B}{A \wedge B} \lambda
 }{A \rightarrow C} \Delta
 }{
 (A \rightarrow C) \wedge (A \rightarrow C)
 } \Delta
 \quad \rightsquigarrow \quad
 \frac{
 \frac{
 \frac{B}{A \wedge B} \lambda
 }{C} \Delta
 }{
 (A \rightarrow C) \wedge (A \rightarrow C)
 } d
 }{
 (A \rightarrow C) \wedge (A \rightarrow C)
 } d$$

$$\frac{
 \frac{
 \frac{A}{A \wedge A} \Delta
 }{A \rightarrow C} \Delta
 }{
 (A \rightarrow C) \wedge (A \rightarrow C)
 } d
 \quad \rightsquigarrow \quad
 \frac{
 \frac{A}{A} \lambda
 }{A \rightarrow C} \Delta
 \wedge
 \frac{
 \frac{A}{A} \lambda
 }{A \rightarrow C} \Delta
 }{
 (A \rightarrow C) \wedge (A \rightarrow C)
 } d$$

The atomic λ -calculus: Term Calculus

An atomic lambda term is given by the mutually recursive grammar

$$t ::= x \mid \lambda x.t \mid (t)t \mid t[x_1, \dots, x_n \leftarrow t] \mid t[x_1, \dots, x_n \leftarrow \lambda y.t^n]$$

$$t^n ::= \langle t_1, \dots, t_n \rangle \mid t^n[x_1, \dots, x_n \leftarrow t] \mid t^n[x_1, \dots, x_m \leftarrow \lambda y.t^m]$$

- Linear calculus - each variable occurs exactly once
- Variables bound by an abstraction/sharing/distributor must occur

Atomic λ -calculus: Fully Lazy Sharing

$$u[z_1, z_2 \leftarrow \lambda x. t[\leftarrow x]]$$

$$\rightsquigarrow u[z_1, z_2 \leftarrow \lambda x. \langle y_1, y_2 \rangle [y_1, y_2 \leftarrow t[\leftarrow x]]]$$

$$\rightsquigarrow u[z_1, z_2 \leftarrow \lambda x. \langle y_1, y_2 \rangle [y_1, y_2 \leftarrow t][\leftarrow x]]$$

$$\rightsquigarrow u[z_1, z_2 \leftarrow \lambda x. \langle y_1, y_2 \rangle [\leftarrow x]][y_1, y_2 \leftarrow t]$$

$$\rightsquigarrow u\{\lambda x_1. y_1[\leftarrow x_1]/z_1\}\{\lambda x_2. y_2[\leftarrow x_2]/z_2\}[y_1, y_2 \leftarrow t]$$

$\lambda x.t[\vec{y} \leftarrow s] \rightsquigarrow (\lambda x.t)[\vec{y} \leftarrow s]$
only if $x \notin \text{fv}(s)$

- Variable lookup operations are expensive
- A potential abstract machine would need to perform these checks, destroying the value of *full laziness*

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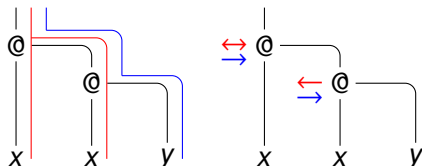
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Director Strings: Local Reduction

$$(x)(xy)\{X/x\}\{Y/y\}$$


Director Strings: Why?

- Director strings provide the ideal information to perform an optimal performance of substitution.
- Many abstract machines have been designed using director strings. Director strings seem like a natural choice to use to help develop a computationally-efficient evaluation for functional programs.
- Efficient reduction strategies involving director strings have already been studied. These strategies are considered efficient in the sense of the number of rewrite steps (not just β -steps).

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The directed atomic λ -calculus

$\Lambda_a^{\mathcal{D}}$: A calculus with local reduction rules that performs fully-lazy reduction

- Typed
- Strongly Normalizing
- Confluent

The directed atomic λ -calculus

$$\langle - \rangle : \Lambda_a^{\mathcal{D}} \rightarrow \Lambda_a$$

$$\llbracket - \rrbracket : \Lambda_a \rightarrow \Lambda_a^{\mathcal{D}}$$

Theorem

Given $\Lambda_a^{\mathcal{D}}$ -terms t and s , if $t \rightsquigarrow s$ then there is a reduction rule in Λ_a such that $\langle t \rangle \rightsquigarrow \langle s \rangle$.

