## MA40254 Differential and geometric analysis : Exercises 6

Hand in answers by 1:15pm on Wednesday 15 November for the Seminar of Thursday 16 November Homepage: http://moodle.bath.ac.uk/course/view.php?id=57709

**0** (Warmup). Let  $\gamma = \frac{-x_2 dx_1 + x_1 dx_2}{x_1^2 + x_2^2} \in \Omega^1(\mathbb{R}^2 \setminus \{0\})$ . Show that  $d\gamma = 0$ .

**Solution**: By the product rule

$$d\gamma = \frac{d(-x_2 \, dx_1 + x_1 \, dx_2)}{x_1^2 + x_2^2} - \frac{2x_1 \, dx_1 + 2x_2 \, dx_2}{(x_1^2 + x_2^2)^2} \wedge (-x_2 \, dx_1 + x_1 \, dx_2) = 0,$$

since  $d(-x_2 dx_1 + x_1 dx_2) = 2dx_1 \wedge dx_2$  and  $(x_1 dx_1 + x_2 dx_2) \wedge (-x_2 dx_1 + x_1 dx_2) = (x_1^2 + x_2^2) dx_1 \wedge dx_2$ .] **1.** Let  $U = \{p \in \mathbb{R}^4 : x_2(p) \neq 0\}$ , and  $\varphi = (x_1, x_2^2 x_3, x_4/x_2) : U \to \mathbb{R}^3$ , where  $x_1, x_2, x_3, x_4$  are the coordinate functions on  $U \subseteq \mathbb{R}^4$ . Let  $\alpha = y_1 dy_2 \wedge dy_3 \in \Omega^2(\mathbb{R}^3)$  where  $y_1, y_2, y_3 : \mathbb{R}^3 \to \mathbb{R}$  denote the coordinate functions.

(i) Express  $\varphi^* \alpha$  and  $\varphi^* d\alpha$  in standard form, i.e., as a sum of terms  $f dx_I$ .

**[Hint:** First expand  $\varphi^* \alpha$  as  $(\varphi^* y_1) d(\varphi^* y_2) \wedge d(\varphi^* y_3)$  and similarly  $\varphi^* d\alpha$ .]

(ii) Compute directly  $d(\varphi^*\alpha)$ . What do you observe?

[**Hint**: To save work, just compute the terms that don't appear in  $\varphi^* d\alpha$ .]

**2.** For U open in  $\mathbb{R}^n$ ,  $\alpha \in \Omega^k(U)$ ,  $p \in U$ , and  $v_1, \ldots, v_k \in \mathbb{R}^n$ , show that

$$d\alpha_p(v_0,\ldots,v_k) = \sum_{i=0}^k (-1)^i D\alpha_p(v_i)(v_0,\ldots,\hat{v}_i,\ldots,v_k)$$

where  $v_0, \ldots, \hat{v}_i, \ldots, v_k$  denotes the list obtained from  $v_0, \ldots, v_k$  by omitting  $v_i$ . Equivalently

$$d\alpha_p = \sum_{i=0}^k \operatorname{sgn}(\sigma_i) \, \sigma_i \cdot D\alpha_p^{\vee},$$

where  $\sigma_i = (0 \ 1 \ \cdots \ i)^{-1} \in G := \text{Sym}(\{0, 1, \dots, k\}) \cong S_{k+1}$ , and for  $\sigma \in G$  and  $\beta \in \text{Alt}^{k+1}(\mathbb{R}^n)$ ,  $(\sigma \cdot \beta)(v_0, \dots, v_k) = \beta(v_{\sigma(0)}, \dots, v_{\sigma(k)})$  (which is  $\beta(v_i, v_0, \dots, \hat{v}_i, \dots, v_k)$  when  $\sigma = \sigma_i$ ).

**[Hint:** One approach, using the second formula, is to let  $H \cong S_k$  be the subgroup of G fixing 0, and observe that  $\sigma_i H : i = 0, ..., k$  is a left coset partition of G. Now split the sum into sums over each coset: what is  $\tau \cdot D\alpha_p^{\vee}$  for  $\tau \in H$ ?]

**3** (Less essential). Let  $U \subseteq \mathbb{R}^3$  an open subset. Given a vector-valued function  $v = (v_1, v_2, v_3) : U \to \mathbb{R}^3$ , define  $v^{\flat} \in \Omega^1(U)$  and  $v \lrcorner \text{Det} \in \Omega^2(U)$  by applying the corresponding operations on vectors pointwise.

(i) Let  $\operatorname{div}(v): U \to \mathbb{R}$  be defined by

$$\operatorname{div}(v) = \frac{\partial v_1}{\partial x_1} + \frac{\partial v_2}{\partial x_2} + \frac{\partial v_3}{\partial x_3}$$

Show that

$$d(v \,\lrcorner\, \text{Det}) = \operatorname{div}(v) \operatorname{Det} \in \Omega^3(U).$$

(ii) Let  $\operatorname{curl}(v): U \to \mathbb{R}^3$  be defined by

$$\operatorname{curl}(v) = \left(\frac{\partial v_3}{\partial x_2} - \frac{\partial v_2}{\partial x_3}, \ \frac{\partial v_1}{\partial x_3} - \frac{\partial v_3}{\partial x_1}, \ \frac{\partial v_2}{\partial x_1} - \frac{\partial v_1}{\partial x_2}\right).$$

Show that

$$d(v^{\flat}) = \operatorname{curl}(v) \,\lrcorner\, \operatorname{Det} \in \Omega^2(U).$$

[**Hint**: Write all the forms in standard form, e.g.,  $v \,\lrcorner\,$  Det can be expressed as  $v_1 dx_2 \land dx_3 - v_2 dx_1 \land dx_3 + v_3 dx_1 \land dx_2$ .]

**4.** Let  $x_1, x_2: \mathbb{R}^2 \setminus \{0\} \to \mathbb{R}$  be the coordinate functions. Which of the following elements of  $\Omega^1(\mathbb{R}^2 \setminus \{0\})$  are closed? Which are exact?

- (i)  $\alpha = -2x_1x_2 dx_1 + x_1^2 dx_2$
- (ii)  $\beta = x_2 dx_1 + x_1 dx_2$
- (iii)  $\gamma = \frac{-x_2 dx_1 + x_1 dx_2}{x_1^2 + x_2^2}$

[**Hint**: For (iii), consider  $\varphi : \mathbb{R} \to \mathbb{R}^2 \setminus \{0\}$  defined by  $t \mapsto (\cos t, \sin t)$ . Suppose that  $\gamma = df$  for some  $f : \mathbb{R}^2 \setminus \{0\} \to \mathbb{R}$ . What can you say about  $\varphi^* f$  and  $\varphi^* \gamma$ ? Or about  $\int_0^{2\pi} \frac{d(f \circ \varphi)}{dt} dt$ ?]

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