

# Topics in Stochastic Geometry

## Lecture 4 The Boolean model

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# 1. Definition of the Boolean model

## Definition

Let  $\eta = \{X_n : n \in \mathbb{N}\}$  be a Poisson process with intensity  $\lambda$  and  $Z_0, Z_1, \dots$  a sequence of independent random particles with common distribution  $\mathbb{Q}$  satisfying the integrability assumption

$$\mathbb{E}V_d(Z_0 + K) < \infty, \quad K \in \mathcal{C}^d.$$

Assume that  $\eta$  and  $(Z_n)$  are independent. Then

$$Z = \bigcup_{n \in \mathbb{N}} (Z_n + \xi_n),$$

is called **Boolean model** with **grain distribution**  $\mathbb{Q}$  and **typical grain**  $Z_0$ .

## Theorem

Let  $\eta = \{X_n : n \in \mathbb{N}\}$  be a Poisson process with positive intensity and  $R_0, R_1, \dots$  a sequence of independent and identically distributed non-negative random variables. Define

$$Z = \bigcup_{n \in \mathbb{N}} B(X_n, R_n),$$

where  $B(x, r)$  is a ball with centre  $x \in \mathbb{R}^d$  and radius  $r \geq 0$ . Then  $\mathbb{P}(Z = \mathbb{R}^d) = 1$  iff  $\mathbb{E}R_0^d = \infty$ .

## Remark

Let  $Z_0 := (0, R_0)$ , where  $R_0$  is as above. Then  $Z_0$  satisfies the required integrability condition iff

$$\mathbb{E}R_0^d < \infty.$$

## Lemma

*Let  $Z$  be a Boolean model as above. Then, almost surely, any bounded set is intersected by only finitely many of the (secondary) grains  $Z_n + X_n$ . In particular,  $Z$  is closed.*

## Convention

A Boolean model  $Z$  is considered as a **random closed set**, that is as a random element in the space of all closed subsets of  $\mathbb{R}^d$  equipped with a suitable  $\sigma$ -field.

## 2. The capacity functional

### Definition

The **capacity functional** of a random closed set  $Z$  is the mapping  $T_Z : \mathcal{C}^d \rightarrow \mathbb{R}$  defined by

$$T_Z(C) := \mathbb{P}(Z \cap C \neq \emptyset), \quad C \in \mathcal{C}^d.$$

### Theorem

*The capacity model of a Boolean model  $Z$  is given by*

$$T_Z(C) = 1 - \exp[-\lambda \mathbb{E} V_d(Z_0 + C^*)], \quad C \in \mathcal{C}^d,$$

*where  $C^* := \{-x : x \in B\}$ .*

## Corollary

A Boolean model  $Z$  is *stationary*, that is

$$Z \stackrel{d}{=} Z + x, \quad x \in \mathbb{R}^d.$$

## Corollary

Assume that the typical grain  $Z_0$  of a Boolean model  $Z$  is *isotropic*, i.e.

$$Z_0 \stackrel{d}{=} \vartheta Z_0$$

for any rotation  $\vartheta$ . Then  $Z$  is isotropic.

### 3. Volume fraction and covariance function

#### Definition

The **volume fraction**  $\rho$  of a stationary random closed set  $Z$  is defined by

$$\rho := \mathbb{E} V_d([0, 1]^d).$$

An equivalent definition is  $\rho := \mathbb{P}(x \in Z)$  for any  $x \in \mathbb{R}^d$ .

#### Corollary

*The volume fraction of a Boolean model is given by*

$$\rho = 1 - \exp(-\lambda \mathbb{E} V_d(Z_0))$$

## Definition

The **covariance function** of a stationary random closed set  $Z$  is the function  $C : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$  defined by

$$C(x, y) := \mathbb{P}(\{x, y\} \subset Z) = \mathbb{E}[\mathbf{1}_Z(x)\mathbf{1}_Z(y)], \quad x, y \in \mathbb{R}^d.$$

## Theorem

*The covariance function of a Boolean model is given by*

$$C(x) = 2p - 1 + (1 - p)^2 \exp(\lambda C_0(x)), \quad x \in \mathbb{R}^d,$$

*where*

$$C_0(x) := \mathbb{E}[V_d(Z_0 \cap (Z_0 - x))].$$



## 4. Ergodicity properties

### Definition

A stationary random closed set  $Z$  in  $\mathbb{R}^d$  is called **mixing** if

$$\lim_{\|x\| \rightarrow \infty} \mathbb{P}(Z \in \mathcal{H} \cap \theta_x \mathcal{H}') = \mathbb{P}(Z \in \mathcal{H})\mathbb{P}(Z \in \mathcal{H}'),$$

for any measurable sets  $\mathcal{H}, \mathcal{H}'$  of closed sets. Here

$$\theta_x \mathcal{H}' := \{A + x : A \in \mathcal{H}'\}, \quad x \in \mathbb{R}^d.$$

### Remark

Any mixing  $Z$  is **ergodic**, that is

$$\mathbb{P}(Z \in \mathcal{H}) \in \{0, 1\}$$

for all **invariant**  $\mathcal{H}$ .