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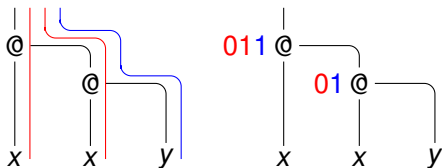
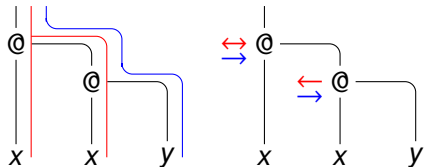
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Linear Director Strings

$$t[x \rightarrow s] \rightsquigarrow t\{s/x\}$$



$$\alpha, \gamma ::= (0|1)^*$$

Invert

$$\bar{\alpha} = \alpha \text{ inverted}$$

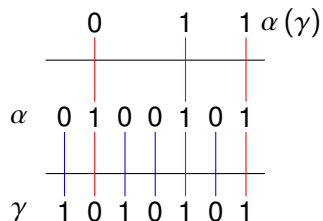
e.g. $\overline{10100} = 01011$

String Operations

Mask

$$\begin{aligned}0 \cdot \alpha(z \cdot \gamma) &= \alpha(\gamma) \\1 \cdot \alpha(z \cdot \gamma) &= z \cdot \alpha(\gamma)\end{aligned}$$

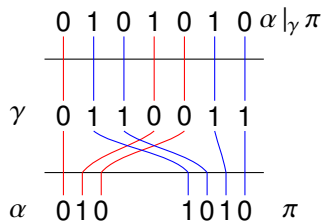
α	=	0	1	0	0	1	0	1
γ	=	1	0	1	0	1	0	1
<hr/>								
$\alpha(\gamma)$	=		0			1		1
$\bar{\alpha}(\gamma)$	=	1		1	0		0	



Interleaving

$$\begin{aligned} (Z \cdot \alpha) |_{0,\gamma} \pi &= Z \cdot (\alpha |_{\gamma} \pi) \\ \alpha |_{1,\gamma} (Z \cdot \pi) &= Z \cdot (\alpha |_{\gamma} \pi) \end{aligned}$$

$$\begin{array}{rcl} \alpha & = & 0 \qquad \qquad \qquad 1 \ 0 \\ \pi & = & \qquad 1 \ 0 \qquad \qquad \qquad 1 \ 0 \\ \gamma & = & 0 \ 1 \ 1 \ 0 \ 0 \ 1 \ 1 \\ \hline \alpha |_{\gamma} \pi & = & 0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \end{array}$$



Merge₁

$$\begin{aligned}(0 \cdot \alpha) \wr_1 (0 \cdot \gamma) &= 0 \cdot (\alpha \wr_1 \gamma) \\ (1 \cdot \alpha) \wr_1 \gamma &= 0 \cdot (\alpha \wr_1 \gamma) \\ \alpha \wr_1 (1 \cdot \gamma) &= 1 \cdot (\alpha \wr_1 \gamma) \quad \text{if } \alpha = 0 \cdot \alpha' \text{ or } |\alpha| = 0\end{aligned}$$

Merge₂

$$\begin{aligned}(0 \cdot \alpha) \wr_2 (0 \cdot \gamma) &= 0 \cdot (\alpha \wr_2 \gamma) \\ (1 \cdot \alpha) \wr_2 \gamma &= 1 \cdot (\alpha \wr_2 \gamma) \\ \alpha \wr_2 (1 \cdot \gamma) &= 0 \cdot (\alpha \wr_2 \gamma) \quad \text{if } \alpha = 0 \cdot \alpha' \text{ or } |\alpha| = 0\end{aligned}$$

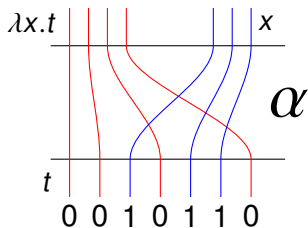
String Operation

$$\begin{array}{rcccccccc} \alpha & = & 0 & 1 & 1 & & 0 & 1 & & & 0 \\ \gamma & = & 0 & & & & 1 & 0 & & 1 & 1 & 0 & 1 \\ \hline \alpha \lambda_1 \gamma & = & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 & 0 & 1 \\ \alpha \lambda_2 \gamma & = & 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \end{array}$$

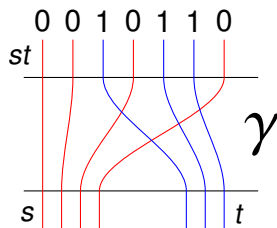
$$\begin{array}{ccc} 0\mathbf{1}\mathbf{1}0\mathbf{1}0 & \lambda_1 & 0\mathbf{1}0\mathbf{1}\mathbf{1}0\mathbf{1} & = & 0\mathbf{0}0\mathbf{1}0\mathbf{0}\mathbf{1}\mathbf{1}0\mathbf{1} \\ \begin{array}{c} | \\ | \\ | \\ | \\ | \end{array} & & \begin{array}{c} | \\ | \\ | \\ | \\ | \end{array} & & \begin{array}{c} | \\ | \\ | \\ | \\ | \end{array} \\ 0\mathbf{1}\mathbf{1}0\mathbf{1}0 & \lambda_2 & 0\mathbf{1}0\mathbf{1}\mathbf{1}0\mathbf{1} & = & 0\mathbf{1}\mathbf{1}0\mathbf{0}\mathbf{1}0\mathbf{0}0\mathbf{0} \\ \begin{array}{c} | \\ | \\ | \\ | \\ | \end{array} & & \begin{array}{c} | \\ | \\ | \\ | \\ | \end{array} & & \begin{array}{c} | \\ | \\ | \\ | \\ | \end{array} \end{array}$$

