# Capped American Lookback

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Consider a financial market consisting of a bank account and a risky asset.

Bank account  $R = (R_t)_{t \ge 0}$  satisfies

$$dR_t = rR_t dt, \quad R_0 = 1, r \ge 0,$$

that is,  $R_t = e^{rt}, t \ge 0$ .

■ Risky asset under P is modeled as exponential Lévy process

$$S_t = S_0 e^{X_t}, \quad S_0 > 0, t \ge 0.$$

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### Motivation

• A (perpetual) American lookback option gives the holder the right to exercise at any finite stopping time  $\tau$  yielding payout

$$e^{-\alpha\tau} \left( M_0 \vee \sup_{0 \le u \le \tau} S_u - K \right)^+, \quad M_0 \ge S_0, \alpha > 0.$$

• Which translates to the optimal stopping problem

$$V^{AL}(x,s) = \sup_{\tau \in \mathcal{M}} \mathbb{E}_{x,s} \left[ e^{-q\tau} \left( e^{\overline{X}_{\tau}} - K \right)^+ \right], \quad q > 0, K > 0,$$

where  $\overline{X}_{\tau} = \sup_{s \leq \tau} X_s, x \leq s$ 

$$\mathbb{P}_{x,s}(\cdot) = \mathbb{P}(\cdot | X_0 = x, \overline{X}_0 = s)$$

and  $\mathcal{M}$  is the set of all stopping times (not necessarily finite).

 This problem has been earlier considered in a diffusive setting by Conze and Viswanathan (1991), Pedersen (2000), Guo and Shepp (2001) and Gapeev (2007).  A (perpetual) American lookback option with cap gives the holder the right to exercise at any finite stopping time τ yielding payouts

$$e^{-\alpha \tau} \left( M_0 \lor \sup_{0 \le u \le \tau} S_u \land C - K \right)^+, \quad C \ge M_0 \ge S_0, \alpha > 0.$$

• Which translates to the optimal stopping problem

$$V_{\epsilon}^{AL}(x,s) = \sup_{\tau \in \mathcal{M}} \mathbb{E}_{x,s} \left[ e^{-q\tau} \left( e^{\overline{X}_{\tau} \wedge \epsilon} - K \right)^{+} \right], \quad q > 0, K > 0,$$

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where  $x \leq s$  and  $\epsilon \in (\log(K), \infty]$ .

#### Notation

- X is a **spectrally negative** Lévy process.
- The Laplace exponent  $\psi$  of X is defined by

$$\psi(\lambda) := \frac{1}{t} \log \mathbb{E}[e^{\lambda X_t}], \qquad \lambda \ge 0$$

• For  $q \ge 0$ , its right-inverse  $\Phi$  is given by

$$\Phi(q) = \sup\{\lambda \ge 0: \psi(\lambda) = q\}.$$

• For  $q \ge 0$ , the q-scale function  $W^{(q)} : \mathbb{R} \longrightarrow [0, \infty)$  is the unique function whose restriction to  $(0, \infty)$  is continuous and has Laplcae transform

$$\int_0^\infty e^{-\lambda x} W^{(q)}(x) \, dx = \frac{1}{\psi(\lambda) - q},$$

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for  $\lambda$  suff. large, and is defined to be zero for  $x \leq 0$ .

• For 
$$q \ge 0$$
, we define  $Z^{(q)} : \mathbb{R} \longrightarrow [1, \infty)$  by

$$Z^{(q)}(x) = 1 + q \int_0^x W^{(q)}(z) \, dz.$$

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## How do Russian-type stopping problems work?

Capped American Lookback:

$$V_{\epsilon}^{AL}(x,s) = \sup_{\tau \in \mathcal{M}} \mathbb{E}_{x,s} \left[ e^{-q\tau} \left( e^{\overline{X}_{\tau} \wedge \epsilon} - K \right)^{+} \right],$$

Russian:

$$V_{\epsilon}^{R}(x,s) := \sup_{\tau \in \mathcal{M}} \mathbb{E}_{x,s} \left[ e^{-q\tau + \overline{X}_{\tau}} \right].$$

Recall the Russian option was introduced and studied by Shepp and Shiryaev (1993,1994) in the Black-Scholes setting and was studied in the current spectrally negative setting by Avram, K. and Pistorius (2004).