## Theorem

*A Boolean model  $Z$  is mixing.*

## Remark

The assertion of the theorem can be reduced to the limit relation

$$\lim_{\|x\| \rightarrow \infty} (1 - T_Z(C \cup (C' + x))) = (1 - T_Z(C))(1 - T_Z(C')),$$

for all compact  $C, C' \subset \mathbb{R}^d$ . For the Boolean model this can be directly verified.

## Theorem (Spatial ergodic theorem)

Assume that  $Z$  is an ergodic random closed set and let  $W \subset \mathbb{R}^d$  be a convex and compact set containing the origin in its interior. Let  $f(Z)$  be a measurable function of  $Z$  such that  $\mathbb{E}|f(Z)| < \infty$ . Then the limit

$$\lim_{r \rightarrow \infty} \frac{1}{V_d(rW)} \int_{rW} f(\theta_x Z) dx$$

exists almost surely and in  $L^1(\mathbb{P})$  and is given by  $\mathbb{E}f(Z)$ .

## Example

For a Boolean model  $Z$  the limit

$$\lim_{r \rightarrow \infty} \frac{1}{V_d(rW)} \int_{rW} \mathbf{1}\{x \in Z\} dx$$

exists and is given by the volume fraction of  $Z$ .

## Definition

Let  $K \subset \mathbb{R}^d$  be compact and convex. The **intrinsic volumes** of  $K$  are the numbers  $V_0(K), \dots, V_d(K)$  uniquely determined by the **Steiner formula**

$$V_d(K + rB^d) = \sum_{j=0}^d r^j \kappa_j V_{d-j}(K), \quad r \geq 0,$$

where  $\kappa_j$  is the ( $j$ -dimensional) volume of the Euclidean unit ball  $B^j$  in  $\mathbb{R}^j$ .

## Remark

$V_d(K)$  is the Lebesgue measure of  $K$ . If  $K$  has non-empty interior, then  $V_{d-1}(K)$  is half the surface area of  $K$ . Moreover,  $V_0(K) = \mathbf{1}\{K \neq \emptyset\}$ .

## Remark

Using the inclusion-exclusion formula the intrinsic volumes can be extended (uniquely!) to finite unions  $K$  of convex and compact sets. Then  $V_{d-1}(K)$  is still half the surface area of  $K$  while  $V_0(K)$  is the **Euler characteristic** of  $K$ .

## Theorem

*Let  $Z$  be a stationary ergodic random closed set that is locally a finite union of convex sets. Under suitable integrability assumptions the limits*

$$\lambda_j := \lim_{r \rightarrow \infty} \frac{V_j(Z \cap rW)}{V_d(rW)}, \quad j = 0, \dots, d,$$

*exist  $\mathbb{P}$ -almost surely.*

## Theorem (Miles)

If  $Z$  is a Boolean model with convex typical grain  $Z_0$ , then

$$\lambda_{d-1} = \lambda \mathbb{E} V_{d-1}(Z_0) e^{-\lambda \mathbb{E} V_d(Z_0)}.$$

If  $Z_0$  is isotropic, then  $\lambda_0, \dots, \lambda_{d-2}$  can be computed explicitly in terms of  $e^{-\lambda \mathbb{E} V_d(Z_0)}$  and  $\lambda \mathbb{E} V_i(Z_0)$ ,  $i = 0, \dots, d-1$ . For instance, we have for  $d = 2$  that

$$\lambda_0 = e^{-\lambda \mathbb{E} V_d(Z_0)} \left( \lambda - \frac{\mathbb{E} V_1(Z_0)}{\pi} \right)$$

and in the case  $d = 3$

$$\lambda_0 = e^{-\lambda \mathbb{E} V_d(Z_0)} \left( \lambda - \frac{\lambda^2}{4} \mathbb{E} V_1(Z_0) \mathbb{E} V_2(Z_0) + \frac{\pi \lambda^3}{48} (\mathbb{E} V_2(Z_0))^3 \right).$$

## 5. References

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