Director Strings in Terms

$\lambda^\alpha.t$



$s^\gamma t$



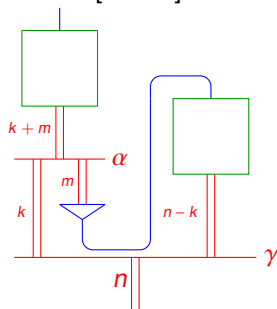
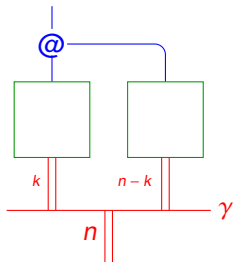
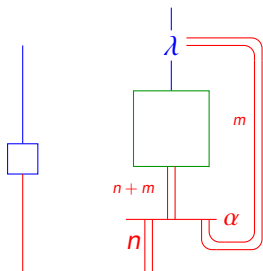
Director Strings in Terms

□

$\lambda^\alpha.t$

$s^\gamma t$

$s[\alpha \leftarrow t]^\gamma$



Directed Well-Formed Terms

Λ -term

$\lambda x.x$

$\lambda x.\lambda y.x$

$\lambda x.\lambda y.\lambda z.(xz)(yz)$

$\Lambda_a^{\mathcal{D}^-}$ -term

$\lambda^1 \square$

$\lambda^1 \lambda^0 \square$

$\lambda^1 \lambda^{01} \lambda^{0011} (\square^{01} \square)^{0101} (\square^{01} \square)$

Term

\square

$\lambda^\alpha t_{n+m}$

$t_k^\gamma t_{n-k}$

$t_{k+m}[\alpha \leftarrow t_{n-k}]^\gamma$

Constraints

$n = 1$

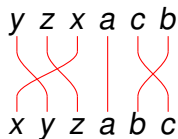
$|\alpha| = n + m, |\alpha|_1 = m$

$|\gamma| = n, |\gamma|_0 = k$

$|\gamma|_0 = |\alpha|_0 = k, |\alpha|_1 = m$

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Permutation Equivalence

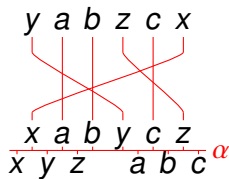
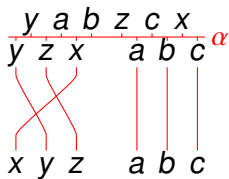
 $\lambda^{01} \square^{01} \square$ $\lambda^{10} \square^{10} \square$ 

$$\begin{pmatrix} y & z & x & a & c & b \\ x & y & z & a & b & c \end{pmatrix}$$

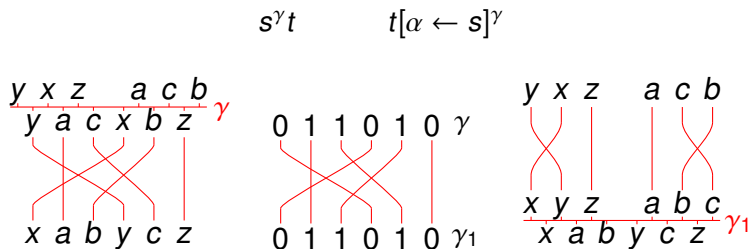
Permutation Equivalence: Permuting

$\lambda^\alpha.t$

$t[\alpha \leftarrow s]^\gamma$



Permutation Equivalence: Permuting



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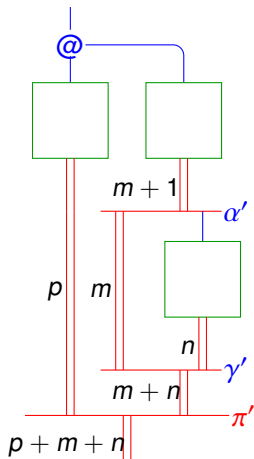
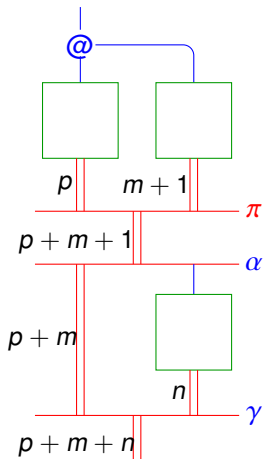
Substitution

$$\begin{aligned} t\{s/\alpha\}^\gamma & \quad |\alpha|_1 = 1 \\ (s^\pi t)\{u/\alpha\}^\gamma & \rightsquigarrow s^{\pi'} t\{u/\alpha'\}^{\gamma'} & \quad \alpha(\pi) = 1 \end{aligned}$$