- As  $\epsilon \uparrow \infty$  we expect to see  $V_{\epsilon}^{AL}(x, s)$  look more and more like the value function of  $V^{AL}$ . Moreover as  $s \uparrow \infty$  we expect to see  $V^{AL}$  look more and more like  $V^{R}$ .
- Roughly speaking all of these optimal stopping problems appear to fit the following setting:

$$V^{f}(x,s) = \sup_{\tau \in \mathcal{M}} \mathbb{E}_{x,s} \left[ e^{-q\tau} f(\overline{X}_{\tau}) \right],$$

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where f is an increasing function.

$$V^{R}(x,s) := \sup_{\tau \in \mathcal{M}} \mathbb{E}_{x,s} \left[ e^{-q\tau + \overline{X}_{\tau}} \right].$$

**Theorem** [Shepp, Shiryaev, Avram, K., Pistorius]: Suppose that  $q > \psi(1)$ . Then

$$V^{R}(x,s) = e^{s}Z^{(q)}(x-s+k^{*})$$

with optimal strategy

$$\tau^R = \inf\{t \ge 0 : \overline{X}_t - X_t \ge k^*\}$$

for some constant  $k^* \in (0, \infty)$ , where  $k^*$  is the unique solution to  $Z^{(q)}(z) - qW^{(q)}(z) = 0.$ 

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#### Russian stopping problem



Figure: Stopping region  $D^*$  and continuation region  $C^*$  for the Russian optimal stopping problem.

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#### How do Russian-type stopping problems work?

$$V^{f}(x,s) = \sup_{\tau \in \mathcal{M}} \mathbb{E}_{x,s} \left[ e^{-q\tau} f(\overline{X}_{\tau}) \right], \qquad x \le s.$$

Assuming the optimal strategy is of the form

$$\tau^f = \inf\{t > 0 : \overline{X}_t - X_t > g(\overline{X}_t)\}:$$

• Let 
$$\tau_s^+ = \inf\{t > 0 : X_t > s\}$$
 and  $\tau_z^- = \inf\{t > 0 : X_t < z\}$ ,

$$V^{f}(x,s) = f(s)\mathbb{E}_{x,s}(e^{-q\tau_{s-g(s)}^{-}}\mathbf{1}_{(\tau_{s-g(s)}^{-} < \tau_{s}^{+})}) + \mathbb{E}_{x,s}(e^{-q\tau_{s}^{+}}\mathbf{1}_{(\tau_{s-g(s)}^{-} > \tau_{s}^{+})})V^{f}(s,s)$$

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### How do Russian-type stopping problems work?

Hence

$$V^{f}(x,s) = f(s) \left( Z^{(q)}(x-s+g(s)) - W^{(q)}(x-s+g(s)) \frac{Z^{(q)}(g(s))}{W^{(q)}(g(s))} \right) + \frac{W^{(q)}(x-s+g(s))}{W^{(q)}(g(s))} V^{f}(s,s)$$

■ Smooth fit:

$$0 = \lim_{x \downarrow s - g(s)} \frac{\partial V^{f}}{\partial x}(x, s)$$
  
= 
$$\lim_{x \downarrow s - g(s)} \frac{W^{(q)'}(x - s + g(s))}{W^{(q)}(g(s))} [V^{f}(s, s) - f(s)Z^{(q)}(g(s))].$$
  
$$\implies V^{f}(x, s) = f(s)Z^{(q)}(x - s + g(s)).$$
  
(Russian) :  $V^{R}(x, s) = e^{s}Z^{(q)}(x - s + k^{*})$ 

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• Once we know  $V^f(x,s) = f(s)Z^{(q)}(x-s+g(s))$ , normal reflection at (s,s) tells us

$$\frac{\partial V^f}{\partial s}(s-,s) = 0 \Longrightarrow g'(s) = 1 - \frac{f'(s)Z^{(q)}(g(s))}{f(s)qW^{(q)}(g(s))}$$