Substitution

$$t\{s/\alpha\}^\gamma \quad |\alpha|_1 = 1$$

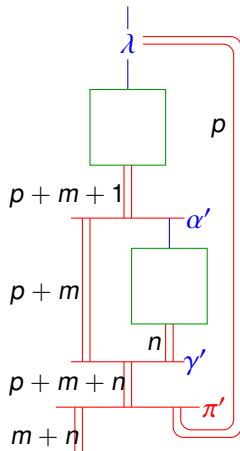
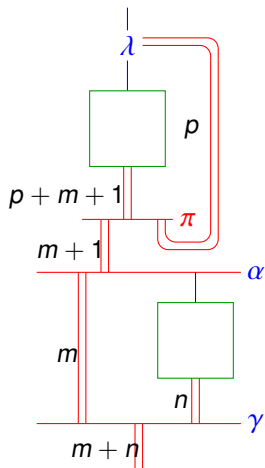
$$(s^\pi t)\{u/\alpha\}^\gamma \rightsquigarrow s^{\pi'} t\{u/\alpha'\}^{\gamma'} \quad \alpha(\pi) = 1$$



$$\begin{array}{l} \pi' \quad \bar{\alpha}(\pi) \upharpoonright_\gamma \bar{1} \\ \alpha' \quad \pi(\alpha) \\ \gamma' \quad \pi'(\gamma) \end{array}$$

Substitution

$$(\lambda^\pi t)\{u/\alpha\}^\gamma \rightsquigarrow \lambda^{\pi'} t\{u/\alpha'\}^{\gamma'}$$



$$\begin{array}{l} \pi' \quad \overline{\alpha'}(\pi) \wr_2 \gamma \\ \alpha' \quad \alpha|_{\pi} \vec{0} \\ \gamma' \quad \overline{\alpha'}(\pi) \wr_1 \gamma \end{array}$$

$$(\lambda^\alpha.t)^\gamma s \rightsquigarrow_\beta t[\alpha \leftarrow s]^\gamma$$

$$t[\alpha \leftarrow s]^\gamma \rightsquigarrow t\{s/\alpha\}^\gamma \quad |\alpha|_1 = 1$$

$$t[\pi \leftarrow s]^\sigma [\alpha \leftarrow u]^\gamma \sim t[\alpha' \leftarrow u]^{\gamma'} [\pi' \leftarrow s]^{\sigma'} \quad \text{if } |\alpha(\sigma)|_1 = 0$$

$$(\lambda^\alpha.t)^\gamma s \rightsquigarrow_\beta t[\alpha \leftarrow s]^\gamma$$

$$t[\alpha \leftarrow s]^\gamma \rightsquigarrow t\{s/\alpha\}^\gamma \quad |\alpha|_1 = 1$$

$$t[\pi \leftarrow s]^\sigma [\alpha \leftarrow u]^\gamma \sim t[\alpha' \leftarrow u]^{\gamma'} [\pi' \leftarrow s]^{\sigma'} \quad \text{if } |\alpha(\sigma)|_1 = 0$$

$$\begin{aligned} & t[001100 \leftarrow s]^{10000} [01100 \leftarrow u]^{0010} \\ \stackrel{\alpha \leftarrow \rightsquigarrow}{=} & ((\lambda^{001100} t)^{10000} s) [01100 \leftarrow u]^{0100} \\ = & ((\lambda^{001100} t) [1100 \leftarrow u]^{010})^{1000} s \\ = & (\lambda^{11000} (t[110000 \leftarrow u]^{00010}))^{1000} s \\ \rightsquigarrow_\beta & t[110000 \leftarrow u]^{00010} [11000 \leftarrow s]^{1000} \end{aligned}$$

Preservation of well-formedness

Let t_n be a well-formed term with n occurrences of free variables. If term s_m can be obtained from t_n , $t_n \rightsquigarrow^* s_m$, by following the beta rule and substitution, then s_m is also a well-formed term. Furthermore, $n = m$.

Preservation of well-formedness: Proof

Case: Abstraction $(\lambda^\pi t)\{u/\alpha\}^\gamma = \lambda^{\pi'} t\{u/\alpha'\}^{\gamma'}$ where $|\vec{0}| = |\pi|_1$

$$\pi' = \overline{\alpha |_\pi \vec{0}}(\pi) \wr_2 \gamma$$

$$\alpha' = \overline{\alpha |_\pi \vec{0}}$$

$$\gamma' = \overline{\alpha |_\pi \vec{0}}(\pi) \wr_1 \gamma$$

The rule preserves well-formedness if

$$|\gamma| = |\pi'|_0$$

$$|\gamma'| = |\pi'|$$

$$|\gamma'|_0 = |\alpha'|_0$$

$$|\pi|_1 = |\pi'|_1$$

$$|\gamma|_1 = |\gamma'|_1$$

$$|\pi| = |\alpha'|$$

$$|\alpha|_1 = |\alpha'|_1 = 1$$

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$$\lambda^\pi t[\alpha \leftarrow u]^\gamma \rightsquigarrow_S (\lambda^{\pi'} t)[\alpha' \leftarrow u]^{\gamma'}$$

$$(s[\alpha \leftarrow u]^\gamma)^\pi t \rightsquigarrow_S (s^{\gamma'_1 \pi'} t)[\alpha' \leftarrow u]^{\gamma'}$$

$$s^\pi t[\alpha \leftarrow u]^\gamma \rightsquigarrow_S (s^{\pi'} t)[\alpha' \leftarrow u]^{\gamma'}$$

$$s[\alpha_2 \leftarrow t[\alpha \leftarrow u]^\gamma]^\pi \rightsquigarrow_S s[\alpha_2 \leftarrow t]^\pi [\alpha' \leftarrow u]^{\gamma'}$$

$$t[\alpha_2 \leftarrow \lambda^\sigma . d[\alpha \leftarrow u]^\gamma]^\pi \rightsquigarrow_S t[\alpha_2 \leftarrow \lambda^{\sigma'} . d]^\pi [\alpha' \leftarrow u]^{\gamma'}$$

$$t[\alpha \leftarrow \square]^\gamma [\alpha_1 \leftarrow u]^{\gamma_1} \rightsquigarrow_S t[\alpha' \leftarrow u]^{\gamma'}$$

Atomic Duplication: Application

$$u[\vec{x} \leftarrow st] \rightsquigarrow_S u\{y_i z_i / x_i\}_{\forall i. x_i \in \vec{x}} [\vec{y} \leftarrow s][\vec{z} \leftarrow t]$$

$$u[\alpha \leftarrow s^{\gamma_1} t]^\gamma \rightsquigarrow_S u\{\square^{01} \square / \alpha^1\}^{\gamma^1} \dots \{\square^{01} \square / \alpha^n\}^{\gamma^n} [\alpha'_1 \leftarrow s]^{\gamma'_1} [\alpha'_2 \leftarrow t]^{\gamma'_2}$$

Atomic Duplication: Application

$$u[\alpha \leftarrow s^{\gamma_1} t]^{\gamma} \rightsquigarrow_S u\{\square^{01}\square/\alpha^1\}^{\gamma^1} \dots \{\square^{01}\square/\alpha^n\}^{\gamma^n} [\alpha'_1 \leftarrow s]^{\gamma'_1} [\alpha'_2 \leftarrow t]^{\gamma'_2}$$
$$u\{\square^{01}\square/\alpha^1\}^{\gamma^1} \dots \{\square^{01}\square/\alpha^n\}^{\gamma^n}$$

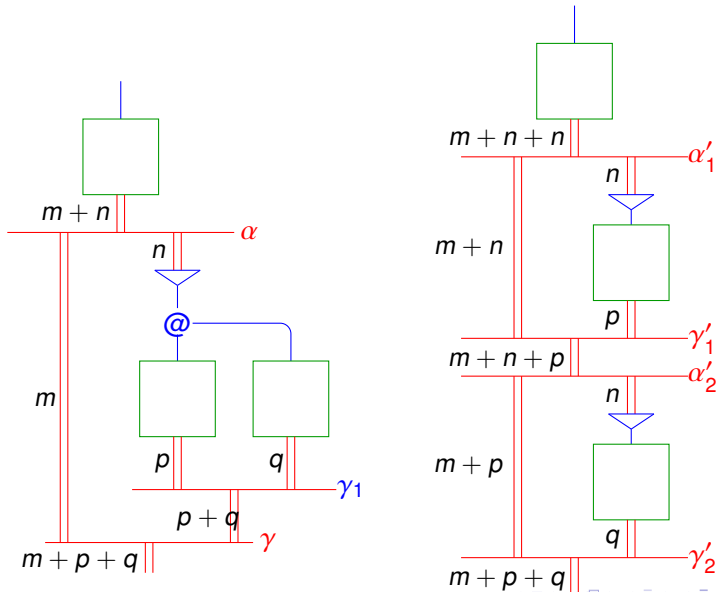
Atomic Duplication: Application

$$u[\alpha \leftarrow s^{\gamma_1} t]^\gamma \rightsquigarrow_S u\{\square^{01}\square/\alpha^1\}^{\gamma^1} \dots \{\square^{01}\square/\alpha^n\}^{\gamma^n} [\alpha'_1 \leftarrow s]^{\gamma'_1} [\alpha'_2 \leftarrow t]^{\gamma'_2}$$

$$u\{\square^{01}\square/\alpha^1\}^{\gamma^1} \dots \{\square^{01}\square/\alpha^n\}^{\gamma^n}$$

α	0	1	0	1	1	0						
α^1	0	1	0	0	0	0						
γ^1	0	.	0	0	0	0	1	1				
α^2	0	.	0	1	0	0	0	0				
γ^2	0	.	0	.	0	0	0	0	1	1		
α^3	0	.	0	.	1	0	0	0	0	0		
γ^3	0	.	0	.	.	0	0	0	0	0	1	1