(Russian):  $(k^*)' = 0 = 1 - \frac{e^s Z^{(q)}(k^*)}{e^s q W^{(q)}(k^*)} \Rightarrow Z^{(q)}(k^*) - q W^{(q)}(k^*) = 0$ 

# Guess solution



Figure: Expected shape of optimal boundary for the Capped American Lookback when  $\epsilon = (\log(K), \infty)$  and  $\epsilon = \infty$  respectively.

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#### Lemma (Solution of ODE)

There exists a unique solution g of the ODE

$$g'(s) = 1 - \frac{e^s Z^{(q)}(g(s))}{(e^s - K)qW^{(q)}(g(s))} \quad on \ (\log(K), \epsilon)$$
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satisfying the boundary conditions  $g(\log(K)+)=\infty$  and

$$\lim_{s\uparrow\epsilon} g(s) = \begin{cases} 0, & \epsilon \in (\log(K), \infty), \\ k^*, & \epsilon = \infty, \end{cases}$$

where  $k^* \in (0,\infty)$  is the unique root of  $Z^{(q)}(s) - qW^{(q)}(s) = 0$ .

See below for sketch of proof.

#### Theorem

Suppose that  $q > \psi(1)$ . The solution of the American Lookback OSP is given by

$$V^*(x,s) = \begin{cases} (e^{s\wedge\epsilon} - K)Z^{(q)}(x - s + g(s)), & (x,s) \in C_I^* \cup D^*, \\ e^{-\Phi(q)(\log(K) - x)}A, & (x,s) \in C_{II}^*, \end{cases}$$

where  $A = \lim_{s \downarrow \log(K)} (e^s - K) Z^{(q)}(g(s)) > 0$ , with optimal strategy

$$\tau^* = \inf\{t \ge 0 : \overline{X}_t - X_t \ge g(\overline{X}_t) \text{ and } \overline{X}_t > \log(K)\},\$$

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where g is given in the Lemma above.

Consider the ODE

$$g'(s) = 1 - \frac{e^s Z^{(q)}(g(s))}{(e^s - K)qW^{(q)}(g(s))} \quad \text{on } (\log(K), \infty).$$

The 0-isocline is given by the graph of

$$f(H) = \log\left(K\left(1 - \frac{Z^{(q)}(H)}{qW^{(q)}(H)}\right)^{-1}\right),$$

where  $H \in (k^*, \infty)$ . It can be shown that f is strictly decreasing,  $\eta := f(\infty) = \log(K(1 - \Phi(q)^{-1})^{-1})$  and  $f(k^*+) = \infty$ .

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Figure: A qualitative picture of the direction field.

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# Sketch of proof of ODE lemma / maximality principle



Figure: The solutions to the ODE and the corresponding possible stopping boundaries.

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- The solutions exhibit a behavior parallel to Peskir's maximality principle in both cases  $\epsilon = \infty$  and  $\epsilon \in (\log(K), \infty)$ .
- If ε = ∞, the "red" curves correspond to the so-called "bad-good" solutions in Peskir's maximality principle (see Peskir (1998));
  "bad" because they do not give the optimal boundary, "good" as they can be used to approximate the optimal boundary.
- The same can be observed in the capped Russian stopping problem.

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Current/future work (Curdin!!!):

• American lookback with floating strike:

$$V^*(x,s) = \sup_{\tau} \mathbb{E}_{x,s} \left[ e^{-q\tau} \left( e^{\overline{X}_{\tau}} - K e^{X_{\tau}} \right)^+ \right]$$

Cap  $\overline{X}$  or X, both?

•  $\pi$ -option:

$$V^*(x,s) = \sup_{\tau} \mathbb{E}_{x,s} \left[ e^{-q\tau} \left( e^{aX_{\tau} + b\overline{X}_{\tau}} - K \right)^+ \right],$$

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where a, b > 0.

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