Atomic Duplication: Application



Atomic Duplication: Application

$$u[\alpha \leftarrow s^{\gamma_1} t]^{\gamma} \rightsquigarrow_S u\{\square^{01} \square / \alpha^1\}^{\gamma^1} \dots \{\square^{01} \square / \alpha^n\}^{\gamma^n} [\alpha'_1 \leftarrow s]^{\gamma'_1} [\alpha'_2 \leftarrow t]^{\gamma'_2}$$

$$\alpha'_1 = \vec{0} \cdot \vec{1\vec{0}} \text{ where } |\vec{0}| = |\alpha|_0, |\vec{1\vec{0}}| = 2|\alpha|_1$$

$$\gamma'_1 = (\vec{1} |_{\gamma} \overline{\gamma_1})(\gamma) \cdot \vec{0} \text{ where } |\vec{0}| = |\alpha|_1$$

$$\alpha'_2 = \vec{0} \cdot \vec{1} \text{ where } |\vec{0}| = |\gamma_1|_0 + |\alpha|_0 \text{ and } |\vec{1}| = |\alpha|_1$$

$$\gamma'_2 = \vec{0} |_{\gamma} \gamma_1$$

Atomic Duplication: Distributor

$$u[\vec{x} \leftarrow \lambda y.t] \llcorner_S u[\vec{x} \leftarrow \lambda y.\langle \vec{z} \rangle[\vec{z} \leftarrow t]]$$

$$u[\alpha \leftarrow \lambda^{\alpha_1} t]^\gamma \rightsquigarrow_S u[\alpha \leftarrow \lambda^{\alpha_1}.d[\vec{m} \leftarrow t]^{\vec{1}}]^\gamma$$

$$|\vec{1}| = |\alpha_1|$$

$$|\vec{m}| = |\vec{m}|_1 = |\alpha_1|_1$$

$$d = \langle \square, \langle \dots \rangle^\gamma \rangle^{0 \cdot \vec{1}} \text{ where } |0 \cdot \vec{1}| = |\vec{m}|$$

Atomic Duplication: Distributor

$$u[\vec{x} \leftarrow \lambda y. \langle \vec{t} \rangle [\vec{z} \leftarrow y]] \rightsquigarrow_S u\{\lambda y_i. t[\vec{a} \leftarrow y_i] / x_i\}_{1 \geq i \geq |\vec{x}|}$$

where $\vec{a} = \vec{z} \cap \text{fv}(t_i)$

$$u[\alpha_1 \leftarrow \lambda^{\alpha_2}. \langle t, \langle \dots \rangle^{\alpha'_3} \rangle^{\alpha_3} [\alpha_4 \leftarrow \square]^{\gamma_1}]^{\gamma_2} \rightsquigarrow_S$$

$$u\{\lambda^{\alpha'_2} t[\alpha'_4 \leftarrow \square]^{\gamma'_1} / \alpha'_1\}^{\gamma'_2} [\alpha''_1 \leftarrow \lambda^{\alpha''_2} \langle \dots \rangle^{\alpha'_3} [\alpha''_4 \leftarrow \square]^{\gamma''_1}]^{\gamma''_2}$$

$$\begin{aligned} \alpha'_4 &= \overline{\alpha_3}(\alpha_4) \\ \alpha'_2 = \gamma'_1 &= \vec{0} \cdot 1 \text{ where } |\vec{0}| = |\alpha'_4|_0 \\ \text{let } \pi &= \vec{1} \upharpoonright_{\gamma_2} \overline{\alpha_4}(\overline{\alpha_3}) \\ \gamma'_2 &= \pi(\gamma_2) \wr_2 \overline{\alpha_1}(\alpha_1) \\ \alpha''_1 &= \pi(\gamma_2) \wr_1 \alpha'_1(\alpha_1) \\ \alpha''_4 &= \alpha_3(\alpha_4) \\ \alpha''_2 = \gamma''_1 &= \vec{0} \cdot 1 \text{ where } |\vec{0}| = |\alpha_3(\alpha_4)|_0 \\ \gamma''_2 &= \vec{0} \upharpoonright_{\gamma_2} \overline{\alpha_4}(\alpha_3) \text{ where } |\vec{0}| = |\gamma_2|_0 \end{aligned}$$

1 Why

- Efficient reduction of λ -terms
- Atomic λ -calculus
- Director Strings

2 What

- The directed atomic λ -calculus

3 How

- Prerequisites
- Permutation Equivalence
- Beta Rule
- Atomic Duplication
- **Translations**

Translation into linear $\Lambda_a^{\mathcal{D}}$ -terms

The translation $\llbracket - \rrbracket : \Lambda_a^{\mathcal{D}} \rightarrow \Lambda_a^{\mathcal{D}}$ translates $\Lambda_a^{\mathcal{D}}$ -terms into linear $\Lambda_a^{\mathcal{D}}$ -terms

$$\begin{aligned}\llbracket \square \rrbracket &= \square \\ \llbracket \mathbf{s}^\gamma \mathbf{t} \rrbracket &= \llbracket \mathbf{s} \rrbracket^\gamma \llbracket \mathbf{t} \rrbracket \\ \llbracket \lambda^\alpha \mathbf{t} \rrbracket &= \lambda^{\vec{0}.1} \llbracket \mathbf{t} \rrbracket [\alpha \leftarrow \square]^{\vec{0}.1} \\ &\quad \text{if } |\alpha|_1 \neq 1 \text{ where } |\vec{0}| = |\alpha|_0 \\ &= \lambda^\alpha \llbracket \mathbf{t} \rrbracket \\ &\quad \text{if } |\alpha|_1 = 1 \\ \llbracket \mathbf{s}[\alpha \leftarrow \mathbf{t}]^\gamma \rrbracket &= \llbracket \mathbf{s} \rrbracket [\alpha \leftarrow \llbracket \mathbf{t} \rrbracket]^\gamma \\ \llbracket \mathbf{s}[\alpha \leftarrow \lambda^{\alpha_1} . \mathbf{d}]^\gamma \rrbracket &= \llbracket \mathbf{s} \rrbracket [\alpha \leftarrow \lambda^{\vec{0}.1} . \llbracket \mathbf{d} \rrbracket [\alpha_1 \leftarrow \square]^{\vec{0}.1}]^\gamma \\ &\quad \text{if } |\alpha_1|_1 \neq 1 \text{ where } |\vec{0}| = |\alpha_1|_0 \\ &= \llbracket \mathbf{s} \rrbracket [\alpha \leftarrow \lambda^\alpha . \llbracket \mathbf{d} \rrbracket]^\gamma \\ &\quad \text{if } |\alpha_1|_1 = 1 \\ \llbracket \langle \mathbf{t}, \langle \dots \rangle^{\gamma_1} \rangle^\gamma \rrbracket &= \langle \llbracket \mathbf{t} \rrbracket, \llbracket \langle \dots \rangle^{\gamma_1} \rrbracket \rangle^\gamma\end{aligned}$$

The interpretation $\llbracket - \rrbracket : \Lambda_a^{\mathcal{D}} \times \mathcal{N}^* \rightarrow \Lambda_a$ is defined by

$$\llbracket \square \rrbracket_x = x$$

$$\llbracket \mathbf{s}^\gamma \mathbf{t} \rrbracket_{\vec{x}} = \llbracket \mathbf{s} \rrbracket_{\vec{\gamma}(\vec{x})} \llbracket \mathbf{t} \rrbracket_{\gamma(\vec{x})}$$

$$\llbracket \lambda^\alpha \mathbf{t} \rrbracket_{\vec{x}} = \lambda y. \llbracket \mathbf{t} \rrbracket_{\vec{x} |_\alpha y}$$

where y is a fresh variable

$$\llbracket \mathbf{s}[\alpha \leftarrow \mathbf{t}]^\gamma \rrbracket_{\vec{x}} = \llbracket \mathbf{s} \rrbracket_{\vec{\gamma}(\vec{x}) |_\alpha \vec{y}} \llbracket \mathbf{t} \rrbracket_{\gamma(\vec{x})}$$

where \vec{y} is a vector of fresh unique variables

$$\llbracket \mathbf{s}[\alpha \leftarrow \lambda^{\alpha_1} . \mathbf{d}]^\gamma \rrbracket_{\vec{x}} = \llbracket \mathbf{s} \rrbracket_{\vec{\gamma}(\vec{x}) |_\alpha \vec{y}} \llbracket \mathbf{d} \rrbracket_{\gamma(\vec{x}) |_{\alpha_1} z}$$

where \vec{y} is a vector of fresh unique variables
and z is a fresh variable

$$\llbracket \langle \mathbf{t}, \langle \dots \rangle^{\gamma_1} \rangle^\gamma \rrbracket_{\vec{x}} = \langle \llbracket \mathbf{t} \rrbracket_{\vec{\gamma}(\vec{x})}, \llbracket \langle \dots \rangle^{\gamma_1} \rrbracket_{\gamma(\vec{x})} \rangle$$

Translation $\Lambda_a \rightarrow \Lambda_a^{\mathcal{D}}$

The interpretation $\llbracket - \rrbracket : \Lambda_a \rightarrow \Lambda_a^{\mathcal{D}} \times \mathcal{N}^*$

$$\llbracket x \rrbracket = (\Box, x)$$

$$\llbracket st \rrbracket = (s'(\vec{0} \cdot \vec{1})t', \vec{s} \cdot \vec{t})$$

where $(s', \vec{s}) = \llbracket s \rrbracket$ and $(t', \vec{t}) = \llbracket t \rrbracket$

$|\vec{0}| = |\vec{s}|$ and $|\vec{1}| = |\vec{t}|$

$$\llbracket \lambda x.t \rrbracket = (\lambda^\alpha t', \vec{\alpha}(\vec{t}))$$

where $(t', \vec{t}) = \llbracket t \rrbracket$, $|\alpha|_1 = 1$, $\alpha(\vec{t}) = x$

$$\llbracket s[\vec{y} \leftarrow t] \rrbracket = (s'[\alpha \leftarrow t']^{\vec{0} \cdot \vec{1}}, \vec{\alpha}(\vec{s}) \cdot \vec{t})$$

where $(s', \vec{s}) = \llbracket s \rrbracket$, $(t', \vec{t}) = \llbracket t \rrbracket$

α is such that $\alpha(\vec{t}) = \vec{y}$, $|\vec{0}| = |\vec{\alpha}(\vec{s})|$ and $|\vec{1}| = |\vec{t}|$

Translation $\Lambda_a \rightarrow \Lambda_a^{\mathcal{D}}$

$$\begin{aligned} \langle\langle s[\vec{y} \leftarrow \lambda z.d] \rangle\rangle &= (s'[\alpha \leftarrow \lambda^{\alpha_1}.d']^{\vec{0} \cdot \vec{1}}, \overline{\alpha}(\vec{s}) \cdot \overline{\alpha_1}(\vec{d})) \\ &\text{where } (s', \vec{s}) = \langle\langle s \rangle\rangle, (d', \vec{d}) = \langle\langle d \rangle\rangle, \\ &\alpha \text{ and } \alpha_1 \text{ are such that } \alpha(\vec{s}) = \vec{y}, \alpha_1(\vec{d}) = z \\ &|\vec{0}| = |\alpha|_0 \text{ and } |\vec{1}| = |\alpha_1|_0 \\ \langle\langle t, \langle \dots \rangle \rangle \rangle &= (\langle\langle t', \langle \dots \rangle^\gamma \rangle^{\vec{0} \cdot \vec{1}}, \vec{t} \cdot \vec{s}) \\ &\text{where } (t', \vec{t}) = \langle\langle t \rangle\rangle \text{ and } (\langle \dots \rangle^\gamma, \vec{s}) = \langle\langle \langle \dots \rangle \rangle \rangle \\ &|\vec{0}| = |\vec{t}| \text{ and } |\vec{1}| = |\vec{s}| \end{aligned}$$

Strongly Normalizing

Given linear $\Lambda_a^{\mathcal{D}}$ -term s , if $s \rightsquigarrow_S t$ then there is a rule in the atomic λ -calculus such that $\llbracket s \rrbracket_{\vec{x}} \rightsquigarrow \llbracket t \rrbracket_{\vec{x}}$.

$$\begin{array}{ccc} s & \rightsquigarrow_S & t \\ \downarrow & & \downarrow \\ \llbracket s \rrbracket_{\vec{x}} & \rightsquigarrow_S & \llbracket t \rrbracket_{\vec{x}} \end{array}$$

Some useful Lemma's for proving this

$$|\alpha(\gamma)|_0 = |\bar{\gamma}(\alpha)|_1$$

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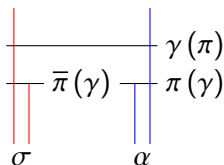
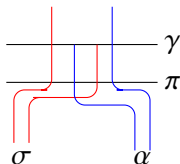
$$|\alpha(\gamma)|_0 = |\bar{\gamma}(\alpha)|_1$$

$$|\alpha(\gamma)|_0 = |\alpha(\bar{\gamma})|_1 = |\bar{\gamma}(\bar{\alpha})|_0 = |\bar{\gamma}(\alpha)|_1$$

$ \alpha(\gamma) _0$		$ \bar{\gamma}(\alpha) _1$	
$\alpha = 1$	$\gamma = 1$	$\gamma = 1$	$\alpha = 1$
$\alpha = 1$	$\gamma = 0$	$\gamma = 0$	$\alpha = 1$
$\alpha = 0$	$\gamma = 1$	$\gamma = 1$	$\alpha = 0$
$\alpha = 0$	$\gamma = 0$	$\gamma = 0$	$\alpha = 0$

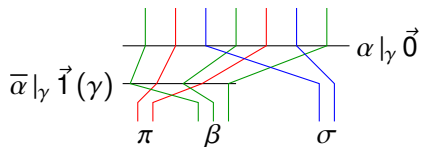
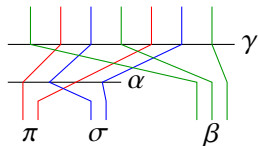
Some useful Lemma's for proving this

$$\gamma(\sigma \mid_{\pi} \alpha) = \bar{\pi}(\gamma)(\sigma) \mid_{\gamma(\pi)} \pi(\gamma)(\alpha)$$



Some useful Lemma's for proving this

$$(\pi |_{\alpha} \sigma) |_{\gamma} \beta = (\pi |_{\bar{\alpha} |_{\gamma} \vec{1}(\gamma)} \beta) |_{\alpha |_{\gamma} \vec{0}} \sigma$$



Summary

- Explain how to implement full laziness using local reduction rules
- Achieved by keeping track of the free variables in all subterms

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- Explain how to implement full laziness using local reduction rules
- Achieved by keeping track of the free variables in all subterms

- Outlook
 - Not clear the book-keeping required can be implemented efficiently as it is - the use of a canonical form and a reduction strategy may solve this
 - Represent the distributor as an environment in an abstract machine
 - To formalize *atomic graphs*, the graphical equivalent of the atomic λ -calculus